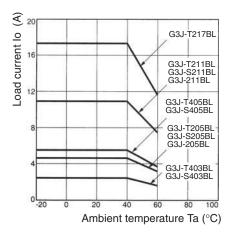
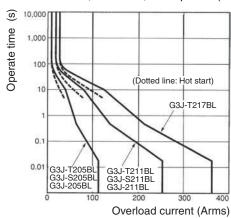
■ Engineering Data

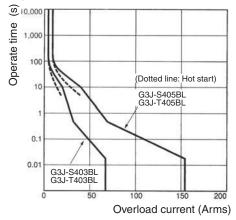
Load Current vs. Ambient Temperature



Overload Current Resistivity

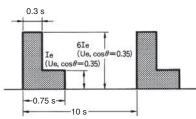
Conditions: 60 Hz, Ta of 25°C, non-repetitive (1/2 for repetitive)





■ Switching Frequency Test Conditions (AC3/AC4/AC53-a)

AC3 Class (Immediate Start)



le: Rated carry current Ue: Rated load voltage (200/400 V)

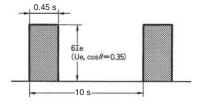
The following Soft-start conditions apply.

Ramp-up time: 1 s Starting torque: 450% In

The following Soft-start/stop conditions apply:

Ramp-up time: 1 s Ramp-down time: 1 s Starting torque: 450% In

AC4 Class (Inching)



le: Rated carry current Ue: Rated load voltage (200/400 V)

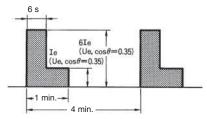
The following Soft-start conditions apply.

Ramp-up time: 1 s Starting torque: 450% In

The following Soft-start/stop conditions apply:

Ramp-up time: 1 s Ramp-down time: 1 s Starting torque: 450% In

AC53-a: 6-6: 25-15



le: Rated carry current

Ue: Rated load voltage (200/400 V)

The following Soft-start conditions apply.

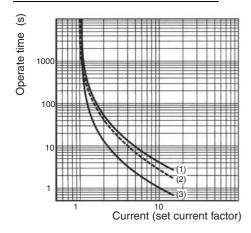
Ramp-up time: 1 s Starting torque: 450% In

The following Soft-start/stop conditions apply:

Ramp-up time: 1 s Ramp-down time: 1 s Starting torque: 450% In

■ Recommended Thermal Overload Performance

Overload Characteristics



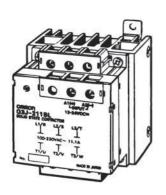
- (1): Balanced operation, 3-phase, from cold state(2): Balanced operation, 2-phase, from cold state(3): Balanced operation, 3-phase, after a long period of set current flow (hot state).

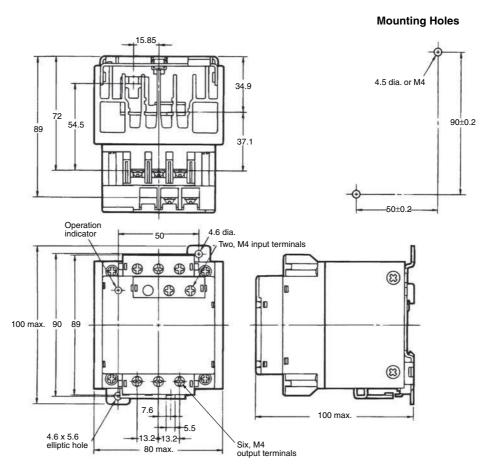
Dimensions

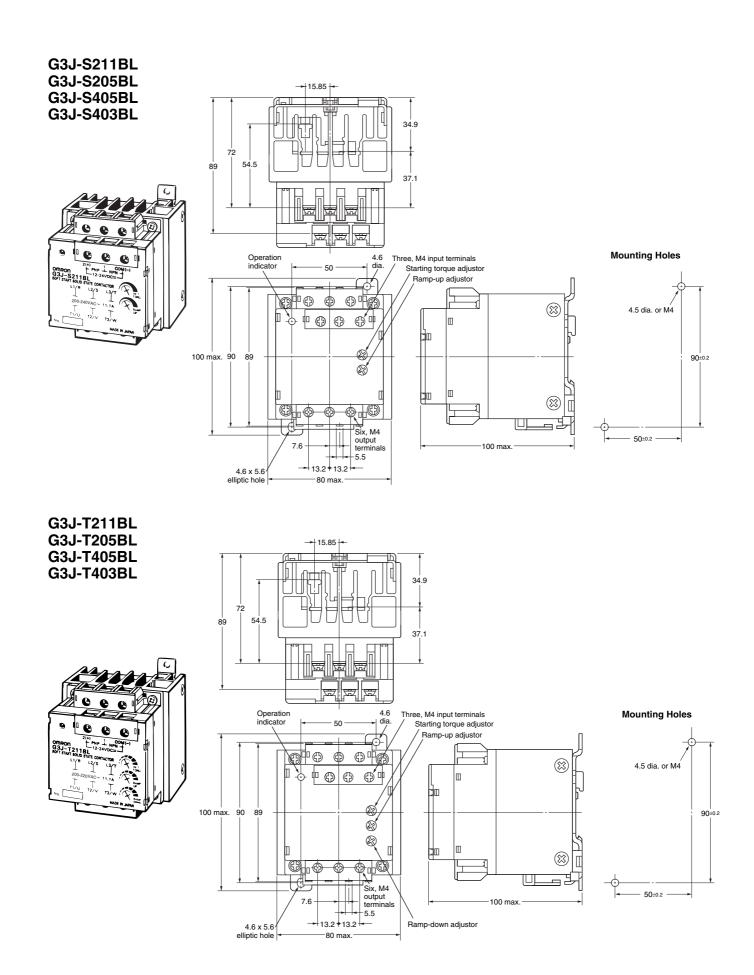
Note: All units are in millimeters unless otherwise indicated.

■ Solid State Contactors

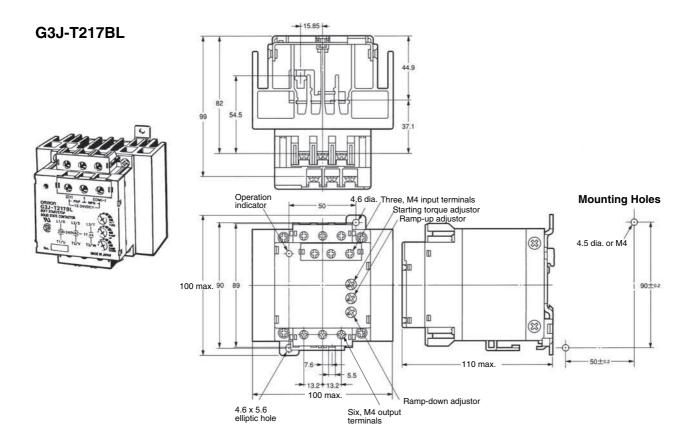
G3J-211BL G3J-205BL G3J-211BL-2 G3J-205BL-2







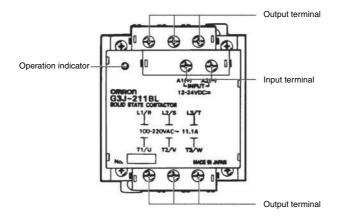
оптроп 3



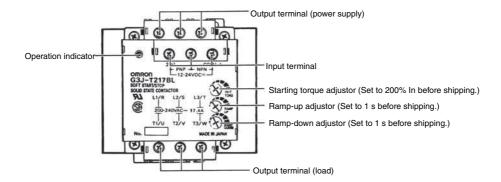
Installation

■ Nomenclature

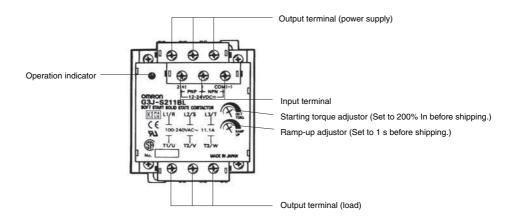
G3J



G3J-T



G3J-S



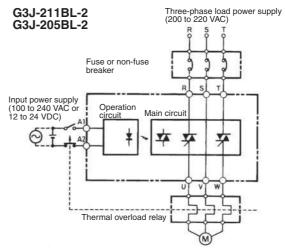
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■ Internal Connections

Simple 3-element Models

G3J-211BL (200 to 220 VAC) Fuse or non-fuse breaker Input power supply (100 to 240 VAC or 12 to 24 VDC) Thermal overload relay Three-phase induction motor (2.2 kW max.)

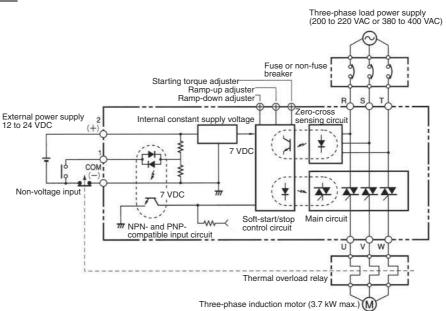
Simple 2-element Models



Three-phase induction motor (2.2 kW max.)

Soft-start/stop Models

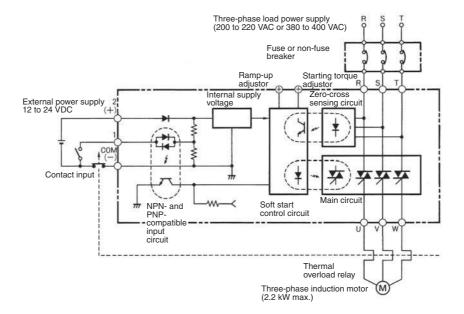




S

Soft-start Models

G3J-S211BL G3J-S205BL G3J-S405BL G3J-S403BL



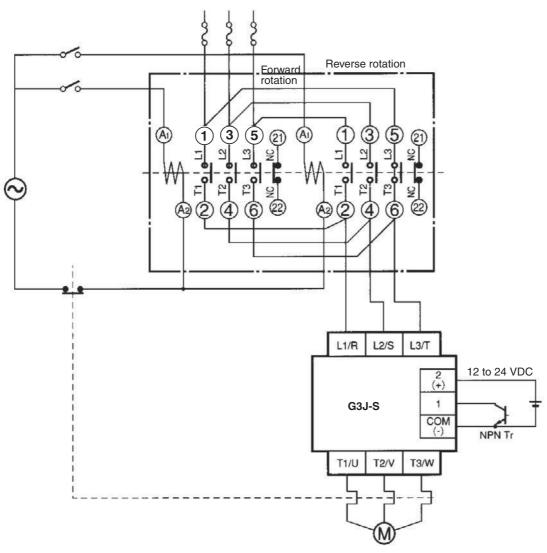
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Forward/Reverse Rotation

G3J-S or G3J-T with a Reversible Contactor with Built-in Mechanical Interlock Function

G3J-S□BL or G3J-T□BL

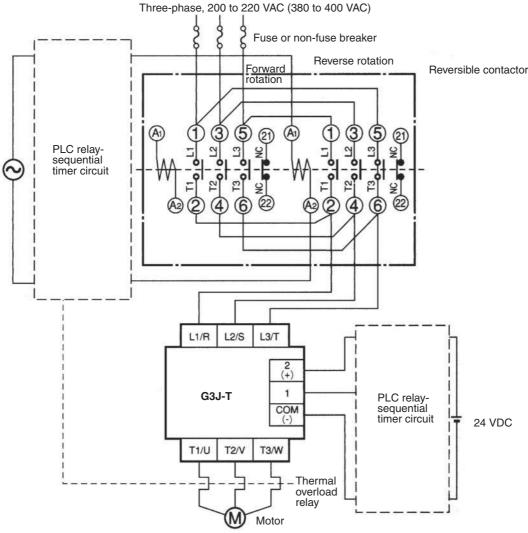
Three-phase, 200 to 220 VAC (380 to 400 VAC)



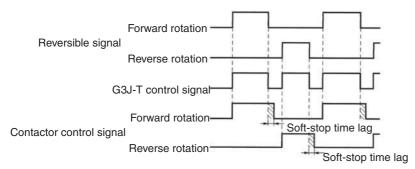
Note: 1. Be sure to use a fuse or non-fuse breaker to protect the G3J.

- 2. Make sure that the interval between forward and reverse operations is at least 100 ms.
- **3.** Be sure to apply the input signal of the G3F-S after the reversible contactor starts operating. If the input signal is applied before the contactor starts operating, the soft-start function may not operate.

G3J-S or G3J-T



For soft-stop control, the G3J-T has enough load current to continue rotating the motor during ramp-down time setting even after the control signal of the G3J-T is tuned OFF. Therefore, a time lag is required between the time when the G3J-T stops operating up to the time when the reversible contactor is turned OFF. The ramp-down time of the G3J-T is adjustable up to approximately 25 s max. Therefore, set the time lag to 25 s in the initial sequence during the adjustment stage. Adjust the time lag of the sequential circuit according to the application.



Note: Make sure that the interval between forward and reverse operations is at least 100 ms. If the G3J is turned ON by noise input, short-circuiting between phases will result. In order to prevent this, insert a protective resistor.

/!\WARNING

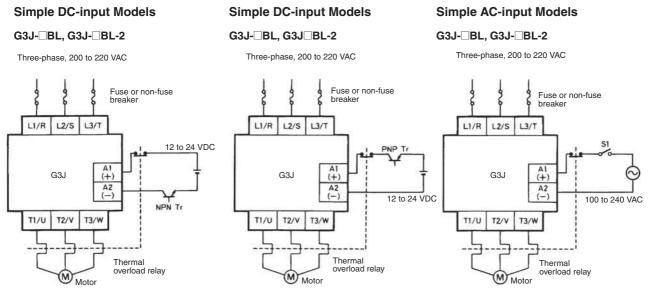
Do not use two G3J-S or G3J-T Units together in reversible operation.

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■ Connections Example

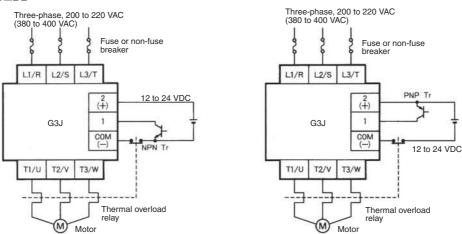
Harmonized protection is ensured for motor overcurrents.

Be sure to supply power to the G3J through a fuse or non-fuse breaker to protect the G3J from damage due to short-circuiting.



Soft-start/Soft-start/stop Models

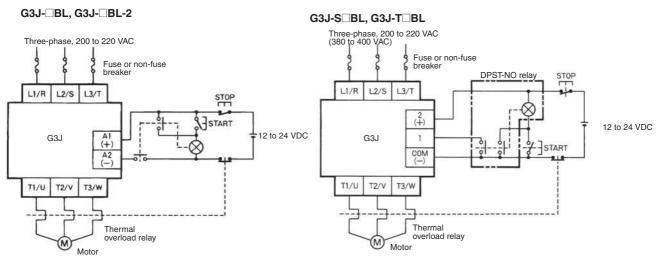
G3J-S□BL, G3J-T□BL



Note: 1. When the minimum applicable load of the thermal relay auxiliary contacts becomes smaller than the input current of the G3J, insert a bleeder resistance.

2. Connect the thermal relay NC contact to the 2 (+) or COM (-) line. Connecting the thermal relay NC contact to the 1 input will cause contact failure.

Self-hold Circuits



Note: Be sure to use a fuse or non-fuse breaker to protect the G3J.

■ Fuse Selection

The following table shows the I²t (60 Hz half-wave 1 cyc) values for G3J models.

Model	l²t
G3J-T217BL	2,660A ² s
G3J-S211BL G3J-T211BL	1,260A ² s
G3J-S205BL G3J-T205BL	121A ² s
G3J-S405BL G3J-T405BL	260A ² s
G3J-S403BL G3J-T403BL	260A ² s

When selecting a fuse to protect a G3J, use a quick-breaking fuse for semiconductor protection that satisfies the following condition: fuse's $l^2t < G3J$'s l^2t .

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Operation

■ Soft-Start/Stop (Function of G3J-T)

The G3J-T is a solid state contactor that smoothly starts and stops machines and equipment connected to power supplies without damaging the machines, equipment, or power supplies.

Soft-start Time

The voltage imposed on the motor increases while ignition α is gradually reduced, thus gradually increasing the rotation speed of the motor.

Ramp-up Time

Ramp-up time is a period required for ignition α to become zero degrees with a 100% voltage imposed on the motor.

Starting Torque

Starting torque is determined by the value of ignition α immediately after the input signal is turned ON.

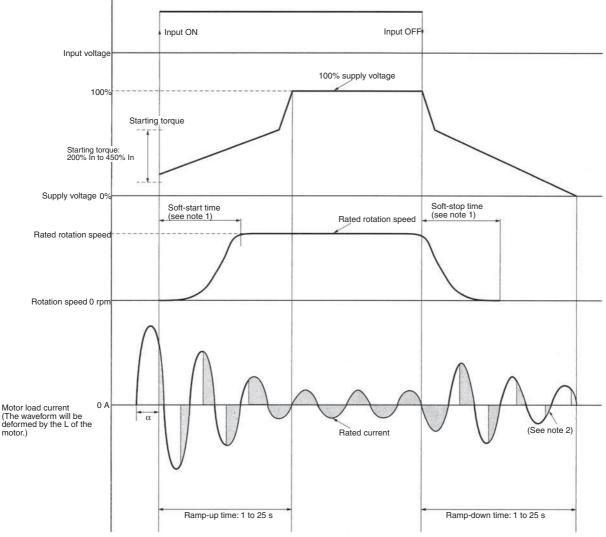
Soft-stop Time

The voltage imposed on the motor decreases while ignition α is gradually increased, thus gradually decreasing the rotation speed of the motor.

Ramp-down Time

Ramp-down time is a period required for ignition α to become 180 degrees with a 0% voltage imposed on the motor.

Soft-start/stop Characteristics



Note: 1. In addition to starting torque, ramp-up time, and ramp-down time, the soft-start time and soft-stop time vary with the load characteristics such as the inertia and friction factor of the load. Therefore, the soft-start time or soft-stop time will not increase beyond a certain point.

2. Due to the soft-stop control characteristics, the load current continues flowing even after the motor stops. Set to the optimum value according to the adjustment steps.

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■ Soft-start/stop Setting Method

Adjuster

Starting Torque Setting with the Starting Torque Adjuster

The starting torque of a motor can be set within a range from 200% to 450% In provided that the starting torque is 600% In when the motor is started at full voltage, which allows optimum motor control without any time lag at the time the motor starts.



Set with a Phillips or flat-blade screwdriver.

Ramp-up Time Setting with the Ramp-up Adjuster

The ramp-up time of a motor can be set within a range from 1 to 25 s, with which the soft-start time of the motor is adjusted until the motor rotates at full speed.



Set with a Phillips or flat-blade screwdriver.

Ramp-down Time Setting with the Ramp-down Adjuster

The ramp-down time of a motor can be set within a range from 1 to 25 s, with which the soft-stop time of the motor is adjusted until the motor decelerates to a stop.



Set with a Phillips or flat-blade screwdriver.

Adjustment Steps

 Start and stop the motor with the factory settings. Ramp-up adjuster: 1 s Starting torque adjuster: 200% In

Ramp-down adjuster: 1 s

- 2. If the motor does not rotate smoothly, increase the starting torque.
- **3.** Gradually increase the ramp-up time to adjust the start time.
- 4. Gradually increase the ramp-down time to adjust the stop time.
- The soft-start time or soft-stop time will not increase beyond a certain point (depend on load). Do not set the ramp-up time or ramp-down time beyond this point.

Further Adjustment or Arrangement

- Increase the starting torque if the motor does not start with a long soft-start time.
- To start normally (i.e., not using soft-start) use a simple G3J model.

ALL DIMENSIONS SHOWN ARE IN MILLIMETERS.

To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

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