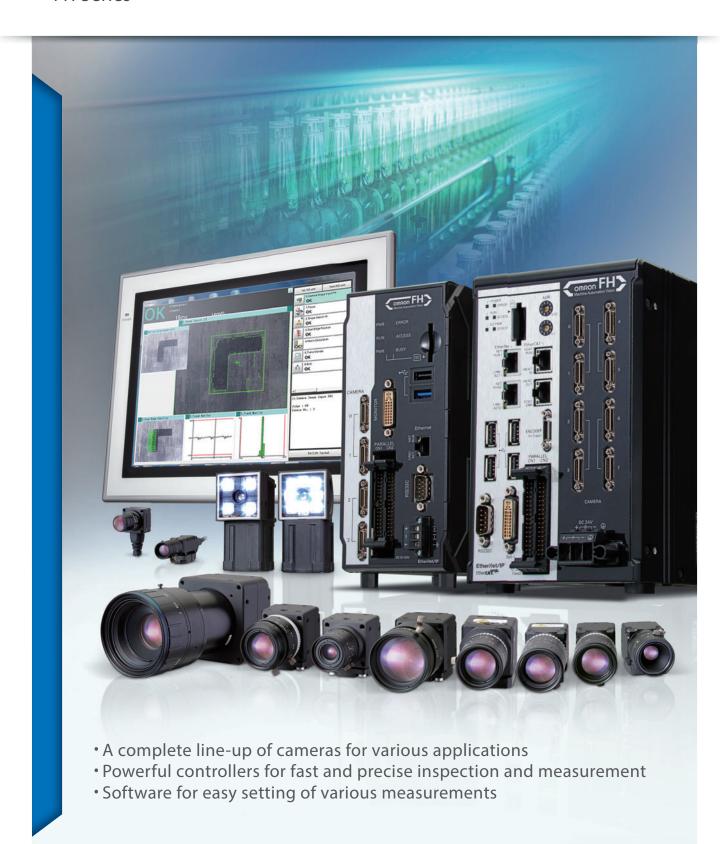


Vision System

FH Series





Best-in class image sensing speed and precision - like or even more than the human eye

Omron has packed image sensing technology for inspection and measurement necessary for automation into compact devices. The FH Series includes software for inspection and measurement in addition to cameras that can capture high-sensitivity and high-resolution images. This vision system, substituted for the human eye, provides high-speed and high-precision inspection and measurement without complex programming and device combination.

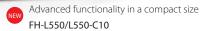
Vision System FH Series

A complete line-up of cameras for various applications





Powerful controllers for fast and precise inspection and measurement





Software for easy setting of various measurements

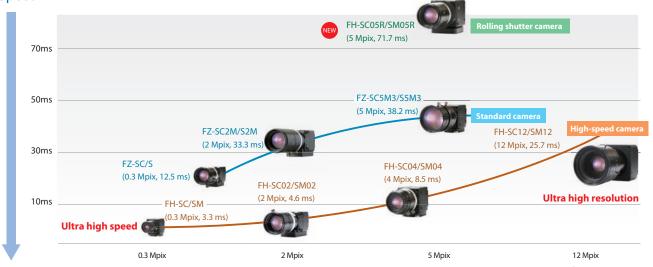
A complete line-up of cameras for various applications

For applications requiring high speed and high resolution

Lens mount camera

You can select the best combination of camera and lens for your application.

Speed



Rolling shutter camera added to the line-up

The benefits of cost-effective rolling shutter cameras are now being recognized once again.

The rolling shutter camera scans the pixels of each line. Although this produces distortions of moving objects, high-resolution yet cost-effective inspection and measurement can be performed.

Easy to install into machines

Camera with built-in light

The all-in-one camera including the light and lens can be easily integrated into almost any machine.

* The FQ2 Smart Cameras are also available.

High-power lighting

The sensor has a built-in high-power light capable of evenly lighting across a wide field of view.

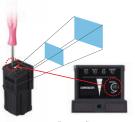
This provides sufficient lighting even when the enclosed polarizing filter is used.

Adjustable lens

The focus of the lens can be adjusted to take clear images for the specific field of view and installation distance you need.







Focus adjustment screw

Rolling shutter Global shutter Stationary object Moving object

Resolution

For narrow space

Small camera

The ultra-compact lens can be installed into limited space in a machine. Select the flat or pen type depending on space.



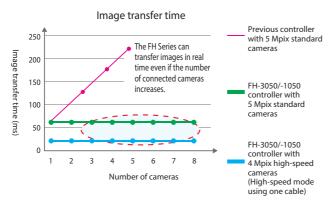
Powerful controllers for fast and precise inspection and measurement

You can select the best controller to suit requirements. All controllers can share the same settings, bringing flexibility to machine design.

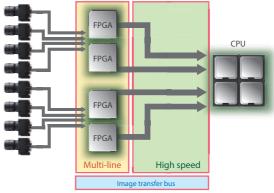
	FH-3050 Series	FH-1050 Series	FH-L550 Series		
Processing speed (CPU)	Core Core Core Core	Core Core 2 core High speed	Core Core 2 core Mid speed		
No. of connectable cameras	2 to 8	2 to 8	2 to 4		
Multi-line processing	\checkmark	✓			
Ether CAT.	\checkmark	✓			
EtherNet/IP	\checkmark		✓		
Connectable camera		All FH and FZ cameras			

Image transfer without delay

The FH-3050/-1050 Series has a high-performance bus to transfer images, maximizing the specifications of any connected camera.



The FH-3050/-1050 Series can transfer large amounts of image data in real time



Note: The image conversion processing time is not included

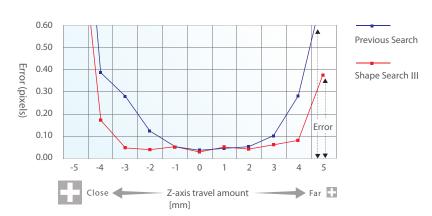
Object detection algorithm Shape Search III for fast and precise inspection and measurement

High-precision object detection

Low-error position detection even with blurry images

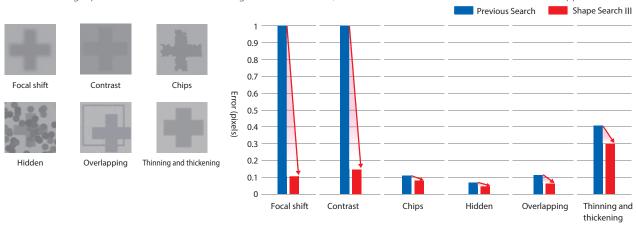
Over many years, Omron has perfected techniques to search for and match templates at high speed. This experience and expertise enables us to develop the Shape Search III vision algorithm, which provides advanced robustness and is critical on FA sites. When measuring lamination of glass or other processes where the distance to the workpiece from the camera varies, size differences and focal shifts can occur. Even in cases like this, the new Shape Search III algorithm detects positions with limited error.





Stable searching with limited error even under adverse conditions

Stable searching is possible even under the following adverse conditions, which occur far too often in actual measurement applications.



Detection of multiple workpieces

Even if many workpieces are within the field of view, searching is possible without compromising detection accuracy.

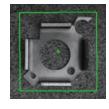


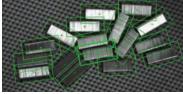
The different types of the searched workpieces can be classified.



Detection of workpieces from background noise and detection of shiny workpieces

Stable searching is possible without being affected by the background or gloss.









What is Think & See?

Powerful core technologies for image sensing.

Omron is continuously developing technologies to measure, detect, or identify the positions, orientations, shapes, materials, colors, status, or attributes of things, people, vehicles, or other objects faster, more precisely, and more easily than the human eye under various conditions.

Shape Search III is based on the Think & See technology.



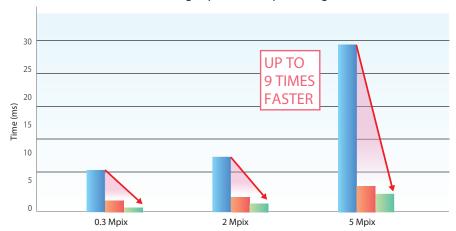
See the details of Think & See.

http://www.omron.com/technology/core/thinkAndSee/

Ultra-high-speed searching 9 times faster than before

New technology makes search algorithms up to nine times faster than before. Even for unstable image conditions (including light interference, overlapping shapes, gloss, and incomplete images), stable searching is now possible without reducing speed.

Ultra-high-speed search processing time



Input image size

Previous Search

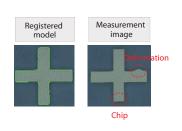
Shape Search ||| in standard mode

Shape Search III in high speed alignment mode

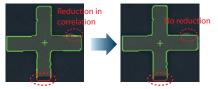
Note: The image conversion processing time is not included.

Visualization of comparisons enables easy setting of high-precision searching Patent Pending

Advanced searching is accompanied by many parameters that must be tuned to match the application. However, it is difficult for the person making the settings to see the internal process. Normally, a lot of time and effort is required to maximize tool performance. But with Shape Search III, you can visualize comparisons between the model data and a part of the measurement object to easily see when comparisons are not optimally matched. Visualization of the comparison level allows for parameters to be adjusted to quickly obtain the best performance.



You can see at a glance the difference between the registered model and measurement image



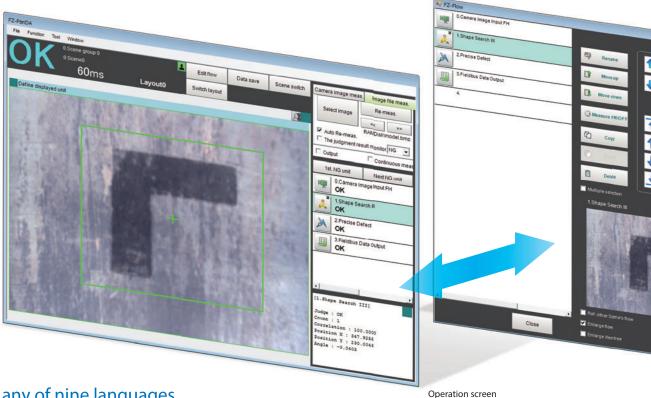
You can adjust a parameter called the Acceptable Distortion Level to enable measurements without reducing the correlation even if there is distortion. You can easily adjust this parameter while monitoring the comparison.

Preinstalled GUIs - for designers and for operators

GUI for operators

Operation interfaces are preinstalled in the FH Series.

You can display operation interfaces just by switching screens, without time-consuming interface development work.



Choose any of nine languages

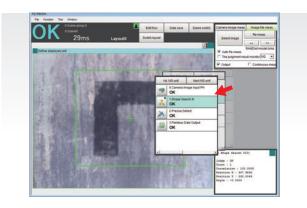
You can change display messages between nine different languages: English, Chinese, Japanese and other languages. Display the best language for the user for applications in other countries.

Touch screen ideal for on-site operation



The IP65-certified touch screen for the FH Series is available (FH-MT12). The resistive film method allows easy operation with a gloved hand.

Easy customization of interface



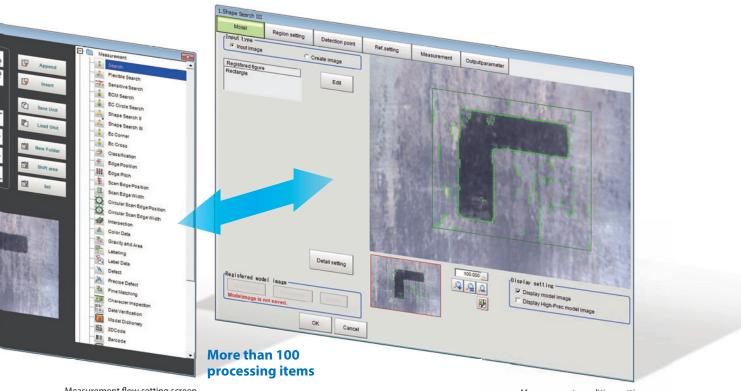
You can easily customize the preinstalled interfaces just by dragging and dropping.





GUI for designers

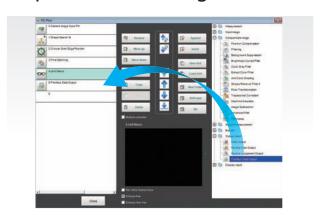
The setting of inspection and measurement can be done by combining processing items to create a flow. GUI for detailed setting for measurement conditions allows intuitive operation.



Measurement flow setting screen

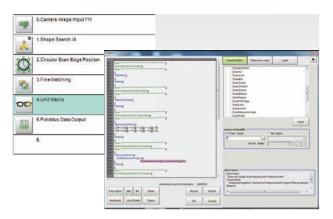
Measurement condition setting screen

Inspection flow design



Drag and drop processing items to create inspection and measurement flows. Flow creation at production sites, offline flow creation, and simulations are possible.

Simple programming

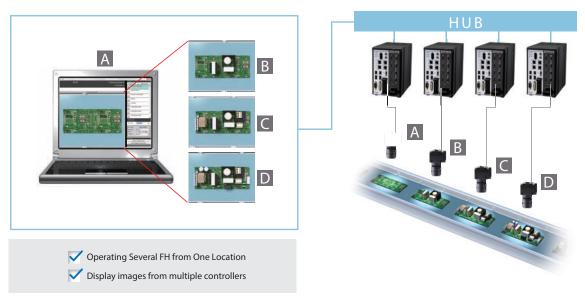


User-defined macro can be used for complex data processing that cannot be performed by inspection flows. The BASIC-like programming language facilitates the macro creation.

Flexible functionalities to provide high compatibility with manufacturing machines

Remote operation via Ethernet

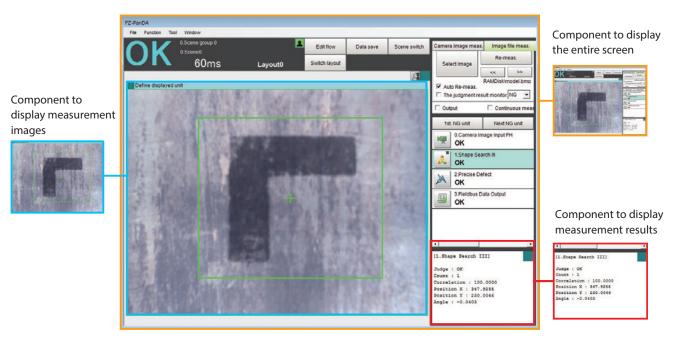
The Remote Operation Tool is provided to control the FH Series from a remote location via Ethernet. Just install the tool on your PC and specify



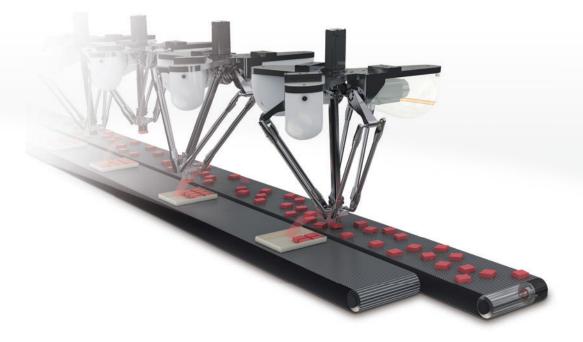
Note: Ask your OMRON representative about obtaining simulation software for a computer.

Integration into user applications

Microsoft.Net software components are supported to integrate the FH interfaces into a PC-based HMI. You can add components that display FH screens and measurement results to your HMI software just by dragging and dropping.



Note: Ask your OMRON representative about the software components.



Integrated development environment

The Automation Software Sysmac Studio integrates setting and operation of the NJ/NX Machine Automation Controller and FH Series. Simulate and debug motion control, logic, drives, and sensing on an integrated platform to reduce the work required for machine design.

Vision system simulation

Inspection and measurement by vision systems can be simulated from the Sysmac Studio.



Data tracing

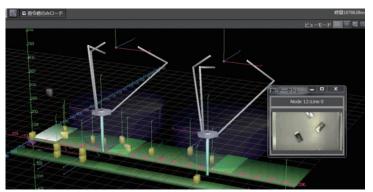
Inputs and outputs of vision systems can be traced as a time series.



3D Simulation

Patent Pending

Machine movement can be simulated based on measurement results of vision systems.



Software customization

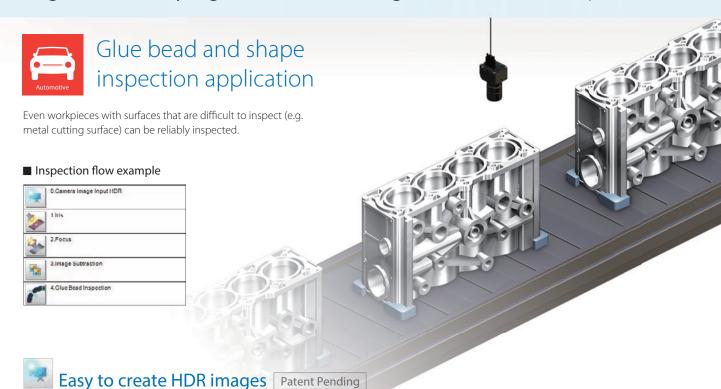
The Application Producer (FH-AP1) provides a development environment that lets you customize software preinstalled in the FH Controller. Original interfaces created with Microsoft Visual Studio can be used with the FH Controller.



Create installation files for the FH Controller with Application Producer



High immunity against ambient light for reliable inspection



The Camera Image Input HDR processing item can create optimized HDR images under variable ambient conditions. Normally, to create a HDR image, you must set the imaging conditions for each shooting. However with the FH Series, once you specify the area to capture on the image, the vision system automatically adjusts the shutter speed while capturing images and combines the images.

Image optimized for the specified area





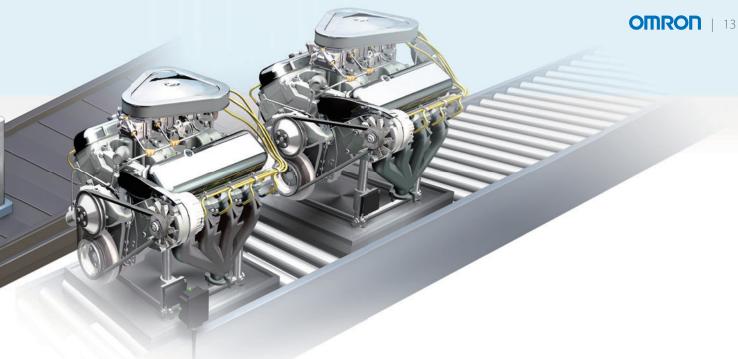
Optimum focus and aperture settings

Until now, focus and brightness settings were adjusted according to experience and intuition. But now they can be evaluated numerically and visually on graphs. This allows quick verification of optimum focus and aperture settings to eliminate inconsistencies in settings caused by worker differences so that you can achieve even higher levels of measurement accuracy.





- · Camera installation and setup are easy.
- Errors can be generated when the focus or aperture changes.
- You can determine the numerical values for the focus and aperture for the master workpiece so that essentially anyone can reproduce the same conditions.





Extraction of objects to inspect

When the complete sealing is inspected, the effects of unstable conditions can be eliminated by updating the image that is captured before applying the sealant and registered as the master. The FH Series can easily update the master image to extract the difference just by using the Image Subtraction processing item.Image Subtraction processing item.





Inspection of paths and widths Patented

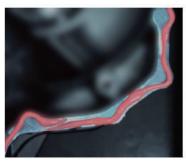
The Glue Bead Inspection processing item evaluates sealing numerically just by defining the start and end points of the object to inspect. This minimizes inconsistencies in inspection. Even complex paths can be detected accurately.

Unlike the general width inspection using edges, the profile of the object is used to inspect.

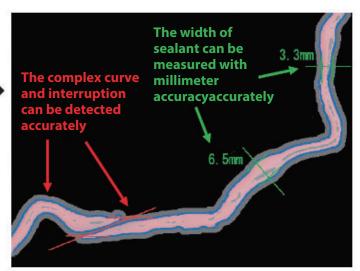
This method enables accurate inspection of complex curves and interruptions.



Difference



Original image



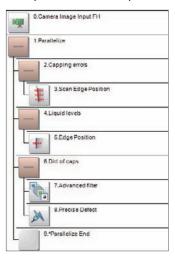
Parallel processing for high-speed inspection

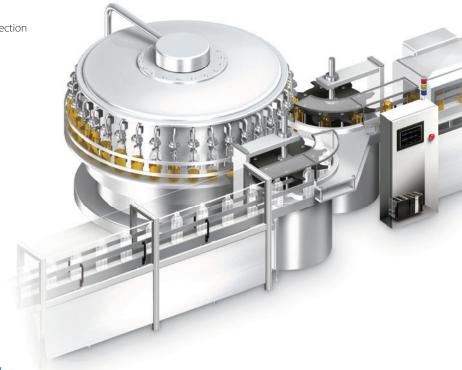


In-line external inspection application on high-speed production lines

The FH Series provides various functions for in-line inspection requiring fast inspection speed.

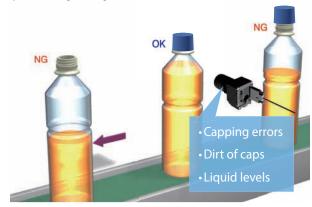
■ Inspection flow example





Trigger interval reduced by up to 75%

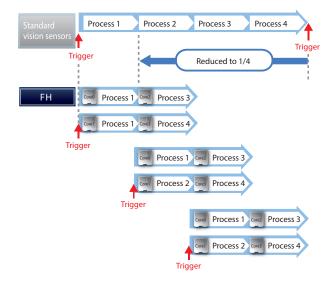
Generally, when multiple inspections are performed simultaneously, the waiting time until the next inspection occurs. Parallel processing on multi-core CPU greatly speeds up inspection by eliminating waiting time.

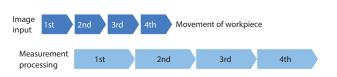


Multi-input function Continuous high-speed image capture

Higher speed from advanced image capture and parallel measurements

Each camera has its own image buffer for storing image data. This is separate from the main memory that is used for measurement processing. This allows for up to 256 frames* of continuous high-speed image capture even when the main memory is processing measurement data.





^{*} The number of images that can be captured depends on the controller and the camera that is connected to it. Refer to the user's manual for details.

Image creation technology to maximize inspection capability

Real Color Sensing

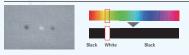


The FH Series features Omron's unique Real Color Sensing, High-speed processing using color information enables high-accuracy detection of edges and defects.



Edges are detected reliably even when the contrast between the background and subject is low.

Color segmentation processing



Color images taken by the camera are processed after being converted into black and white pixels. Based on minimum information, high speed processing is possible. Since color data is limited only to brightness, however, it takes a long time to make optical adjustments for extracting color features.

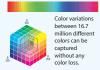
Color image processing



Color images are converted into 256 levels of black-and-white brightness and the contrasts of specific colors are enhanced. More precise, stable results can be produced compared to color segmentation. However, this method has difficulty in capturing subtle variations in color because all colors are converted into black-and-white brightness levels. Therefore, it is difficult to detect subtle changes in images with low contrast.



Real Color Sensing



Different colors are represented as different positions in the 3D RGB space. Subtle variations in color can be recognized by representing them as distances between different color pixels comprising this space. Thus, scratches and dirt can be detected accurately even in images with low contrast.

Previous image processing



🖥 Stripe Removal Filter [[

This processing item filters out the stripped pattern or other background. Reliable defect inspection can be achieved by extracting minute changes such as defects.

External appearance of bottle cap

Unfiltered image



Due to the stripes inspection is possible only in the very center of the image. To inspect the entire surface, the cap must be rotated and many images must be taken.

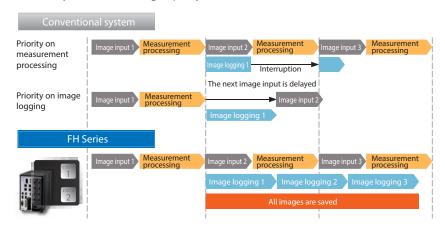


Because even the defect at the edge of the image can be detected, the number of images that is required to inspect the entire cap is greatly reduced.

Utilities

High-speed logging to save all images even during measurements

The CPU can perform parallel processing of measurements and image logging. With high-speed connection to a high-capacity (3 TB) HDD, all images on the high-speed line can be saved, which was previously difficult. Trend analysis of all saved images quickly isolates errors and facilitates countermeasures.



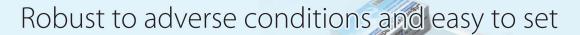
- *1. All images can be saved under the following conditions:
- •300,000-pixel camera x 1 unit
- Measurement time: 20 ms
- •Images can be saved continuously for approx. 5 days when a 3 TB HDD is used (based on 8 hours of operation a day)

Since logging was not possible during measurement, the user had to choose either measurement or logging. Accordingly, not all images could be saved or image input triggers had to be delayed depending on the measurement trigger intervals.



Solution

Measurement and image logging are processed completely in parallel. As a result, you can save all images.





Track&Trace **Applications**

A single sensor can perform everything, from GS1 code reading to image inspection, which saves costs and space in Track & Trace application.

■ Inspection flow example

哽	0.Camera Image Input FH	
OCR	1,0CR	
IIII	2.Barcode	



OCR is based on the Think & See technology, Omron's image sensing technology. See the details of Think & See.









Printed characters can be too close to each other, and characters can be printed on curved surfaces. Even in these cases, stable reading is now possible.





Curved character strings



Easy installation with built-in dictionary

Reads code

Reads characters

Many previous character reading methods required dictionary setup before usage, which was a tedious step. The built-in dictionary developed through Omron's long and rich experiences on FA sites includes a variety of fonts and possible character variations, eliminating the need of dictionary setup. You can also add non-conventional characters when special fonts are read.

Characters from most printers can be read, including dot and

impact printers.

Approx. 80 different fonts



Hot printer





Thermal printer

Both a code reader and a vision sensor were

used for inspection

3 Judges printing quality of code

4 Compares code data

with character data



Multi-line random processing

A single FH-3050/-1050 Controller can perform completely different inspections. Controllers installed for each inspection can be integrated into one, which reduces initial costs and save space.



NJ/NX Machine Automation Controller

NX-IO

EtherCAT.

MX2 Inverter

Easy commissioning of complex systems



Conveyor tracking application

The FH-1050/-3050 Controller provides the functionality to help you build the conveyor tracking system that is difficult to build because of complicated calibration.

Calibration synchronized with conveyor control can be performed via EtherCAT.

Calibration Wizard Patent Pending

Easy on-site calibration

To detect positions of workpieces carried on a conveyor and grip them with a robot hand, three different coordinate systems for the robot, conveyor, and vision must be aligned. With the FH Series, you can easily calibrate the entire system using a step-by-step wizard.

Calibration plate for wizard



From the Sysmac Studio you can print the calibration plate in various sizes, from 30 mm to 2,000 mm, according to the size of the conveyor or camera field

STEP1

Start the Calibration Wizard from the Sysmac Studio, and capture the image of the calibration plate.

STEP2

G5 Servomotors and Servo Drives

Move the calibration plate into the tracking area, and let the robot touch the target mark to automatically obtain the robot coordinates.

STEP3

The FH Controller automatically calculates by using the data including the conveyor travel distance. Calibration between the robot and FH Vision System is completed.

Removing duplication Patent Pending

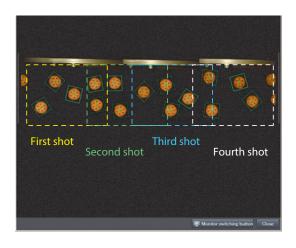
Workpieces that overlap within more than one field of view are segregated and only inserted in the picking line once. You can eliminate the need to create the program for the machine controller to identify the same workpiece.

The positions and orientations of workpieces 1 to 5 are detected and added to the picking line.

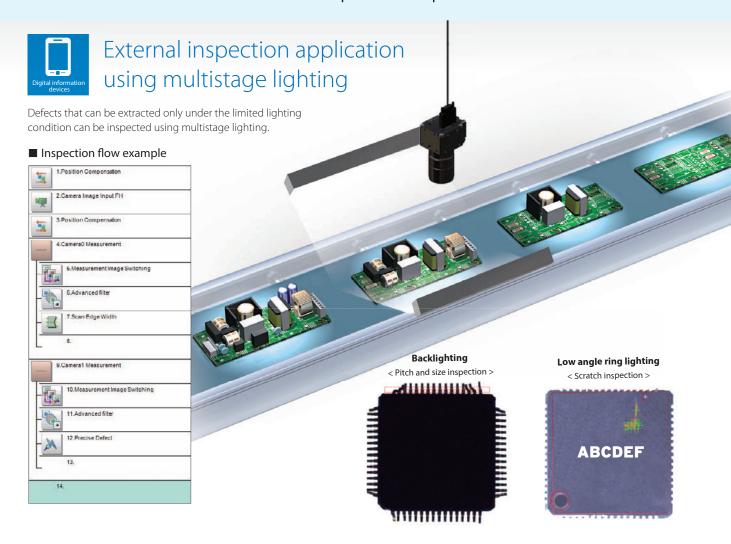
Workpieces 4 to 8 are detected, but only the data of 6 to 8 is evaluated. The data of 4 and 5 is ignored because it was already

Check ideal shooting intervals on panorama view Patented

The Conveyor Panorama Display Tool allows you to view the measurement trigger input intervals to ensure all workpieces can be detected.



Reliable execution of complex inspection



Light switching control

You can perform the inspection using images captured under different conditions by inputting multiple images in a inspection flow. The FH Series can capture images required for each inspection while changing the lighting conditions depending on inspection.

Easy light installation and setting

The use of camera-mount lighting controller eliminates the needs of power supply for lights and lighting cables, saving space and wiring. As the controller can switch lights and control brightness, you do not need to set from an external device.

Connect up to 32 lights for multistage control

You can perform multistage control with up to four lights connected to each electronic flash controller. If eight cameras are connected, up to 32 lights can be connected to the FH Controller.



Automatic generation of measurement regions

A measurement region of any shape can be automatically set by specifying a part of the area to inspect. A region of a complex shape can be set with a few operations.

Specify a part of the area to inspect





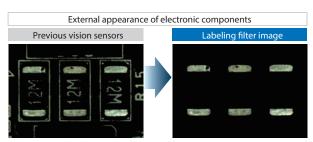
A measurement region is automatically generated from the consecutive areas in the same color





Labeling filter

This filter uses label processing to output an extracted image that contains only the specified characteristic labels.



Extraction is possible only with color or brightness information.

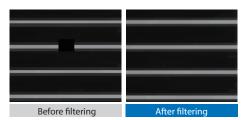
Extraction of labels with specified areas or shapes is possible.



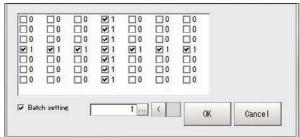
Custom filter

You can set the mask coefficients as required for these filters. The mask size can be up to 21 x 21. You can more flexibly set image smoothing, edge extractions, dilation, and erosion.

Example: Dilation/erosion in one direction



Filter coefficients

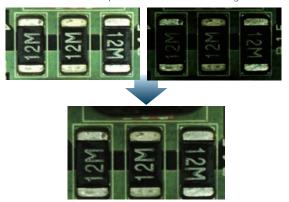


You can set the filter coefficients as required.



Calculations between images

You can perform arithmetic operations, bit operations, averaging, or maximum/minimum operations between two images.

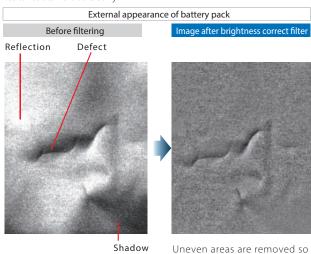


Example: You can get the average of two images that were taken under different conditions.



Brightness correct filter

This filter cuts out uneven lighting and changes in brightness caused by workpiece surface irregularities to make characteristic features stand out clearly.



The wavy inconsistencies are judged as defects.

that only the defect appears in the inspection.

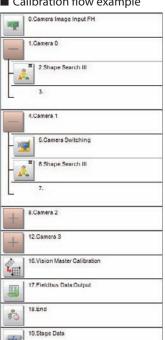


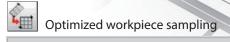


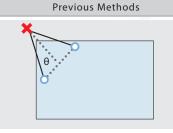
Automatic precise calibration

Just execute the flow created for calibration to complete calibration for stages.

■ Calibration flow example



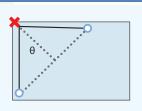




With the previous method, the user specifies the sampling points for calibration.

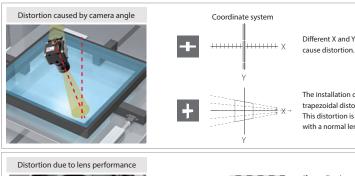
If the rotation angle is not wide enough, the calibration accuracy is low.

FH Series

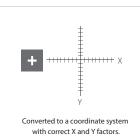


The FH Series automatically calculates sampling points that maximize the rotation angle by combining parallel movement with rotation movement within the travel range

High calibration accuracy that is not dependent on operator skill is assured.



Three types of Different X and Y magnifications The installation can cause trapezoidal distortion. This distortion is even greater with a normal lens.





The influence of distortion increase towards the edges of the field of view.

performed away from the center of the field of view, distortion reduces the calibration



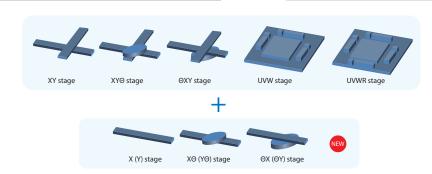
Conversion is made to the coordinate system even at the edges of the field of view



Stages

Patent Pending

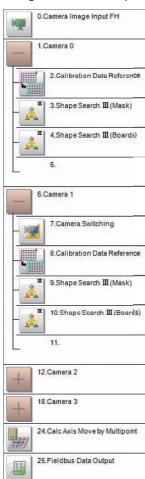
The single axis $+\Theta$ axis stages which are popular today as well as UVW stages can be used. The use of the same axis for both the handling axis of a manufacturing machine and the axis for positioning simplifies machine configuration.



High-speed and high-precision positioning

High-precision positioning can be performed by referencing calibration parameters. Fast object detection and calculation by utilizing parallel processing increase machine speeds.

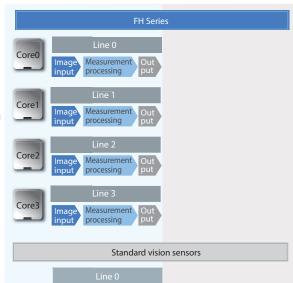
■ Alignment flow example

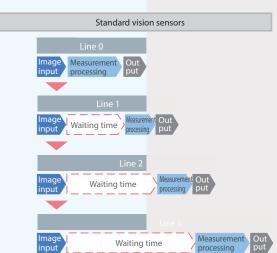




Parallel processing

Object detections using multiple cameras are performed in parallel. Pipeline processing enables fast detection without waiting.



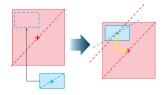




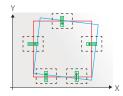
Available alignment methods

The processing items specialized for alignment calculations are provided, enabling flexible positioning of any workpiece.

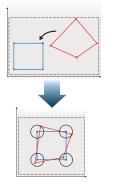
·Alignment using positions and angles



•Alignment with side measurements



·Alignment using corresponding points



Data communications cycle 125 µs

EtherCAT machine control network

You can use EtherCAT to connect NJ/NX Machine Automation Controllers and motion control G5 Servomotors and Servo Drives for high-speed control from workpiece detection to starting axis motion.

Communications cycle



Time from trigger input to producing measurement results



Note: The times given above are typical times. They depend on parameter settings.

Versatile selection

You can select the best combination of camera and controller for your application.

Software assets can be shared between controllers. This allows you to Install devices with the capabilities you need, anywhere you need them.

Cameras

Choose the right camera to suit your resolution requirements. Easy-to-use cameras with built-in light are also available.

Resolution	Standard camera	High-speed camera	Rolling shutter camera	Camera with built-in light
12 Mpix	-	FH-S□12	_	_
5 Mpix/ 4 Mpix	FZ-S□5M	FH-S□04	FH-S□05R	-
2 Mpix	FZ-S□2M	FH-S□02	-	-
0.3 Mpix	FZ-S□	FH-S□	-	FZ-SQ 🗆 🗆 🗆

FH Controllers

Select a controller based on the required processing speed and network.All controllers can connect to any camera.

Model	Multi-line processing
FH-3050-□□	\checkmark
FH-1050-□□	\checkmark
FH-L550-□□	_





Lights

Omron offers a complete line-up of lights required for image processing. The use of the camera-mount lighting controller allows you to control lighting conditions from the FH Series, making machine configuration simple.

Description	LED	High-brightness LED
Camera-mount Lighting Controller	FLV-TCC	FL-TCC
Bar Light	FLV-BR	FL-BR
Direct Ring Light	FLV-DR	FL-DR
Low Angle Ring Light	FLV-DL	_
Coaxial Light	FLV-CL	_
Shadowless Light	FLV-FR/FP/FS/FQ	_
Spot Light	FLV-EP	-
Direct Back/Edge Type Ligh	FLV-DB/FB	-
Dome Light	FLV-DD	-

Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

Camera cables

The cable line-up includes handy bend-resistant cables and right-angle cables. Use the FZ-VSJ Cable Extension Unit for further extension of the cable.

Description	Model
Camera Cable	FZ-VS3 □□
Right-angle Camera Cable	FZ-VSL3□□
Bend-resistant Camera Cable	FZ-VSB3 □□
Bend-resistant Right-angle Camera Cable	FZ-VSLB3 □□
Cable Extension Unit	FZ-VSJ

Application Producer

This software enables you to install applications you created on the FH Series.

Description	Model
DVD for installation	FH-AP1
Software license	FH-AP1L

No. of connectable cameras	Fieldbus
8 max.	EtherNet/IP,EtherCAT
8 max.	EtherNet/IP,EtherCAT
4 max.	EtherNet/IP



Ether CAT.

EtherNet/IP



Touch panel monitor

The touch panel monitor is optimized for the operation of the FH Series.

Description	Model
Touch Panel Monitor 12.1 inches	FH-MT12
DVI-Analog Conversion Cable for Touch Panel Monitor	FH-VMDA □□
USB Cable for Touch Panel Monitor	FH-VUAB □□

*RS-232C cables for long-distance connections are also available. Refer to Ordering Information for details.



Vision System

FH-Series

Like or even more than the human eye

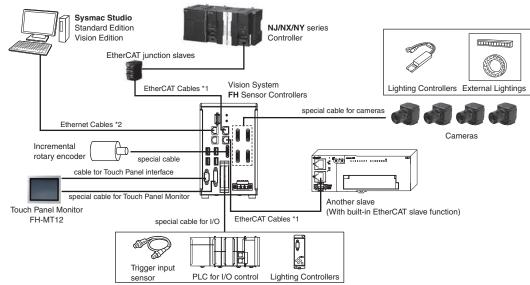
- A complete line-up of cameras for various applications
- Powerful controllers for fast and precise inspection and measurement
- · Software for easy setting of various measurements



System configuratio

EtherCAT connections for FH series

Example of the FH Sensor Controllers (4-camera type)



^{*1.} To use STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT and RJ45 connector.
*2. To use STP (shielded twisted-pair) cable of category 5 or higher for Ethernet and RJ45 connector.

Ordering Information

FH Series Sensor Controllers

Item		CPU	No. of cameras	Output	Model
		High-speed Controllers	2	NPN/PNP	FH-3050
1 9 7 7			4	NPN/PNP	FH-3050-10
	Box-type	(4 core)	8	NPN/PNP	FH-3050-20
	controllers	Standard	2	NPN/PNP	FH-1050
		Controllers (2 core)	4	NPN/PNP	FH-1050-10
- 1			8	NPN/PNP	FH-1050-20
	71.	Lite Controllers (2 core)	2	NPN/PNP	FH-L550
	controllers		4	NPN/PNP	FH-L550-10

Cameras

ltem		Descriptions	Color / Monochrome	Image Acquisition Time *1	Model
	High-speed Digital CMOS Cameras	12 million pixels (Up to four cameras can be connected to one Controller. Up to eight cameras other than	Color	25.7 ms *2	FH-SC12
C	(Lens required)	12 million-pixel cameras can be connected to a FH-3050-20 or a FH-1050-20.)	Monochrome	2011 1110 2	FH-SM12
		4 million pixels	Color	8.5 ms *2	FH-SC04
		4 million pixels	Monochrome	0.5 1115 2	FH-SM04
O COL	High-speed Digital CMOS Cameras	2 million pixels	Color	4.6 ms *2	FH-SC02
	(Lens required)	2 million pixels	Monochrome	4.0 1113 2	FH-SM02
		300,000 pixels	Color	3.3 ms	FH-SC
92.		ουσ,σου μιχειο	Monochrome	0.0 1115	FH-SM
	Digital CMOS Cameras	Consider wheels	Color		FH-SC05R
	(Lens required)	5 million pixels	Monochrome	71.7ms	FH-SM05R
		5 million pixels	Color	38.2 ms	FZ-SC5M3
			Monochrome		FZ-S5M3
	Digital CCD/CMOS Cameras	2 million pixels	Color	33.3 ms	FZ-SC2M
	(Lens required)		Monochrome		FZ-S2M
			Color	40.5	FZ-SC
ON E		300,000 pixels	Monochrome	12.5 ms	FZ-S
	High-speed Digital		Color	4.9 ms	FZ-SHC
	CCD Cameras (Lens required)	300,000 pixels	Monochrome		FZ-SH
		000 000	Color	40.5	FZ-SFC
	Small Digital	300,000-pixel flat type	Monochrome	12.5 ms	FZ-SF
	 CCD Cameras (Lenses for small camera required) 	300,000-pixel pen type	Color	12.5 ms	FZ-SPC
	,	Suo,uuu-pixei peri type	Monochrome	12.5 1118	FZ-SP
10		Narrow view	Color		FZ-SQ010F
	Intelligent Compact Digital CMOS Camera (Camera + Manual Focus Lens + High power Lighting)	Standard view	Color	16.7 ms	FZ-SQ050F
•		Wide View (long-distance)	Color	10./ MS	FZ-SQ100F
	3	Wide View (short-distance)	Color		FZ-SQ100N

^{*1} The image acquisition time does not include the image conversion processing time of the sensor controller.
The camera image input time varies depending on the sensor controller model, number of cameras, and camera settings.
Check before you use the camera.
*2 Frame rate in high speed mode when the camera is connected using two camera cables. For other conditions, please refer to the chart below.

• 1		· ·						
Model		FH-SM02	FH-SC02	FH-SM04	FH-SC04	FH-SM12	FH-SC12	
Image Acquisition Time 2 Cables *1 1 Cables	High Speed Mode *2	4.6ms		8.5ms		25.7ms		
	Standard Mode	9.7ms		17.9ms		51.3ms		
	1 Cables	High Speed Mode *2	9.2ms		17.0ms		51.3ms	
	1 Capies	Standard Mode	19.	3ms	35.8	Bms	102.	0ms

^{*1} Two Camera ports of the controller are used per one camera.
*2 Up to 5 m Camera Cable lengh.

Camera Cables

Item	Descriptions	Model *3
Ó	Camera Cable Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VS3 □M
19	Bend resistant Camera Cable Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VSB3 □M
9	Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5m, or 10 m *2	FZ-VSL3 □M
9	Bend resistant Right-angle Camera Cable *1 Cable length: 2 m, 3 m, 5 m, or 10 m *2	FZ-VSLB3 □M
.9	Long-distance Camera Cable Cable length: 15 m *2	FZ-VS4 15M
.0	Long-distance Right-angle Camera Cable *1 Cable length: 15 m *2	FZ-VSL4 15M
	Cable Extension Unit Up to two Extension Units and three Cables can be connected. (Maximum cable length: 45 m *2)	FZ-VSJ

^{*1} This Cable has an L-shaped connector on the Camera end.
*2 The maximum cable length depends on the Camera being connected, and the model and length of the Cable being used. For further information,please refer to the "Cameras / Cables Connection Table" and "Maximum Extension Length Using Cable Extension Units FZ-VSJ table".
When a high-speed Digital CMOS camera FH-S□02/-S□04/-S□12 is used in the high speed mode of transmission speed, two camera cables are required.
*3 Insert the cables length into □ in the model number as follows. 2 m = 2, 3 m = 3, 5 m = 5, 10 m = 10

Cameras / Cables Connection Table

			High-speed Digital CMOS cameras							Digital CMOS Camera
Type of			300,000-pixel	2 millio	n-pixel	4 millio	n-pixel	12 million-pixel		5 megapixel camera
	Model	Cable	FH-SM/SC	FH-SM	02/SC02	FH-SM04/SC04		FH-SM12/SC12		FH-SC05R/SM05R
camera	iiiouoi	length		High speed mode	Standard mode	High speed mode	Standard mode	High speed mode	Standard mode	
			_	of transmission speed select	_					
		2 m	Yes	Yes						
Camera Cables Right-angle	FZ-VS3 FZ-VSL3	3 m	Yes	Yes						
camera cables		5 m	Yes	Yes						
		10 m	Yes	No	Yes	No	Yes	No	Yes	Yes
Bend resistant	FZ-VSB3 FZ-VSLB3	2 m	Yes	Yes						
camera cables Bend resistant		3 m	Yes	Yes						
Right-angle		5 m	Yes	Yes						
Camera Cable		10 m	Yes	No	Yes	No	Yes	No	Yes	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	No	Yes	No	Yes	No	Yes	Yes

		odel Cable length	Digital CCD/CMOS cameras			Small digital	High-speed	Intelligent Compact
Type of camera	Model		300,000-pixel	2 million-pixel	5 million-pixel	CCD cameras Pen type / flat type	Digital CCD cameras	Digital CMOS Camera
			FZ-S/SC	FZ-S2M/SC2M	FZ-S5M3/SC5M3	FZ-SF/SFC FZ-SP/SPC	FZ-SH/SHC	FZ-SQ□
		2 m	Yes	Yes	Yes	Yes	Yes	Yes
Camera Cables Right-angle	FZ-VS3 FZ-VSL3	3 m	Yes	Yes	Yes	Yes	Yes	Yes
camera cables		5 m	Yes	Yes	Yes	Yes	Yes	Yes
		10 m	Yes	Yes	No	Yes	Yes	Yes
Bend resistant		2 m	Yes	Yes	Yes	Yes	Yes	Yes
camera cables Bend resistant	FZ-VSB3	3 m	Yes	Yes	Yes	Yes	Yes	Yes
Right-angle	FZ-VSLB3 5 m 10 m	5 m	Yes	Yes	Yes	Yes	Yes	Yes
Camera Čable		10 m	Yes	Yes	No	Yes	Yes	Yes
Long-distance camera cable Long-distance right-angle camera cable	FZ-VS4 FZ-VSL4	15 m	Yes	Yes	No	Yes	Yes	Yes

Maximum Extension Length Using Cable Extension Units FZ-VSJ

		T	No. of CH used	Maximum cable length	Max. number of	Using Cable Extension Units FZ-VSJ		
Item	Model	Transmission speed (*1)	for connection (*2)	using 1 Camera Cable (*1)	connectable Ex- tension Units	Max. cable length	Connection configuration	
	FH-SM/SC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
		Standard	1	15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
High-speed Digital CMOS Cameras	FH-SM02/SC02 FH-SM04/SC04	Staridard	2	15 m (Using FZ-VS4/VSL4)	4 (*3)	45 m	[Configuration 2] Camera cable: 15 m × 6 Extension Unit: 4	
	FH-SM12/SC12	High speed	1	5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2	
			2	5 m (Using FZ-VS□/VSL□)	4 (*3)	15 m	[Configuration 4] Camera cable: 5 m × 6 Extension Unit: 4	
Digital CMOS Cameras	FH-SC05R FH-SM05R			15m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
Digital CCD/CMOS	FZ-S/SC FZ-S2M/SC2M			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
Cameras	FZ-S5M3/SC5M3			5 m (Using FZ-VS□/VSL□)	2	15 m	[Configuration 3] Camera cable: 5 m × 3 Extension Unit: 2	
Small Digital CCD Cameras Flat type/ Pen type	FZ-SF/SFC FZ-SP/SPC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m × 3 Extension Unit: 2	
High-speed Digital CCD Cameras	FZ-SH/SHC			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m X 3 Extension Unit: 2	
Intelligent Compact Digital CMOS Camera	FZ-SQ□			15 m (Using FZ-VS4/VSL4)	2	45 m	[Configuration 1] Camera cable: 15 m X 3 Extension Unit: 2	

^{*1} The FH-S — enables switching between standard and high speed modes. In high speed mode, images can be transferred approximately two times faster than in standard mode, but the connectable cable length will be shorter.

^{*2} The FH-S has two channels to connect Camera Cables. Connection to two channels makes image transfer two times faster than connection to one channel: high speed mode using two channels can transfer approximately four times as many images as standard mode using one channel.

^{*3} Each channel can be used to connect up to two Cable Extension Units: up to four extension units, two channels x two units, can be connected by using two channels.

Connection Configuration

	Connection configuration using the maximum length of Camera Cables	Remarks
Configuration 1	15 m 15 m 15 m (2) (3)	
Configuration 2	CH1 15 m 15 m 15 m 15 m (1) (2) (3) (3) 15 m 15	Camera cable connector CH2 Camera cable connector CH1
Configuration 3	5 m 5 m 5 m (3)	
Configuration 4	CH1 5 m 5 m 5 m 5 m 5 m CH2 (4) (5) (6)	Camera cable connector CH2 Camera cable connector CH1

Select the Camera Cables between the Controller and Extension Unit, between the Extension Units, and between the Extension Unit and Camera according to the connected Camera. Different types or lengths of Camera Cables can be used for (1), (2), and (3) as well as for (4), (5), and (6). However, the type and length of Camera Cable (1) must be the same as those of Camera Cable (4), (2) must be the same as (5), and (3) must be the same as (6).

Touch Panel Monitor

Item	Descriptions	Model
	Touch Panel Monitor 12.1 inches For FH Sensor Controllers *	FH-MT12

^{*} FH Series Sensor Controllers version 5.32 or higher is required.

Touch Panel Monitor Cables

Item	Descriptions	Model
40	DVI-Analog Conversion Cable for Touch Panel Monitor Cable length: 2 m, 5 m or 10 m	FH-VMDA □M *1
40	RS-232C Cable for Touch Panel Monitor Cable length: 2 m, 5 m or 10 m	XW2Z-□□□PP-1 *2
/9	USB Cable for Touch Panel Monitor Cable length: 2 m or 5 m	FH-VUAB □M *1

Insert the cables length into \square in the model number as follows. 2 m = 2, 5 m = 5, 10 m = 10

A video signal cable and an operation signal cable are required to connect the Touch Panel Monitor.

Signal	Cable	2 m	5 m	10 m
Video signal	DVI-Analog Conversion Cable	Yes	Yes	Yes
Touch panel operation signal	USB Cable	Yes	Yes	No
	RS-232C Cable	Yes	Yes	Yes

Parallel I/O Cables/Encoder Cable

Item	Descriptions	Model
-9	Parallel I/O Cable *1 Cable length: 2m, 5m or 15m	XW2Z-S013- □ *2
	Parallel I/O Cable for Connector-terminal Conversion Unit *1 Cable length: 0.5 m, 1 m, 1.5 m, 2 m, 3 m, 5 m Connector-Terminal Block Conversion Units can be connected (Terminal Blocks Recommended Products: OMRON XW2R-□34G-T)	XW2Z-□□□EE *3
	Connector-Terminal Block Conversion Units, General-purpose devices	XW2R-□34GD-T *4
\O	Encoder Cable for line-driver Cable length: 1.5 m	FH-VR 1.5M

Insert the cables length into $\square\square$ in the model number as follows. 2 m = 200, 5 m = 500, 10 m = 010.

² Cables are required for all I/O signals.
Insert the cables length into □ in the model number as follows. 2 m = 2, 5 m = 5, 15 m = 15
Insert the cables length into □□□ in the model number as follows. 0.5 m = 050, 1 m = 100, 1.5 m = 150, 2 m = 200, 3 m = 300, 5 m = 500
Insert the wiring method into □ in the model number as follows. Phillips screw = J, Slotted screw (rise up) = E, Push-in spring = P
Refer to the XW2R Series catalog (Cat. No. G077) for details.

Parallel Converter Cable

When you change to connect the F series, FZ5 series, or FZ5-L series to FH series Sensor Controller, you can convert by using the appropriate parallel converter cable of FH-VPX series under the usable condition.

Item	Applicable Model		Usable Condition	Model
	FZ⊡ series		Do not use RESET signal. * Use with COMIN and COMUT are same power source.	FH-VPX-FZ
1	FZ□-L35x series		Do not use RESET signal. *	FH-VPX-FZL
	F160 series F160-C10		Do not use RESET signal.* Use with COMIN and COMOUT are same power source. Do not use DI5 and DI6.	FH-VPX-F160
	F210 series	F210-C10	Do not use RESET signal. *	
*)	FZ TO SELIES	F210-C10-ETN	Use with COMIN and COMOUT are same power source.	FH-VPX-F210
	F500 series	F500-C10	Do not use DI8 and DI9.	

^{*} Even if RESET signal cannot be use by conversion, conversion is possible to convert satisfying other usable condition. Note: Cannot be used for the F160-C10CP/-C10CF.

Recommended EtherCAT and EtherNet/IP Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT. Use Straight or cross STP (shielded twisted-pair) cable of category 5 or higher for EtherNet/IP.

Item	Descriptions				Model
				Cable length: 0.3 m	XS6W-6LSZH8SS30CM-Y
		Cable with Connectors on Both Ends (RJ45/	RJ45)	Cable length: 0.5 m	XS6W-6LSZH8SS50CM-Y
		Standard RJ45 plugs type *1 Wire Gauge and Number of Pairs: AWG26, 4	1 noir Cabla	Cable length: 1 m	XS6W-6LSZH8SS100CM-Y
-		Cable Sheath material: LSZH *2	+-pair Cable	Cable length: 2 m	XS6W-6LSZH8SS200CM-Y
-		Cable color: Yellow *3		Cable length: 3 m	XS6W-6LSZH8SS300CM-Y
				Cable length: 5 m	XS6W-6LSZH8SS500CM-Y
				Cable length: 0.3 m	XS5W-T421-AMD-K
		Cable with Connectors on Both Ends (RJ45/	D (45)	Cable length: 0.5 m	XS5W-T421-BMD-K
M		Rugged RJ45 plugs type *1	H040)	Cable length: 1 m	XS5W-T421-CMD-K
-0		Wire Gauge and Number of Pairs: AWG22,	2-pair Cable	Cable length: 2 m	XS5W-T421-DMD-K
		Cable color: Light blue		Cable length: 5 m	XS5W-T421-GMD-K
	For EtherCAT			Cable length: 10 m	XS5W-T421-JMD-K
	For EtherCA1			Cable length: 0.5 m	XS5W-T421-BM2-SS
		Cable with Connectors on Both Ends (M12 Straight/M12 Straight) Shield Strengthening Connector cable *4 M12/Smartclick Connectors Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black		Cable length: 1 m	XS5W-T421-CM2-SS
				Cable length: 2 m	XS5W-T421-DM2-SS
-0				Cable length: 3 m	XS5W-T421-EM2-SS
				Cable length: 5 m	XS5W-T421-GM2-SS
				Cable length: 10 m	XS5W-T421-JM2-SS
				Cable length: 0.5 m	XS5W-T421-BMC-SS
		Cable with Connectors on Both Ends (M12 S Shield Strengthening Connector cable *4	Straight/RJ45)	Cable length: 1 m	XS5W-T421-CMC-SS
15		M12/Smartclick Connectors Rugged RJ45 plugs type Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black		Cable length: 2 m	XS5W-T421-DMC-SS
0				Cable length: 3 m	XS5W-T421-EMC-SS
				Cable length: 5 m	XS5W-T421-GMC-SS
				Cable length: 10 m	XS5W-T421-JMC-SS
				Hitachi Metals, Ltd.	NETSTAR-C5E SAB 0.5 × 4P *5
	For EtherCAT and EtherNet/IP	Wire Gauge and Number of	Cables	Kuramo Electric Co.	KETH-SB *5
		Pairs: AWG24, 4-pair Cable		SWCC Showa Cable Systems Co.	FAE-5004 *5
			RJ45 Connectors	Panduit Corporation	MPS588-C *5
			Cables	Kuramo Electric Co.	KETH-PSB-OMR *6
		Wire Gauge and Number of Pairs: AWG22, 2-pair Cable	Cables	JMACS Japan Co.,Ltd.	PNET/B *6
			RJ45 Assembly Connector	OMRON	XS6G-T421-1 *6

Note: Please be careful while cable processing, for EtherCAT, connectors on both ends should be shield connected and for EtherNet/IP, connectors on only one end should be shield connected.

shield connected.

Standard type cables length 0.2, 0.3, 0.5, 1, 1.5, 2, 3, 5, 7.5, 10, 15 and 20 m are available.

Rugged type cables length 0.3, 0.5, 1, 2, 3, 5, 10 and 15 m are available.

For details, refer to Cat.No.G019.

The lineup features Low Smoke Zero Halogen cables for in-cabinet use and PUR cables for out-of-cabinet use. Although the LSZH cable is single shielded, its communications and noise characteristics meet the standards.

Cables colors are available in blue, yellow, or Green.

For details, contact your OMRON representative.

We recommend you to use above cable for EtherCAT and EtherNet/IP, and RJ45 Connector together.

We recommend you to use above cable for EtherCAT and EtherNet/IP, and RJ45 Assembly Connector together.

Automation Software Sysmac Studio

Please purchase a DVD and licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. The license does not include the DVD.

Item	Specifications		Model	
item	Specifications	Number of licenses	Media	Wodel
	The Sysmac Studio is the software that provides an integrated	(Media only)	DVD *1	SYSMAC-SE200D
	environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU	1 license	_	SYSMAC-SE201L
	Units, NY-series Industrial PC, EtherCat Slave, and the HMI.	3 license	-	SYSMAC-SE203L
Sysmac Studio	Windows 8.1 (32-bit/64-bit version) / Windows 10 (32-bit/64-bit version)	10 license	_	SYSMAC-SE210L
Standard Edition Ver.1.□□		30 license	_	SYSMAC-SE230L
		50 license	_	SYSMAC-SE250L
Sysmac Studio Vision Edition Ver.1.□□ *2 *3	Sysmac Studio Vision Edition is a limited license that provides selected functions required for FH-serise/FQ-M-series Vision Sensor settings.	1 license	_	SYSMAC-VE001L
Sysmac Studio Robot Additional Option *3	Sysmac Studio Robot Additional Option is a license to enable the Vision & Robot integrated simulation.	1 license	_	SYSMAC-RA401L

Note: 1. Site licenses are available for users who will run Sysmac Studio on multiple computers. Ask your OMRON sales representative for details. 2. Sysmac Studio version 1.07 or higher supports the FH Series. Sysmac Studio does not support the FH-L550/-L550-10.

- The same media is used for both the Standard Edition and the Vision Edition. With the Vision Edition, you can use only the setup functions for FH-series/FQ-M-series Vision Sensors. This product is a license only. You need the Sysmac Studio Standard Edition DVD media to install it.

Development Environment

Please purchase a CD-ROM and licenses the first time you purchase the Application Producer. CD-ROMs and licenses are available individually. The license does not include the CD-ROM.

Product	Specifications	Number of Model Standards licenses	Media	Model
	Software components that provide a development environment to further customize the standard controller features of the FH Series. System requirements: • CPU: Intel Pentium Processor (SSE2 or higher) • OS: Windows 7 Professional (32/64bit) or Enterprise(32/64bit) or Ultimate (32/64bit), Windows 8 Pro(32/64bit) or Enterprise(32/64bit),	— (Media only)	CD-ROM	FH-AP1
Application Producer	Windows 8.1 Pro(32/64bit) or Enterprise(32/64bit) • .NET Framework: .NET Framework 3.5 or higher • Memory: At least 2 GB RAM Available disk space: At least 2 GB • Browser: Microsoft® Internet Explorer 6.0 or later • Display: XGA (1024 × 768), True Color (32-bit) or higher • Optical drive: CD/DVD drive The following software is required to customize the software: Microsoft® Visual Studio® 2010 Professional or Microsoft® Visual Studio® 2008 Professional or Microsoft® Visual Studio® 2012 Professional	1 license	_	FH-AP1L

FH-Series

Accessories

Item			Descriptions		Model
	LCD Monitor 8.4 inches				FZ-M08
.0			H sensor controller, please use it	2 m	FZ-VM 2M
	in combination with a DVI-	I-RGB Conversion C		5 m	FZ-VM 5M
	DVI-I -RGB Conversion Co	onnector			FH-VMRGB
◆ Barrier	USB Memory		2 GB 8 GB		FZ-MEM2G FZ-MEM8G
	OD 0		2 GB		HMC-SD291
5.0 2m	SD Card		4 GB		HMC-SD491
	Display/USB Switcher				FZ-DU
_	Mouse Recommended Propriverless wired mouse	oducts			
	(A mouse that requires the	mouse driver to be	installed is not supported.)		
E .	EtherCAT junction slaves	3 port	Power supply voltage: 20.4 to 28.8 VDC	Current consumption: 0.08 A	GX-JC03
200 200 200		6 port	(24 VDC -15 to 20%)	Current consumption: 0.17 A	GX-JC06
1	Industrial Switching Hubs	3 port	Failure detection: None	Current consumption: 0.08 A	W4S1-03B
40	for EtherNet/IP and Ether- net	5 port	Failure detection: None	Current consumption:	W4S1-05B
		5 port	Failure detection: Supported	0.12 A	W4S1-05C
_	Calibration Plate			FZD-CAL	
		DIN rail mounting b	oracket		FH-XDM-L
	Common items related to DIN rail	DIN 35mm rail	PHOENIX CONTACT	Length: 75.5/95.5/ 115.5/200 cm Height: 7.5mm Material: Iron Surface: Conductive	NS 35/7,5 PERF
	(for FH-L550/-L550-10)	DIN SSIIII TAII	THOLINIX GONTAGT	Length:75.5/95.5/ 115.5/200 cm Height: 15mm Material: Iron Surface: Conductive	NS 35/15 PERF
		End plate	PHOENIX CONTACT	Need 2 pieces each Sensor Controller	CLIPFIX 35
	External Lighting	<u> </u>		_	FLV Series *
	External Lighting				FL Series *
			For FLV-Series	Camera Mount Light- ing Controller	FLV-TCC Series *
88	Lighting Controller (Required to control external lighting from a Co	ntroller)		Analog Lighting Controller	FLV-ATC Series *
			For FL-Series	Camera Mount Light- ing Controller	FL-TCC Series *
				Mounting Bracket	FQ-XL
	For Intelligent Compact Dig	gital CMOS Camera		Mounting Brackets	FQ-XL2
				Polarizing Filter Attachment	FQ-XF1
	Mounting Bracket for FZ-S				FZ-S-XLC
	Mounting Bracket for FZ-S Mounting Bracket for FZ-S				FZ-S2M-XLC FZ-SH-XLC
_	Mounting Bracket for FZ-S Mounting Bracket for FH-S				FZ-SH-XLC FH-SM-XLC
	ourning Draonot for 1 11-0				
	Mounting Bracket for FH-S	□12			FH-SM12-XLC

^{*} Refer to the Vision Accessory Catalog (Cat. No. Q198) for details.

Lenses

C-mount Lens for 1/3-inch image sensor (Recommend: FZ-S□/FZ-SH□/FH-S□)

Model	3Z4S-LE SV-03514V	3Z4S-LE SV-04514V	3Z4S-LE SV-0614V	3Z4S-LE SV-0813V	3Z4S-LE SV-1214V	3Z4S-LE SV-1614V	3Z4S-LE SV-2514V	3Z4S-LE SV-3518V	3Z4S-LE SV-5018V	3Z4S-LE SV-7527V	3Z4S-LE SV-10035V
Appearance/ Dimensions (mm)	29.5 dia 30.4	29.5 dia. 29.5	29 dia. 30.0	28 dia. 34.0	29 dia. 29.5	29 dia. 24.0	29 dia. 24.5	29 dia. 33.5[WD:∞] to 37.5[WD:300]	32 dia. 37.0[WD:∞] to 39.4[WD:1000]	32 dia. 42.0[WD:∞] to 44.4[WD:1000]	32 dia. 43.9[WD:∞] to 46.3[WD:1000]
Focal length	3.5 mm	4.5 mm	6 mm	8 mm	12 mm	16 mm	25 mm	35 mm	50 mm	75 mm	100 mm
Aperture (F No.)	1.4 to Close	1.4 to Close	1.4 to Close	1.3 to Close	1.4 to Close	1.4 to Close	1.4 to Close	1.8 to Close	1.8 to Close	2.7 to Close	3.5 to Close
Filter size	_	_	M27.0 P0.5	M25.5 P0.5	M27.0 P0.5	M27.0 P0.5	M27.0 P0.5	M27.0 P0.5	M30.5 P0.5	M30.5 P0.5	M30.5 P0.5
Maximum sensor size	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch	1/3 inch
Mount		•	•	•	•	•	C mount				

C-mount Lens for 2/3-inch image sensor (Recommend: FZ-S \square 2M/FZ-S \square 5M3/FH-S \square 05R) (3Z4S-LE SV-7525H and 3Z4S-LE SV-10028H can also be used for FH-S \square 02 and FH-S \square 04)

Model	3Z4S-LE SV-0614H	3Z4S-LE SV-0814H	3Z4S-LE SV-1214H	3Z4S-LE SV-1614H	3Z4S-LE SV-2514H	3Z4S-LE SV-3514H	3Z4S-LE SV-5014H	3Z4S-LE SV-7525H	3Z4S-LE SV-10028H
Appearance/ Dimensions (mm)	42 dia. 57.5	39 dia. 52.5	30 dia. 51.0	30 dia. 47.5	30 dia. 36.0	44 dia. 45.5	44 dia. 57.5	36 dia. 49.5[WD:xc] to 54.6[WD:1200]	39 dia. 66.5[WD:∞] to 71.6[WD:2000]
Focal length	6 mm	8 mm	12 mm	16 mm	25 mm	35 mm	50 mm	75 mm	100 mm
Aperture (F No.)	1.4 to 16	2.5 to Close	2.8 to Close						
Filter size	M40.5 P0.5	M35.5 P0.5	M27.0 P0.5	M27.0 P0.5	M27.0 P0.5	M35.5 P0.5	M40.5 P0.5	M34.0 P0.5	M37.5 P0.5
Maximum sensor size	2/3 inch	1 inch	1 inch						
Mount					C moun	ŀ			

C-mount Lens for 1-inch image sensor (Recommend: FH-S \square 02/FH-S \square 04) (3Z4S-LE SV-7525H with focal length of 75 mm and 3Z4S-LE SV-10028H with focal length of 100 mm are also available.)

Model	3Z4S-LE VS-0618H1	3Z4S-LE VS-0814H1	3Z4S-LE VS-1214H1	3Z4S-LE VS-1614H1N	3Z4S-LE VS-2514H1	3Z4S-LE VS-3514H1	3Z4S-LE VS-5018H1
Appearance/ Dimensions (mm)	64.5 dia. 57.2	57 dia. 59	38 dia. 48.0[WD:∞] to 48.5[WD:300]	38 dia. 45.0[WD:∞] to 45.9[WD:300]	38 dia. 33.5[WD:∞] to 35.6[WD:300]	38 dia. 35.0[WD:∞] to 39.1[WD:300]	44 dia. 44.5[WD:∞] to 49.5[WD:500]
Focal length	6 mm	8 mm	12 mm	16 mm	25 mm	35 mm	50 mm
Aperture (F No.)	1.8 to 16	1.4 to 16	1.4 to 16	1.4 to 16	1.4 to 16	1.4 to 16	1.8 to 16
Filter size	Can not be used a filter	M55.0 P0.75	M35.5 P0.5	M30.5 P0.5	M30.5 P0.5	M30.5 P0.5	M40.5 P0.5
Maximum sensor size	1 inch	1 inch	1 inch	1 inch	1 inch	1 inch	1 inch
Mount		•		C mount			•

M42-mount Lens for large image sensor (Recommend: FH-S□12)

Model	3Z4S-LE VS-L1828/M42-10	3Z4S-LE VS-L2526/M42-10	3Z4S-LE VS-L3528/M42-10	3Z4S-LE VS-L5028/M42-10	3Z4S-LE VS-L8540/M42-10	3Z4S-LE VS-L10028/M42-10
Appearance/ Dimensions (mm)	58.5 dia. 94	58.5 dia. 80	64.5 dia. 108	66 dia. 94.5	55.5 dia. 129.5	54 dia. 134.5
Focal length	18 mm	25 mm	35 mm	50 mm	85 mm	100 mm
Aperture (F No.)	2.8 to 16	2.6 to 16	2.8 to 16	2.8 to 16	4.0 to 16	2.8 to 16
Filter size	M55.0 P0.75	M55.0 P0.75	M62.0 P0.75	M62.0 P0.75	M52.0 P0.75	M52.0 P0.75
Maximum sensor size			1.8	inch	1	
Mount			M42 ı	mount		

Lenses for small camera

Model	FZ-LES3	FZ-LES6	FZ-LES16	FZ-LES30		
Appearance/ Dimensions (mm)	12 dia. 16.4	12 dia. 19.7	12 dia. 23.1	12 dia. 25.5		
Focal length	3 mm	6 mm	16 mm	30 mm		
Aperture (F No.)	2.0 to 16	2.0 to 16	3.4 to 16	3.4 to 16		

FH-Series

Vibrations and Shocks Resistant C-mount Lens for 2/3-inch image sensor $(Recommend: FZ-S \square / FZ-S \square 2M/FZ-S \square 5M3/FZ-SH \square / FH-S \square / FH-S \square 05R)$

(Vibrations and Shocks Resistant Lenses for 1-inch image sensors and for large image sensors are also available. Ask your OMRON representative for details.)

Model				3Z VS-MC1	Z4S-LE 5-□□□	□□ *1						,	3Z VS-MC20	'4S-LE)-□□□	□□ *1			
Appearance/ Dimensions (mm)				31 dia. 25.	.4[0.03×] to 2	29.5[0.3×]							31 dia. 23	.0[0.04×] to	30.5[0.4×]			
Focal length		15 mm											2	0 mm				
Filter size		M27.0 P0.5								M27.0 P0.5								
Optical magnification	C	.03×			0.2×			0.3×		0.04 × 0.25 × 0.4 ×								
Aperture (fixed F No.) *2	2	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8
Depth of field (mm) *3	183.1	33.1 512.7 732.4 4.8 13.4 19.2 2.3 6.5 9							9.2	110.8	291.2	416.0	3.4	9.0	12.8	1.5	3.9	5.6
Maximum sensor size									2/3	inch	•							
Mount									СМ	C Mount								

Model			\	3Z S-MC25/	'4S-LE N-□□□								3Z VS-MC3	24S-LE 0□□□	□□ *1			
Appearance/ Dimensions (mm)				31 dia. 26	.5[0.05×] to	38.0[0.5×]						3	31 dia. 24.0)[0.06×] to 3	5.7[0.45×]			
Focal length		25 mm										3	0 mm					
Filter size		M27.0 P0.5										M2	7.0 PO.	5				
Optical magnification	C).05 ×		0	.25 ×			0.5×		0.06 × 0.15 × 0.45 ×								
Aperture (fixed F No.) *2	2	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8
Depth of field (mm) *3	67.2	37.2 188.2 268.8 3.2 9.0 12.8 1.0 2.7 3							3.8	47.1	131.9	188.4	8.2	22.9	32.7	1.1	3.2	4.6
Maximum sensor size								2/3 i	nch	•								
Mount									C M	Mount								

Model				3Z VS-MC3	'4S-LE 5-□□□	□□ *1							3Z VS-MC50	24S-LE 0-□□□	□□ *1			
Appearance/ Dimensions (mm)				31 dia. 32.	0[0.26×] to 4	5.7[0.65×]							31 dia. 44,	5[0.08×] to 6	63.9[0.48×]			
Focal length		35 mm											5	0 mm				
Filter size		M27.0 P0.5								M27.0 P0.5								
Optical magnification	0	.26×		(0.3×		0	.65×		0.08 × 0.2 × 0.48 ×								
Aperture (fixed F No.) *2	1.9	5.6	8	1.9	5.6	8	1.9	5.6	8	2	5.6	8	2	5.6	8	2	5.6	8
Depth of field (mm) *3	2.8	2.8 8.4 11.9 2.2 6.5 9.2 0.6 1.7							2.5	33.8	75.6	108.0	6.0	13.4	19.2	1.3	2.9	4.1
Maximum sensor size									2/3 i	2/3 inch						•		
Mount									C M	ount								

Model				3Z VS-MC75	4S-LE 5-□□□	□□ *1							
Appearance/ Dimensions (mm)				31 dia. 70.0[0.14x] to 10	5.5[0.62×]							
Focal length				7	5 mm								
Filter size		M27.0 P0.5											
Optical magnification	0	.14×		().2×		C).62×					
Aperture (fixed F No.) *2	3.8	5.6	8	3.8	5.6	8	3.8	5.6	8				
Depth of field (mm) *3	17.7	17.7 26.1 37.2 9.1 13.4 19.2 1.3 1.9 2.7											
Maximum sensor size	2/3 inch												
Mount		C Mount											

^{*1} Insert the aperture into □□□□□ in the model number as follows. F=1.9 to 3.8: blank F=5.6: FN056 F=8: FN080
*2 F-number can be selected from maximum aperture, 5.6, and 8.0.
*3 When circle of least confusion is 40 μm.

High-resolution Telecentric Lens for C-mount Lens for 2/3-inch image sensor (Recommend: FZ-S□/FZ-SH□/FZ-S□2M/FZ-S□5M3/FH-S□/FH-S□05R)



Model *	1		3Z4S-LE VS-TCH05 -65□□□□	3Z4S-LE VS-TCH05 -110□□□□	3Z4S-LE VS-TCH1 -65□□□□	3Z4S-LE VS-TCH1 -110□□□□	3Z4S-LE VS-TCH1.5 -65□□□□	3Z4S-LE VS-TCH1.5 -110□□□□	3Z4S-LE VS-TCH2 -65□□□□	3Z4S-LE VS-TCH2 -110□□□□	3Z4S-LE VS-TCH4 -65□□□□	3Z4S-LE VS-TCH4 -110□□□□
Optical (±5%)	magnificatio	on	0.5x	•	1.0x	•	1.5x	,	2.0x	•	4.0x	•
	FH-SC/- SM	1/3 inch equivalent	9.6×7.2		4.8×3.6		3.2×2.4		2.4×1.8		1.2×0.9	
Field of	FH-S□05R	1/2.5 inch equivalent	11.4×8.56		5.7×4.28		3.8×2.85		2.85×2.14		1.43×1.07	
view	FZ-SC/-S	1/3 inch equivalent	9.6×7.2		4.8×3.6		3.2×2.4		2.4×1.8		1.2×0.9	
(±5%) (VxH) (mm)	FZ-SC2M 1/1.8 inch equiva		14.0×10.6		7.0×5.3		4.7×3.5		3.5×2.7		1.8×1.3	
,	FZ-SC5M□ /-S5M□	2/3 inch equivalent	16.8×14.2		8.4×7.1		5.6×4.7		4.2×3.6		2.1×1.8	
WD(mm	ı) *2		75.3	110.8	68.8	110.3	65	110.8	65	110.8	65	110.8
Effectiv	e FNO		9.42	9.49	9.94	10.49	11.8	11.97	13.6	13.5	17.91	22.2
Depth o	f field (mm)	*3	3	3.04	0.8	0.84	0.4	0.43	0.3	0.27	0.09	0.11
Resolut	esolution *4		12.43	12.9	6.71	6.99	5.24	5.33	4.53	4.53	3	3.73
TV disto	ortion		0.02%	0.02%	0.01%	0.02%	0.01%	0.02%	0.03%	0.03%	0.02%	0.03%
Maximu	m sensor si	ze	2/3 inch		2/3 inch		2/3 inch		2/3 inch		2/3 inch	

^{*1} Insert the shape into □□□□ in the model number as follows.

Straight: -O Coaxial: CO-O

2. The above specifications are values calculated from the optical design and can vary depending on installation conditions.

Extension Tubes

Lenses	For M42 mount Lenses *	For C mount Lenses *	For Small Digital CCD Cameras		
Model	3Z4S-LE VS-EXR/M42	3Z4S-LE SV-EXR	FZ-LESR		
Contents	Set of 5 tubes (20 mm, 10 mm, 8 mm, 2 mm, and 1 mm) Maximum outer diameter: 47.5 mm dia.	Set of 7 tubes (40 mm, 20 mm, 10 mm, 5 mm, 2.0 mm, 1.0 mm, and 0.5 mm) Maximum outer diameter: 30 mm dia.	Set of 3 tubes (15 mm,10 mm, 5 mm) Maximum outer diameter: 12 mm dia.		

Do not use the 0.5-mm, 1.0-mm, and 2.0-mm Extension Tubes attached to each other. Since these Extension Tubes are placed over the threaded section of the Lens or other Extension Tube, the connection may loosen when more than one 0.5-mm, 1.0-mm or 2.0-mm Extension Tube are used together. Reinforcement is required to protect against vibration when Extension Tubes exceeding 30 mm are used. When using the Extension Tube, check it on the actual device before using it.

^{*2} The working distance is the distance from the end of the lens to the workpiece.

^{*3} The depth of field is calculated using a permissible circle of confusion diameter of 0.04 mm.

^{*4} The resolution is calculated using a wavelength of 550 nm.

Note: 1. Fixing the lens or other reinforcement may be required depending on the installation angle or operating environment (vibration/shock). When fixing the lens, insulate the lens from the fixture.

FH-Series

Ratings and Specifications (FH Sensor Controllers)

High-speed Controllers/Standard Controllers

	ensor Controller Series		FH-3000 series									
Sensor Controller Model												
ontroller Type			BOX type			*		*				
arallel IO	1	10	NPN/PNP (common)									
	Operation	Standard Double Speed Multi-input	Yes Yes									
	Mode	Non-stop adjustment mode	Yes									
		Multi-line random-trigger mode	Yes (Maximum 8 lines	:)								
	Parallel Proce	essing	Yes	,								
	Number of Co	onnectable Camera	2	4	8	2	4	8				
	Supported FH-S series camera		All of the FH-S series	cameras	All of the FH-S series cameras	All of the FH-S serie	s cameras	All of the FH-S series cameras				
	Supported Camera	rn-o selles calliela	are connectable.		are connectable. *1	are connectable.		are connectable				
ain		FZ-S series camera	All of the FZ-S series	cameras are connectable	э.	-						
unctions	Camera I/F		OMRON I/F									
	Possible Number of Captured Images Possible Number of Logging Images to		Defeate ness 26									
	Possible Num Sensor Contr		Refer to page 36.									
		ber of Scenes	128									
	Operating	USB Mouse	Yes (wired USB and driver is unnecessary type)									
	on UI	Touch Panel	Yes (RS-232C/USB connection: FH-MT12)									
	Setup		Create the processing flow using Flow editing.									
	Language		Japanese, English, Simplified Chinese, Traditional Chinese, Korean, German, French, Spanish, Italian									
	Serial Comm	A CONTRACTOR OF THE PARTY OF TH	RS-232C × 1	IDD)								
	Ethernet Communication	Protocol I/F	Non-procedure (TCP/UDP)									
		ommunication	Ethernet port (transmi			TOUDAGE-I X I	TOUUDAGE-T X Z					
	EtherCAT Co		Yes (slave)									
			12 inputs/31 outputs	:								
			Use 1 Line. Operation mode: I	Except Multi-line random	-trigger mode							
			17 inputs/37 outputs		ingger mode.							
			• Use 2 Lines.									
kternal	Parallel I/O		Operation mode: Multi-line random-trigger mode.									
terface			14 inputs/29 outputs: Use 3 to 4 Lines.									
				Operation mode: Multi-line random-trigger mode.								
			 19 inputs/34 outputs Use 5 to 8 Lines. 	:								
-				Multi-line random-trigger	mode.							
			Input voltage: 5 V ± 5%									
	Encoder Inter	face	Signal: RS-422A LineDriver Level Phase A/B/Z: 1 MHz									
	Monitor Interface			RGB & DVI-D single link)	× 1							
	USB I/F											
	SD Card I/F		USB2.0 host × 4 (BUS Power: Port5 V/0.5 A) SDHC × 1									
			POWER: Green									
	Main		ERROR: Red RUN: Green									
			ACCESS: Yellow									
			NET RUN: Green	NET RUN1: Green		NET RUN: Green	NET RUN1: Green	'allaw				
	Ethernet		NET LINK NET LINK ACKT: YEIOW NET LINK NET LINK NET LINK ACKT: YEIOW									
dicator			ACT: YelloW NET LINK ACK2: Yellow NET LINK ACK2: Yellow									
			SD POWER: Green SD BUSY: Yellow									
	SD Card			_								
	SD Card			Green	EtherCAT LINK/ACT IN LED: Green EtherCAT LINK/ACT OUT LED: Green							
ndicator .amps			EtherCAT RUN LED: 0 EtherCAT LINK/ACT I	N LED: Green								
	SD Card EtherCAT		EtherCAT RUN LED: (EtherCAT LINK/ACT I EtherCAT LINK/ACT (N LED: Green DUT LED: Green								
amps	EtherCAT		EtherCAT RUN LED: 0 EtherCAT LINK/ACT 0 EtherCAT LINK/ACT 0 EtherCAT ERR LED: 1	N LED: Green DUT LED: Green Red								
amps	EtherCAT oltage	Connected to 2 cameras	EtherCAT RUN LED: (EtherCAT LINK/ACT I EtherCAT LINK/ACT (N LED: Green DUT LED: Green Red	6.4 A max.	4.7 A max.	5.0 A max.	5.9 A max.				
amps	EtherCAT oltage When connected to	Connected to 4 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT CETHERCAT ERR LED: I 20.4 VDC to 26.4 VDC	N LED: Green DUT LED: Green Red	8.1 A max.	4.7 A max.	5.0 A max. 6.5 A max.	7.5 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller	Connected to 4 cameras Connected to 8 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: 1 20.4 VDC to 26.4 VDC 5.0 A max.	N LED: Green DUT LED: Green Red 5 5.4 A max. 7.0 A max.	8.1 A max. 11.5 A max.		6.5 A max.	7.5 A max. 10.9 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras	EtherCAT RUN LED: teherCAT LINK/ACT I EtherCAT LINK/ACT CHercAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max.	8.1 A max. 11.5 A max. 5.2 A max.		6.5 A max. 3.7 A max.	7.5 A max. 10.9 A max. 4.5 A max.				
ower-supply vo	EtherCAT Oltage When connected to a Controller When not connected	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras	EtherCAT RUN LED: teherCAT LINK/ACT I EtherCAT LINK/ACT CHORCAT ERR LED: 1 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max.	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max.	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo urrent unsumption	EtherCAT oltage When connected to a Controller When not	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT CHENCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max 4.1 A max	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max.	8.1 A max. 11.5 A max. 5.2 A max.		6.5 A max. 3.7 A max.	7.5 A max. 10.9 A max. 4.5 A max.				
ower-supply vo urrent onsumption	EtherCAT Oltage When connected to a Controller When not connected to Controller	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras	EtherCAT RUN LED: t EtherCAT LINK/ACT I EtherCAT LINK/ACT (EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max 4.2 A max. 4.8 A max.	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vi urrent onsumption	EtherCAT Oltage When connected to a Controller When not connected to Controller	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras	EtherCAT RUN LED: t EtherCAT LINK/ACT i EtherCAT LINK/ACT of EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max 4.1 A max Yes Operating: 0°C to 50°C Storage: -20 to +65°C	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. C (with no icing or conden	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vi urrent onsumption	EtherCAT Oltage When connected to a Controller When not connected to Controller	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras	EtherCAT RUN LED: tetherCAT LINK/ACT I EtherCAT LINK/ACT (EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max 4.2 A max. 4.8 A max. C (with no icing or conden	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vi urrent onsumption	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range	EtherCAT RUN LED: teherCAT LINK/ACT I EtherCAT LINK/ACT CHENErCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%RH-Storage: 35 to 85%RH-	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. C (with no icing or conden	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo urrent onsumption	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient tem	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max 4.1 A max Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R- No corrosive gases	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. C (with no icing or condensation)	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo urrent onsumption	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max 4.1 A max Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden H (with no condensation)	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo urrent onsumption	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: t EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%RI- No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s²	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden iH (with no condensation)	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vi urrent onsumption uilt-in FAN	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atmentation	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. C (with no icing or conden H (with no condensation) 10 to 150 Hz n	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vi urrent onsumption	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atmentation	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: t EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: 1 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Operating: 35 to 85%RP No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute/ Sweep count: 10 Vibration direction: up	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or condentH (with no condensation) 10 to 150 Hz n (count and down/front and beh	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atmo	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max 4.1 A max Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Swept time: 8 minute. Sweep count: 10 Vibration direction: up/	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden H (with no condensation) 10 to 150 Hz n //count and down/front and beh	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atmentation	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: t EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT ERR LED: 1 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%RF No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute/ Sweep count: 10 Vibration direction: up Impact force: 150 m/s² Test direction: up and behind/left and right	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden H (with no condensation) 10 to 150 Hz n //count and down/front and beh	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atmo	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute/ Sweep count: 10 Vibration direction: up Impact force: 150 m/s² Test direction: up and behind/left and right • DC power	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. 4.8 I max. 4.9 I max. 4.9 I max. 4.9 I max. 4.0 I max.	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max.	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atmo	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere	EtherCAT RUN LED: tetherCAT LINK/ACT is EtherCAT LINK/ACT is EtherCAT LINK/ACT is EtherCAT ERR LED: 1 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%RI-No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute. Sweep count: 10 Vibration direction: up Impact force: 150 m/s² Test direction: up and behind/left and right • DC power Direct infusion: 2kV,	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden H (with no condensation) 10 to 150 Hz n //count and down/front and beh	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. sation)	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temporal Ambient atmospherical Controller Shock resista	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 9 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R+ No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minutes Sweep count: 10 Vibration direction: up and behind/left and right • DC power Direct infusion: 2kV, Burst continuation tir I/O line	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden H (with no condensation) 10 to 150 Hz n //count and down/front and beh and down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. sation)	3.6 A max.	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vo	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atme Vibration tole Shock resista	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 9 cameras	EtherCAT RUN LED: tetherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: 1 20.4 VDC to 26.4 VDC 5.0 A max.	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or condentith (with no condensation) 10 to 150 Hz and down/front and beh down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. sation) ind/left and right width: 50ns, d: 300ms, Application tin width: 50ns,	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
wer-supply von	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atme Vibration tole Shock resista	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 9 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to -65°C Operating: 35 to 85%R Storage: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute/ Sweep time: 10 minute/ Sweep time: 1	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. 4.8 h max. 10 to 150 Hz and down/front and beh down/front and Dulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. sation) ind/left and right width: 50ns, d: 300ms, Application tir width: 50ns, d: 300ms, Application tir	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
wer-supply von	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atme Vibration tole Shock resists Noise immunity Grounding	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 9 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max.	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or condentith (with no condensation) 10 to 150 Hz and down/front and beh down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. 6.8 A max. width: 50ns, 300ms, Application tin width: 50ns, 300ms, Application tin sistance) "2	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
ower-supply vi	EtherCAT oltage When connected to a Controller When not connected to Controller Ambient temp Ambient atme Vibration tole Shock resists Noise immunity Grounding Dimensions	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 9 cameras	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. 9 Operating: 0°C to 50°C Storage: -20 to -65°C Operating: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Swept time: 8 minute, Sweep count: 10 Vibration direction: up Impact force: 150 m/s² Test direction: up and behind/left and right DC power Direct infusion: 2kV, Burst continuation tir I/O line Direct infusion: 1kV, Burst continuation tir I/O line Direct infusion: 1kV, Burst continuation tir Type D grounding (10 190 mm × 115 mm × 1 Note Height: Including	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. 4.8 A max. 10 to 150 Hz and down/front and beh down/front and Dustrians 15 ms, Pulse me: 15 ms/0.75 ms, Perio Pulse rising: 5 ns, Pulse me: 15 ms/0.75 ms, Perio 0 Ω or less grounding re: 182.5 mm the rubber feet at the bat	8.1 A max. 11.5 A max. 11.5 A max. 5.6 A max. 5.6 A max. 6.8 A max. sation) width: 50ns, d: 300ms, Application tin width: 50ns, d: 300ms, Application tin sistance) *2 ase.	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max. 6.2 A max.				
wer-supply vo	EtherCAT Oltage When connected to a Controller When not connected to Controller Ambient tem Ambient atm Vibration tole Shock resists Noise immunity Grounding Dimensions Weight	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere Fast Transient Burst	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute. Sweep count: 10 Vibration direction: up and behind/left and right DC power Direct infusion: 2kV, Burst continuation tir J/O line Direct infusion: 1kV, Burst continuation tir Type D grounding (10 190 mm × 115 mm × 1 Note Height: Including Approx. 3.2 kg	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or condentith (with no condensation) 10 to 150 Hz and down/front and beh down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \text{ resing: 5ns, Pulse} \) Pulse rising: 5ns, Pulse	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. 6.8 A max. width: 50ns, 300ms, Application tin width: 50ns, 300ms, Application tin sistance) "2	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max.				
wer-supply vo	EtherCAT Oltage When connected to a Controller When not connected to Controller Ambient temporal Ambient atmospherical Controller Ambient temporal Ambient atmospherical Controller Ambient atmospherical Controller Shock resists Noise immunity Grounding Dimensions Weight Degree of pro	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere Fast Transient Burst	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC to 5.0 A max	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or conden H (with no condensation) 10 to 150 Hz m (count and down/front and beh 2 down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 \(\Omega \) or less grounding re 182.5 mm the rubber feet at the ba Approx. 3.4 kg	8.1 A max. 11.5 A max. 11.5 A max. 5.6 A max. 5.6 A max. 6.8 A max. sation) width: 50ns, d: 300ms, Application tin width: 50ns, d: 300ms, Application tin sistance) *2 ase.	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max. 6.2 A max.				
wer-supply vo	EtherCAT Oltage When connected to a Controller When not connected to Controller Ambient tem Ambient atm Vibration tole Shock resists Noise immunity Grounding Dimensions Weight	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere Fast Transient Burst	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC 5.0 A max. 4.1 A max. Yes Operating: 0°C to 50°C Storage: -20 to +65°C Operating: 35 to 85%R No corrosive gases Oscillation frequency: Half amplitude: 0.1 mr Acceleration: 15 m/s² Sweep time: 8 minute. Sweep count: 10 Vibration direction: up and behind/left and right DC power Direct infusion: 2kV, Burst continuation tir J/O line Direct infusion: 1kV, Burst continuation tir Type D grounding (10 190 mm × 115 mm × 1 Note Height: Including Approx. 3.2 kg	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or condentith (with no condensation) 10 to 150 Hz and down/front and beh down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 Ω or less grounding rei B2.5 mm the rubber feet at the back poprox. 3.4 kg	8.1 A max. 11.5 A max. 11.5 A max. 5.6 A max. 5.6 A max. 6.8 A max. sation) width: 50ns, d: 300ms, Application tin width: 50ns, d: 300ms, Application tin sistance) *2 ase.	3.6 A max	6.5 A max. 3.7 A max. 4.3 A max.	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max. 6.2 A max.				
wer-supply von	EtherCAT Oltage When connected to a Controller When not connected to Controller Ambient temporal Ambient atmospherical Controller Ambient temporal Ambient atmospherical Controller Ambient atmospherical Controller Shock resists Noise immunity Grounding Dimensions Weight Degree of pro	Connected to 4 cameras Connected to 8 cameras Connected to 2 cameras Connected to 4 cameras Connected to 8 cameras Connected to 8 cameras Connected to 8 cameras Derature range idity range Desphere Fast Transient Burst	EtherCAT RUN LED: EtherCAT LINK/ACT I EtherCAT LINK/ACT C EtherCAT LINK/ACT C EtherCAT ERR LED: I 20.4 VDC to 26.4 VDC to 5.0 A max.	N LED: Green DUT LED: Green Red 5.4 A max. 7.0 A max. 4.2 A max. 4.8 A max. (with no icing or condentith (with no condensation) 10 to 150 Hz and down/front and beh down/front and Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio Pulse rising: 5ns, Pulse me: 15ms/0.75ms, Perio 0 Ω or less grounding rei B2.5 mm the rubber feet at the back poprox. 3.4 kg	8.1 A max. 11.5 A max. 5.2 A max. 5.6 A max. 6.8 A max. 6.8 A max. sation) ind/left and right width: 50ns, d: 300ms, Application tin width: 50ns, d: 300ms, Application tin sistance) *2 ase. Approx. 3.4 kg	me: 1 min Approx. 3.2 kg	6.5 A max 3.7 A max. 4.3 A max Approx. 3.4 kg	7.5 A max. 10.9 A max. 4.5 A max. 5.0 A max. 6.2 A max.				

^{*1} When the 12 megapixels camera: Max. 4 cameras are connectable. When use except 12 megapixels cameras: Max. 8 cameras are connectable. *2 Existing third class grounding

Lite Controllers

Consor Controll	ler Series		FH-L	series					
Туре			Lite Controller						
	Sensor Controller Model		FH-L550	FH-L550-10					
Controller Type	1		BOX type						
Parallel IO			NPN/PNP (common)						
		Standard	Yes						
	Double Speed Multi-input		Yes						
	Operation Mode	Non-stop adjustment	Yes						
	wode	mode							
		Multi-line random-trigger mode	No						
	Parallel Proce		Yes						
		nnectable Camera	2 4						
Main Func-	Supported	FH-S series camera	All of the FH-S series cameras are connectable						
	Camera	FZ-S series camera	All of the FZ-S series cameras are connectable.						
	Camera I/F		OMRON I/F						
	Possible Num	ber of Captured Images							
	Possible Number of Logging Images to		Refer to page 36.						
	Sensor Contro	oller							
	Possible Num	ber of Scenes	128						
	UI Opera-	USB Mouse	Yes (wired USB driver-less type)						
	tions	Touch Panel	Yes (RS-232C/USB connection: FH-MT12)						
	Setup		Create the processing flow using Flow editing.						
	Language		Japanese, English, Simplified Chinese, Traditional Chinese, Korean, Ge	rman, French, Spanish, Italian					
	Serial Commu		RS-232C × 1						
	Ethernet	Protocol	Non-procedure (TCP/UDP)						
	Communica- tion	I/F	1000BASE-T × 1						
		ommunication	Ethernet port (transmission rate: 1 Gbps)						
	EtherCAT Cor		No						
			High-speed input: 1						
External Interface P	Parallel I/O		Normal speed: 9						
	Parallel I/O		High-speed output: 4						
	Enceder Inter		Normal speed: 23 None						
	Encoder Inter								
	Worldor Interi	ice	DVI-I output (Analog RGB & DVI-D single link) × 1						
	USB I/F		USB2.0 host × 1: BUS Power: Port 5 V/0.5 A USB3.0 × 1: BUS Power: Port 5 V/0.5 A						
	SD Card I/F		SDHC ×1						
			POWER: Green						
	Main		ERROR: Red RUN: Green						
			ACCESS: Yellow						
Indicator			NET RUN: Green						
Lamps	Ethernet		NET LINK ACT: Yellow						
	SD Card		SD POWER: Green						
			SD BUSY: Yellow						
	EtherCAT		None						
Power-supply v	1		20.4 VDC to 26.4 VDC	I					
	When con-	Connected to 2 cameras	3.5 A max.	3.7 A max.					
	nected to a Controller	Connected to 4 cameras		5.9 A max.					
Current		Connected to 8 cameras		4.7.4					
consumption	When not	Connected to 2 cameras	1.5 A max.	1.7 A max.					
	to Controller	Connected to 4 cameras Connected to 8 cameras		2.0 A max.					
Built-in FAN		Connected to a cameras	No						
Dunt-in FAIN			Operating: 0°C to 55°C						
	Ambient temp	erature range	Operating: 0°C to 55°C Storage: -25 to +70°C						
	Ambient hum	dity range	Operating and Storage: 10 to 90%RH (with no condensation)						
	Ambient atmo		No corrosive gases						
	·		5 to 8.4 Hz with 3.5 mm amplitude, 8.4 to 150 Hz, acceleration of 9.8 m/s ²						
	Vibration 4. 1	ance	100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total)						
	Vibration tole	4	100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100) min total)					
Usage Envi-	Vibration tole		Impact force: 150 m/s ²) min total)					
Usage Envi- ronment			Impact force: 150 m/s ² Test direction: up and down/front and behind/left and right	min total)					
			Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power	min total)					
	Shock resista	nce	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim						
	Shock resista		Impact force: 150 m/s² Test direction: up and down/front and behind/left and right DC power Direct influsion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim I/O line						
	Shock resista	nce	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim • I/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns,	e: 1 min					
	Shock resista Noise immunity	nce	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim • I/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim	e: 1 min					
	Shock resista	nce	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim • I/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns,	e: 1 min					
ronment	Shock resista Noise immunity Grounding Dimensions	nce	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right $^{\circ}$ DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 16ms/0.75ms, Period: 300ms, Application time Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim Type D grounding (100 Ω or less grounding resistance) * 200 mm \times 80 mm \times 130 mm	e: 1 min					
ronment External	Shock resista Noise immunity Grounding Dimensions Weight	Fast Transient Burst	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim • I/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim Type D grounding (100 Ω or less grounding resistance) * 200 mm × 80 mm × 130 mm Approx. 1.5 kg	e: 1 min					
	Shock resista Noise immunity Grounding Dimensions	Fast Transient Burst	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right $^{\circ}$ DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 16ms/0.75ms, Period: 300ms, Application time Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim Type D grounding (100 Ω or less grounding resistance) * 200 mm \times 80 mm \times 130 mm	e: 1 min					
External Features	Noise immunity Grounding Dimensions Weight Degree of pro	Fast Transient Burst	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right • DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim • I/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application tim Type D grounding (100 Ω or less grounding resistance) * 200 mm × 80 mm × 130 mm Approx. 1.5 kg IEC60529 IP20 PC Instruction Sheet (Japanese and English): 1, Instruction Installation Mar	e: 1 min e: 1 min Approx. 1.5 kg					
ronment External	Noise immunity Grounding Dimensions Weight Degree of pro	Fast Transient Burst	Impact force: 150 m/s² Test direction: up and down/front and behind/left and right \bullet DC power Direct infusion: 2kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time: 1/O line Direct infusion: 1kV, Pulse rising: 5ns, Pulse width: 50ns, Burst continuation time: 15ms/0.75ms, Period: 300ms, Application time Type D grounding (100 Ω or less grounding resistance) * 200 mm \times 80 mm \times 130 mm Approx. 1.5 kg IEC60529 IP20 PC	e: 1 min e: 1 min Approx. 1.5 kg					

^{*} Existing third class grounding

Number of logged images/Max. Number of Loading Images during Multi-input

Cameras Color/ Monoch	Color/		Number of logged images *1								Max. Number of
	Monochrome	Model	Connected to 1 camera	Connected to 2 camera	Connected to 3 camera	Connected to 4 camera	Connected to 5 camera	Connected to 6 camera	Connected to 7 camera	Connected to 8 camera	Loading Images during Multi-input *2
Intelligent Compact Digital CMOS Cameras *3	Color	FZ-SQ010F/-SQ050F/ -SQ100F/-SQ100N	232	116	77	58	46	38	33	29	
300,000 pixels	Monochrome	FZ-S/-SF/-SH/-SP	272	136	90	68	54	45	38	34	256
CCD Cameras	Color	FZ-SC/-SFC/-SHC/ -SPC	270	135	90	67	54	45	38	33	
300,000 pixels CMOS	Monochrome	FH-SM	272	136	90	68	54	45	38	34	256
Cameras	Color	FH-SC	270	135	90	67	54	45	38	33	250
2 million pixels CMOS Cameras	Color/ Monochrome	FH-SC02/-SM02	37	18	12	9	7	6	5	4	51
2 million pixels CCD Cameras	Color/ Monochrome	FZ-SC2M/-S2M	43	21	14	10	8	7	6	5	64
4 million pixels CMOS Cameras	Color/ Monochrome	FH-SC04/-SM04	20	10	6	5	4	3	2	2	32
5 million pixels CCD Cameras	Color/ Monochrome	FZ-SC5M3/-S5M3	16	8	5	4	3	2	2	2	25
5 million pixels Digital CMOS Cameras	Color/ Monochrome	FH-SC05R/-SM05R	16	8	5	4	3	2	2	2	25
12 million pixels CMOS Cameras	Color/Mono- chrome	FH-SC12/-SM12	6	3	2	2					10

^{*1} Number of logging images is the maximum number of logging images that can be saved in the memory of the Sensor Controller itself and it depends on the settings of the system and the scene.

Refer to Vision System FH/FZ5 Series User's Manual (Z340).

*2 When using two camera cables for connection, the maximum number of loaded images during multi-input is twice the number given in the table.

*3 The multi-input function cannot be used when the built-in lighting of an intelligent compact Digital camera is used.

Refer to the Vision System FH/FZ5 Series User's Manual (Cat. No. Z340) for details.

Ratings and Specifications (Cameras)

High-speed Digital CMOS cameras

Model	FH-SM	FH-SC	FH-SM02	FH-SC02	FH-SM04	FH-SC04	FH-SM12	FH-SC12	
Image elements	CMOS image elements (1/3-inch equivalent)		CMOS image elements (2/3-inch equivalent)		CMOS image elements (1-inch equivalent)		CMOS image elements (1.76-inch equivalent)		
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color	Monochrome	Color	
Effective pixels	640 (H) × 480 (V)		2040 (H) × 1088 (V)		2040 (H) × 2048	3 (V)	4084 (H) × 3072 (V)		
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0 mm)		11.26 × 5.98 (12.76 mm)		11.26 × 11.26 (15.93 mm)		22.5 × 16.9 (28.14 mm)		
Pixel size	$7.4~(\mu m) \times 7.4~(\mu$	ım)	$5.5 (\mu m) \times 5.5 ($	μm)	$5.5 \ (\mu m) \times 5.5 \ (\mu m)$	μm)	$5.5 (\mu m) \times 5.5 ($	μm)	
Shutter function	Electronic shutte Shutter speeds ca μs to 100 ms.	,	Electronic shutte Shutter speeds	er; can be set from 2	Electronic shutter; Shutter speeds can be set from 60 µs to 100 ms.				
Partial function	1 to 480 lines	2 to 480 lines	1 to 1088 lines	2 to 1088 lines	1 to 2048 lines 2 to 2048 lines		4 to 3072 lines (4-line increments)		
Frame rate (Image Acquisition Time)	308 fps (3.3 ms)		219 fps (4.6 ms) *	38.9 fps (25.7 ms) *				
Lens mounting	C mount						M42 mount		
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance								
Ambient temperature range	Operating: 0 to 40 °C, Storage: -25 to 65 °C (with no icing or condensation)								
Ambient humidity range	Operating and s	torage: 35% to 8	5% (with no cond	ensation)					
Weight	Approx.105 g		Approx.110 g				Approx.320 g		
Accessories	Instruction manu	ıal	•				•		

^{*} Frame rate in high speed mode when the camera is connected using two camera cables.

Digital CMOS Cameras

Model	FH-SM05R	FH-SC05R						
Image Elements	CMOS image elements (1/2.5-inch equivalent)							
Color/Monochrome	Monochrome Color							
Effective Pixels	2592 (H) × 1944 (V)							
Imaging area H × V (opposing corner)	5.70 × 4.28 (7.13 mm)							
Pixel Size	2.2 (μm) × 2.2 (μm)							
Scan Type	Progressive							
Shutter Method	Rolling shutter							
Shutter Function	Electronic shutter; Shutter speeds can be set from 500 to 10000 ms in multiples of 50 μs							
Frame Rate (Image Acquisition Time)	14 fps (71.7 ms)							
Lens Mounting	C mount							
Field of vision, Installation distance	Selecting a lens according to the field of vision and installation distance							
Ambient temperature range	Operating: 0 to +40°C Storage: -30 to 65°C (with no icing or condensation)							
Ambient humidity range	Operating: 35 to 85%RH Storage: 35 to 85%RH (with no condensation)							
Weight	Approx. 52 g							
Accessories	Instruction Sheet							

Digital CCD/CMOS Cameras

Model	FZ-S	FZ-SC	FZ-S2M	FZ-SC2M	FZ-S5M3	FZ-SC5M3	
Image elements	Interline transfer read CCD image elements		Interline transfer read CCD image elements	ing all pixels, (1/1.8-inch equivalent)	CMOS image elemen	ts (2/3-inch equivalent)	
Color/Monochrome	Monochrome	Color	Monochrome	Color	Monochrome	Color	
Effective pixels	640 (H) × 480 (V)	*	1600 (H) × 1200 (V)	*	2448 (H) × 2048 (V)	•	
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0mm)		7.1 × 5.4 (8.9mm)		8.4 × 7.1 (11mm)	8.4 × 7.1 (11mm)	
Pixel size	$7.4 (\mu m) \times 7.4 (\mu m)$		4.4 (μ m) \times 4.4 (μ m)		$3.45 \; (\mu m) \times 3.45 \; (\mu m)$)	
Shutter function	Electronic shutter; sel	Electronic shutter; select shutter speeds from 20 μs to 100 ms					
Partial function	12 to 480 lines		12 to 1200 lines		4 to 2048 lines		
Frame rate (Image Acquisition Time)	80 fps (12.5 ms)		30 fps (33.3 ms)		25.6 fps (38.2 ms)		
Lens mounting	C mount						
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance						
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C (with no icing or condensation)		Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or cond	ensation)			
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)						
Weight	Approx. 55 g		Approx. 76 g		Approx. 85 g		
Accessories	Instruction manual						

Small CCD Digital Cameras

Model	FZ-SF	FZ-SFC	FZ-SP	FZ-SPC
Image elements	Interline transfer reading all pixels, CCD image elements (1/3-inch equivalent)			
Color/Monochrome	Monochrome	Color	Monochrome	Color
Effective pixels	640 (H) × 480 (V)			
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0mm)	4.8 × 3.6 (6.0mm)		
Pixel size	$7.4 (\mu m) \times 7.4 (\mu m)$			
Shutter function	Electronic shutter; select shutter s	Electronic shutter; select shutter speeds from 20 μm to 100 ms		
Partial function	12 to 480 lines	12 to 480 lines		
Frame rate (Image Acquisition Time)	80 fps (12.5ms)			
Lens mounting	Special mount (M10.5 P0.5)			
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance			
Ambient temperature range	Operating: 0 to 50 °C (camera amp) 0 to 45 °C (camera head) Storage: -25 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)			
Weight	Approx. 150 g			
Accessories	Instruction manual, installation bracket, Four mounting brackets (M2) Instruction manual			

High-speed Digital CCD Cameras

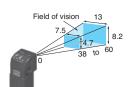
Model	FZ-SH	FZ-SHC	
Image elements	Interline transfer reading all pixels, CCD image elements (1/3-inch equivalent)		
Color/Monochrome	Monochrome	Color	
Effective pixels	640 (H) × 480 (V)		
Imaging area H x V (opposing corner)	4.8 × 3.6 (6.0mm)		
Pixel size	7.4 (µm) × 7.4 (µm)		
Shutter function	Electronic shutter; select shutter speeds from 1/10 to 1/50,000 s		
Partial function	12 to 480 lines		
Frame rate (Image Acquisition Time)	204 fps (4.9ms)		
Field of vision, installation distance	Selecting a lens according to the field of vision and installation distance		
Ambient temperature range	Operating: 0 to 40 °C Storage: -25 to 65 °C (with no icing or condensation)		
Ambient humidity range	e Operating and storage: 35% to 85% (with no condensation)		
Weight	Approx. 105 g		
Accessories	Instruction manual		

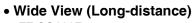
Intelligent Compact Digital CMOS Cameras

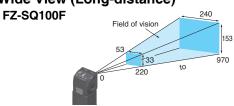
Model	FZ-SQ010F	FZ-SQ050F	FZ-SQ100F	FZ-SQ100N	
Image elements	CMOS color image elements (1/3-inch equivalent)				
Color/Monochrome	Color				
Effective pixels	752 (H) × 480 (V)				
Imaging area H x V (opposing corner)	4.51 × 2.88 (5.35mm)	4.51 × 2.88 (5.35mm)			
Pixel size	6.0 (μ m) \times 6.0 (μ m)				
Shutter function	1/250 to 1/32,258				
Partial function	8 to 480 lines				
Frame rate (Image Acquisition Time)	60 fps (16.7 ms)				
Field of vision	7.5 × 4.7 to 13 × 8.2 mm	13 × 8.2 to 53 × 33 mm	53 × 33 to 240 × 153 mm	29 × 18 to 300 × 191 mm	
Installation distance	38 to 60 mm	56 to 215 mm	220 to 970 mm	32 to 380 mm	
LED class *	Risk Group2	Risk Group2			
Ambient temperature range	Operating: 0 to 50 °C Storage: -25 to 65 °C				
Ambient humidity range	Operating and storage: 35% to 85% (with no condensation)				
Weight	Approx. 150 g Approx. 140 g				
Accessories	Mounting bracket (FQ-XL), polarizing filter attachment (FQ-XF1), instruction manual and warning label				

^{*} Applicable standards: IEC62471-2

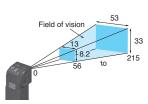
Narrow View FZ-SQ010F

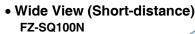


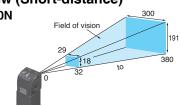




• Standard FZ-SQ050F







Ratings and Specifications (Cable, Monitor)

Camera Cables

Model	FZ-VS3 (2 m)	FZ-VSB3 (2 m)	FZ-VSL3 (2 m)	FZ-VSLB3 (2 m)
Туре	Standard	Bend resistant	Right-angle	Bend resistant Right-angle
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times			
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)			
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)			
Ambient atmosphere	No corrosive gases			
Material	Cable sheath, connector: PVC			
Minimum bending radius	69mm	69mm	69mm	69mm
Weight	Approx. 170 g	Approx. 180 g	Approx. 170 g	Approx. 180 g

Cable Extension Unit

Model	FZ-VSJ
Power supply voltage *1	11.5 to 13.5 VDC
Current consumption *2	1.5 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 240 g
Accessories	Instruction Sheet and 4 mounting screws

^{*1} A 12-VDC power supply must be provided to the Cable Extension Unit when connecting the Intelligent Compact Camera, or the Lighting Controller.

Long-distance Camera Cables

Model	FZ-VS4 (15 m)	FZ-VSL4 (15 m)
Туре	Standard	Right-angle
Shock resistiveness (durability)	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times	
Ambient temperature range	Operation and storage: 0 to 65 °C (with no icing or condensation)	
Ambient humidity range	Operation and storage: 40 to 70%RH (with no condensation)	
Ambient atmosphere	No corrosive gases	
Material	Cable sheath, connector: PVC	
Minimum bending radius	lius 78 mm	
Weight	Approx. 1400 g	

Encoder Cable

Model	FH-VR
Vibration resistiveness	10 to 150 Hz single amplitude 0.1 mm 3 directions, 8 strokes, 10 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -10 to 60 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable Jacket: Heat, oil and flame resistant PVC Connector: polycarbonate resin
Minimum bending radius	65 mm
Weight	Approx. 104 g

Touch Panel Monitor

Model		FH-MT12
	Display area	12.1 inch
	Resolution	1024 (V) × 768 (H)
	Number of color	16,700,000 colors (8 bit/color)
	Brightness	500cd/m ² (Typ)
Major Function	Contrast Ratio	600:1 (Typ)
	Viewing angle	Left and right: each 80°, upward: 80°, downward: 60°
	Backlight Unit	LED, edge-light
	Backlight lifetime	About 100,000hour
	Touch panel	4wire resistive touch screen
	Video input	analog RGB
External interface	Touch panel signal	USB
	Touch paner signal	RS-232C
	Power supply voltage	24 VDC (21.6 to 26.4 VDC)
Ratings	Current consumption	0.5A
	Insulation resistance	Between DC power supply and Touch Panel Monitor FG: 20 M Ω or higher (rated voltage 250 V)
	Ambient temperature range	Operating: 0 to 50°C, Storage: -20 to +65°C (with no icing or condensation)
	Ambient humidity range	Operating and Storage: 20 to 85 %RH (with no icing or condensation)
Operating	Ambient environment	No corrosive gas
environment	Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm (Max. acceleration 15 m/s²) 10 times for 8 minutes for each three direction
	Degree of protection	Panel mounting: IP65 on the front
Operation		Touch pen
	Mounting	Panel mounting, VESA mounting
Structure	Weight	Approx.2.6 kg
	Material	Front panel: PC/PBT, Front Sheet: PET, Rear case: SUS

Note: FH Series Sensor Controllers version 5.32 or higher is required.

Touch Panel Monitor Cables

Model	FH-VMDA (2 m)	FH-VUAB (2 m)	XW2Z-200PP-1 (2 m)	
Cable type	DVI-Analog Conversion Cable	USB Cable	RS-232C Cable	
Vibration resistance	10 to 150 Hz, one-side amplitude 0.1 mm,	10 to 150 Hz, one-side amplitude 0.1 mm, 10 times for 8 minutes for each three direction		
Ambient Temperature	Operating Condition: 0 to 50°C, Storage Co	Operating Condition: 0 to 50°C, Storage Condition: -10 to 60°C (with no icing or condensation)		
Ambient Humidity	Operating Condition: 35 to 85%RH, Storage Condition: 35 to 85%RH (with no icing or condensation)			
Ambient environment	No corrosive gases			
Material	Cable outer sheath, Connector: PVC Cable outer sheath: PVC, Connector: ABS/Ni Plating			
Minimum bend radius	36 mm	25 mm	59 mm	
Weight	Approx.220 g	Approx.75 g	Approx.162 g	

^{*2} The current consumption shows when connecting the Cable Extension Unit to an external power supply.

LCD Monitor

Model	FZ-M08
Size	8.4 inches
Туре	Liquid crystal color TFT
Resolution	1,024 × 768 dots
Input signal	Analog RGB video input, 1 channel
Power supply voltage	21.6 to 26.4 VDC
Current consumption	Approx. 0.7 A max.
Ambient temperature range	Operating: 0 to 50 °C; Storage: -25 to 65 °C (with no icing or condensation)
Ambient humidity range	Operating and storage: 35 to 85% (with no condensation)
Weight	Approx. 1.2 kg
Accessories	Instruction Sheet and 4 mounting brackets

LCD Monitor Cable

Model	FZ-VM
Vibration resistiveness	10 to 150 Hz single amplitude 0.15 mm 3 directions, 8 strokes, 4 times
Ambient temperature range	Operation: 0 to 50 °C; Storage: -20 to 65 °C (with no icing or condensation)
Ambient humidity range	Operation and storage: 35 to 85%RH (with no condensation)
Ambient atmosphere	No corrosive gases
Material	Cable sheath: heat-resistant PVC Connector: PVC
Minimum bending radius	75 mm
Weight	Approx. 170 g

Note: When you connect a LCD Monitor FZ-M08 to FH sensor controller, please use it in combination with a DVI-I -RGB Conversion Connector FH-VMRGB.

EtherCAT Communications Specifications

Item		Specifications	
Communications standard		IEC61158 Type 12	
Physical layer		100 BASE-TX (IEEE802.3)	
Modulation		Base band	
Baud rate		100 Mbps	
Topology		Depends on the specifications of the EtherCAT master.	
Transmission Media		Twisted-pair cable of category 5 or higher (double-shielded straight cable with aluminum tape and braiding)	
Transmission Distance		Distance between nodes: 100 m or less	
Node address setting		00 to 9	
External connection terminals	\$	RJ45 × 2 (shielded) IN: EtherCAT input data, OUT: EtherCAT output data	
Send/receive PDO data sizes	Input	56 to 280 bytes/line (including input data, status, and unused areas) Up to 8 lines can be set. *	
Selid/receive PDO data sizes	Output	28 bytes/line (including output data and unused areas) Up to 8 lines can be set. *	
Mailbox data size Input Outpu		512 bytes	
		512 bytes	
Mailbox		Emergency messages, SDO requests, and SDO information	
Refreshing methods		I/O-synchronized refreshing (DC)	

^{*} This depends on the upper limit of the master.

Version Information

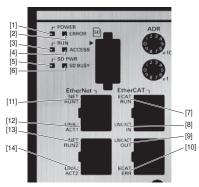
FH Series and Programming Devices

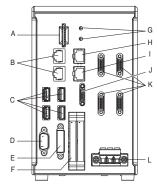
Use the latest version of Sysmac Studio Standard Edition/Vision Edition.

FH Series	Version of FH Series	Corresponding version of Sysmac Studio Standard Edition/Vision Edition
	Version 5.72	Support expected with new version after October 2017.
	Version 5.71	Supported by version 1.18 or higher.
	Version 5.60	Supported by version 1.15 or higher.
FH-3050 (-□)	Version 5.50	Supported by version 1.14.89 or higher.
FH-1050 (-□)	Version 5.30	Supported by version 1.10.80 or higher.
	Version 5.20	Supported by version 1.10 or higher.
	Version 5.10	Supported by version 1.07.43 or higher.
	Version 5.00	Supported by version 1.07 or higher. Not supported by version 1.06 or lower.

Components and Functions

Sensor Controllers High-speed Controllers/ Standard Controllers BOX type (4-camera type)



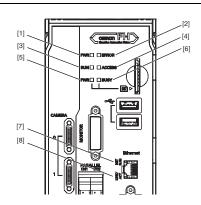


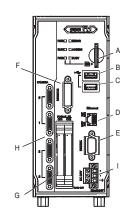
	Name	Description
[1]	POWER LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD POWER LED	Blinks while power is supplied to the SD memory card and the card is usable.
[6]	SD BUSY LED	Blinks while the SD memory card is accessed.
[7]	EtherCAT RUN LED	Lit while EtherCAT communications are usable.
[8]	EtherCAT LINK/ACT IN LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[9]	EtherCAT LINK/ACT OUT LED	Lit when connected with an EtherCAT device, and blinks while performing communications.
[10]	EtherCAT ERR LED	Lit when EtherCAT communications have become abnormal.
[11]	EtherNet NET RUN1 LED	Lit while EtherNet communications are usable.
[12]	EtherNet NET LINK/ACK1 LED	Lit when connected with an EtherNet device, and blinks while performing communications.
[13]	EtherNet NET RUN2 LED	Lit when EtherNet communications are usable.
[14]	EtherNet NET LINK/ACK2 LED	Lit when connected with an EtherNet device, and blinks while performing communications.

	Name	Description			
Α	SD memory card installation connector	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation. Otherwise measurement time may be affected or data may be destroyed.			
		Connect an EtherNet device. Camera 2ch type Camera 4ch/8ch type			
В	EtherNet connector	Ethernet port and EtherNet/IP port are sharing use. EtherNet IP port are sharing use.			
С	USB connector	Connect a USB device. Do not plug or unplug it during measurement operation. Otherwise measurement time may be affected or data may be destroyed.			
D	RS-232C connector	Connect an external device such as a programmable controller.			
Е	DVI-I connector	Connect a monitor.			
F	I/O connector (control lines, data lines)	Connect the controller to external devices such as a sync sensor and PLC.			
G	EtherCAT address setup volume	Used to set a node address (00 to 99) as an EtherCAT communication device.			
Н	EtherCAT communication connector (IN)	Connect the opposed EtherCAT device.			
1	EtherCAT communication connector (OUT)	Connect the opposed EtherCAT device.			
J	Encoder connector	Connect an encoder.			
K	Camera connector	Connect cameras.			
L	Power supply terminal connector	Connect a DC power supply. Wire the controller independently on other devices. Wire * the ground line. Be sure to ground the controller alone.			

* Use the attachment power terminal connector (male) of FH-XCN series.
For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual (Z366).

Lite Controllers BOX type (4-camera type)





	LED name	Description
[1]	PWR LED	Lit while power is ON.
[2]	ERROR LED	Lit when an error has occurred.
[3]	RUN LED	Lit while the layout turned on output setting is displayed.
[4]	ACCESS LED	Blinks while the internal nonvolatile memory is accessed.
[5]	SD PWR LED Lit while power is supplied to the SD memory card and the card is usable.	
[6]	SD BUSY LED	Lit when access to the SD memory card.
[7]	Ethernet NET RUN LED	Lit while Ethernet communications are usable.
[8]	Ethernet NET LINK/ACT LED	Blinks when connected with an Ethernet device, and blinks while performing communications.

	Connector name	Description
۸	SD memory card installation	Install the SD memory card. Do not plug or unplug the SD memory card during measurement operation
^	connector	Otherwise measurement time may be affected or data may be destroyed.
В	USB 2.0 connector	Connects to USB 2.0. Do not insert or remove during loading or writing of measurement or data.
	GGB 2.0 connector	The measurement time can be longer or data can be damaged.
		Connects to USB 3.0. Do not insert or remove during loading or writing of measurement or data.
С	USB 3.0 connector	The measurement time can be longer or data can be damaged.
C	USB 3.0 Connector	USB 3.0 has a high ability to supply the bus power.
		Use the Sensor Controller by combining USB 3.0, faster transport can be realized.
D	Ethernet connector	Connect an Ethernet device.
U	Ethernet connector	Shared Ethernet port and EtherNet/IP port.
Е	RS-232C connector	Connect an external device such as a programmable controller.
F	DVI-I connector	Connect a monitor.
G	Parallel connector	Compatible controller to external devices such as a supersonal
G	(control lines, data lines)	Connect the controller to external devices such as a sync sensor.
Н	Camera connector Connect a camera.	
ı	Power supply terminal connector Connect a DC power supply. Wire the controller independently on other devices. Be sure to ground the FH Sensor Controller alone.	

^{*} Use the attachment power terminal connector (male) of FH-XCN-L series.
For details, refer to 5-3 Sensor Controller Installation on Vision System FH/FZ5 series Hardware Setup Manual(Z366).

Processing Items

Group	Icon		Processing Item	Page in the Catalog
	å	Search	Used to identify the shapes and calculate the position of measurement objects.	P16
	600	Flexible Search	Recognizing the shapes of workpieces with variation and detecting their positions.	P16
	清	Sensitive Search	Search a small difference by dividing the search model in detail, and calculating the correlation.	P16
		ECM Search	Used to search the similar part of model form input image. Detect the evaluation value and position.	
		EC Circle Search	Extract circles using "round " shape information and get position, radius and quantity in high preciseness.	
	4	Shape Search II	Used to search the similar part of model from input image regardless of environmental changes. Detect the evaluation value and position.	P16
	4	Shape Search III	Robust detection of positions is possible at high-speed and with high precision incorporating environmental fluctuations, such as differences in individual shapes of the workpieces, pose fluctuations, noise superimposition and shielding.	P16
		EC Corner	This processing item measures a corner position (corner) of a workpiece.	
	,	Ec Cross	The center position of a crosshair shape is measured using the lines created by the edge information on each side of the crosshair.	
		Classification	Used when various kinds of products on the assembly line need to be sorted and identified.	P16
	+	Edge Position	Measure position of measurement objects according to the color change in measurement area.	P16
		Edge Pitch	Detect edges by color change in measurement area. Used for calculating number of pins of IC and connectors.	P16
	#	Scan Edge Position	Measure peak/bottom edge position of workpieces according to the color change in separated measurement area. Measure max/min/average width of	P16
	=	Scan Edge Width	workpieces according to the color change in separated measurement area.	P16
	Q	Circular Scan Edge Position	Measure center axis, diameter and radius of circular workpieces.	P16
Measurement	$ \mathfrak{O} $	Circular Scan Edge Width	Measure center axis, width and thickness of ring workpieces.	P16
		Intersection	Calculate approximate lines from the edge information on two sides of a square workpiece to measure the angle formed at the intersection of the two lines.	P16
	2	Color Data	Used for detecting presence and mixed varieties of products by using color average and deviation.	
		Gravity and Area	Used to measure area, center of gravity of workpices by extracting the color to be measured.	
		Labeling	Used to measure number, area and gravity of workpieces by extracting registered color.	
		Label Data	Selecting one region of extracted Labeling, and get that measurement. Area and Gravity position can be got and judged.	
	M	Defect	Used for appearance measurement of plain-color measurement objects such as defects, stains and burrs.	P16
	A	Precise Defect	Check the defect on the object. Parameters for extraction defect can be set precisely.	P16
		Fine Matching	Difference can be detected by overlapping and comparing (matching) registered fine images with input images.	P16
	ABC	Character Inspect	Recognize character according correlation search with model image registered in [Model Dictionary].	P17
	Date 08:02:1	Date Verification	Reading character string is verified with internal date. Register character pattern as dictionary. The	P17
	A	Model Dictionary	pattern is used in [Character Inspection].	
		2DCode *2	Recognize 2D code and display where the code quality is poor. Recognize barcode, verify and output	P17
		Barcode *1	decoded characters.	P17
	OCR	OCR Hoor	Recognize and read characters in images as character information.	P17
	OCR	OCR User Dictionary	Register dictionary data to use for OCR.	P17
		Circle Angle	Used for calculating angle of inclination of circular measurement objects.	
		Glue Bead Inspection Camera Image	You can inspect coating of a specified color for gaps or runoffs along the coating path. To input images from cameras. And set up	P17
	哽	Input FH	the conditions to input images from cameras. (For FH Sensor Controllers only)	
Input Image	•	Camera Image Input HDR	Create high-dynamic range images by acquiring several images with different conditions.	
	Lite	Camera Image Input HDRLite	HDR function for FZ-SQ□ Intelligent Compact Cameras.	
		Camera Switch	To switch the cameras used for measurement. Not input images from cameras again.	

Group	Icon		Processing Item	Corresponding Page in the Catalog
		Measurement Image Switching	To switch the images used for measurement. Not input images from camera again.	
Input Image	哽哽	Multi-trigger Imaging	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert the Multi-trigger Imaging to the top of the flow.	
	에 에 에 에 에 에 에 에 에 에 에 에 에	Multi-trigger Imaging Task	The Multi-trigger Imaging processing item captures multiple images at user-defined timings and executes parallel measurement for each image. Insert this processing item to the top of the processing which requires imaging for multiple times.	
,	=	Position Compensation	Used when positions are differed. Correct measurement is performed by correcting position of input images.	P18
	M	Filtering	Used for processing images input from cameras in order to make them easier to be measured.	P18
		Backgrond Suppression	To enhance contrast of images by extracting color in specified brightness.	P18
		Brightness Correct Filter	Track brightness change of entire screen and remove gradual brightness change such as uneven brightness.	P18
		Color Gray Filter	Color image is converted into monochrome images to emphasize specific color.	P18
		Extract Color Filter	Convert color image to color extracted image or binary image.	P18
	4	Anti Color Shading	To remove the irregular color/pattern by uniformizing max.2 specified colors.	P18
Compensate		Stripes Removal Filter II	Remove the background pattern of vertical, horizontal and diagonal stripes.	P19
image	#	Polar Transformation	Rectify the image by polar transformation. Useful for OCR or pattern inspection printed on circle.	P18
	4	Trapezoidal Correction	Rectify the trapezoidal deformed image.	P18
	4/	Machine Simulator	How the alignment marks would move on the image when each stage or robot axis is controlled can be checked.	
		Image Subtraction	The registered model image and measurement image are compared and only the different pixels are extracted and converted to an image.	
		Advanced filter	Process the images acquired from cameras in order to make them easier to measure. This processing item consolidates exting image conversion filtering into one processing item and adds extra functions.	P18
		Panorama	Combine multiple image to create one big image.	P18
	O \$	Unit Macro	Advanced arithmetic processing can be easily incorporated into workflow as Unit Macro processing items.	P20
	O¢	Unit Calculation Macro	This function is convenient when the user wants to calculate a value using an original calculation formula or change the set value or system data of a processing item.	P20
	""	Calculation	Used when using the judge results and measured values of ProcItem which are registered in processing units.	
	* +	Line Regression	Used for calculating regression line from plural measurement coodinate.	
	Ö	Circle Regression	Used for calculating regression circle from plural measurement coordinate.	
		Precise Calibration	Used for calibration corresponding to trapezoidal distortion and lens distortion.	P15
	User	User Data	Used for setting of the data that can be used as common constants and variables in scene group data.	P21
Support		Set Unit Data	Used to change the ProcItem data (setting parameters,etc.) that has been set up in a scene.	
Support measurement		Get Unit Data	Used to get one data (measured results, setting parameters,etc.) of ProcItem that has been set up in a scene.	
		Set Unit Figure	Used for re-setting the figure data (model, measurement area) registered in an unit.	
		Get Unit Figure	Used for get the figure data (model, measurement area) registered in an unit.	
		Trend Monitor	Used for displaying the information about results on the monitor, facilitating to avoid NG and analyze causes.	P21
		Image Logging	Used for saving the measurement images to the memory and USB memory.	
	a →	Image Conversion Logging	Used for saving the measurement images in JPEG and BMP format.	
	#	Data Logging	Used for saving the measurement data to the memory and USB memory.	
	٩	Elapsed Time	Used for calculating the elapsed time since the measurement trigger input.	
		Wait	Processing is stopped only at the set time. The standby time is set by the unit of [ms].	
		Focus	Focus setting is supported.	P15

Group	Icon		Processing Item	Corresponding Page in the Catalog	
	*	Iris	Focus and aperture setting is supported.	P15	
	999	Parallelize	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed at the top of processing to be performed in parallel.		
	1 000	Parallelize Task	A part of the measurement flow is divided into two or more tasks and processed in parallel to shorten the measurement time. This processing item is placed immediately before processing to be performed in parallel between Parallelize and Parallelize End.		
		Statistics	Used when you need to calculate an average of multiple measurement results.		
		Referrence Calib Data	Calibration data and distortion compensation data held under other processing items can be referenced.		
		Position Data Calculation	The specified position angle is calculated from the measured positions.	P14	
		Stage Data	Sets and stores data related to stages.		
	70	Robot Data	Sets and stores data related to robots.		
Support measurement		Vision Master Calibration	This processing item automatically calculates the entire axis movement amount of the control equipment necessary for calibration.	P15	
		PLC Mastoer Calibration	Calibration data is created using a communication command from PLC.	P15	
	ڗ۬	Convert Position Data	The position angle after the specified axis movement is calculated.	P14	
	+/	Movement Single Position	The axis movement that is required to match the measured position angle to the reference position angle is calculated.	P14	
	-1/ /	Movement Multi Points	The axis movements that are required to match the measured position angles to the corresponding reference position angles are calculated.	P14	
	+	Detection Point	Obtains position/angle information by referring to the coordinate values measured with the Measurement Processing Unit.		
	*	Camera Calibration	By setting the camera calibration, the measurement result can be converted and output as actual dimensions.	P15	
	=	Data Save	The set data can be saved in the controller main unit or as scene data. The data is held even after the FH/FZ power is turned off.		
	<u> </u>	Conveyor Calibration	Conveyor Calibration is used to calibrate camera, conveyor, and robots for conveyor tracking application.		

Group	Icon			Corresponding Page in the Catalog
	-	Conditional Branch	Used where more than two kinds of products on the production line need to detected separately.	
	\$	End	This Procltem must be set up as the last processing unit of a branch.	
	100	DI Branch	Same as ProcItem "Branch". But you can change the targets of conditional branching via external inputs.	
Branch		Control Flow Normal	Set the measurement flow processing into the wait state in which the specific no-protocol command can be executed.	
branch	==	Control Flow PLC Link	Set the measurement flow processing into the wait state in which the specific PLC Link command can be executed.	
	==	Control Flow Parallel	Set the measurement flow processing into the wait state in which the specific parallel command can be executed.	
	==	Control Flow Fieldbus	Set the measurement flow processing into the wait state in which the specific Fieldbus command can be executed.	
	SMITCH	Selective Branch	Easily branch to multiple destinations.	
		Data Output	Used when you need to output data to the external devices such as PLC or PC via serial ports.	
		Parallel Data Output	Used when you need to output data to the external devices such as PLC or PC via parallel ports.	
Output result	<u> </u>	Parallel Judgement Output	Used when you need to output judgement results to the external devices such as PLC or PC via parallel ports.	
		Fieldbus Data Output	Outputs data to an external device, such as a Programmable Controller, through a fieldbus interface.	
Display result	OK	Result Display	Used for displaying the texts or the figures in the camera image.	
		Display Image File	Display selected image file.	
	NG	Display Last NG Image	Display the last NG images.	
*1 Bar Code		Conveyor Panorama Display	Display images of the tracking area as a panoramic image.	

 ^{*1} Bar Codes that can be read : JAN/EAN/UPC (including add-on codes), Code 39, Codabar (NW-7), ITF (Interleaved 2 of 5), Code 93, Code 128, GS1-128, GS1 DataBar (RSS-14 / RSS Limited / RSS Expanded), Pharmacode
 *2 D Codes that can be read : Data Matrix (ECC200), QR Code

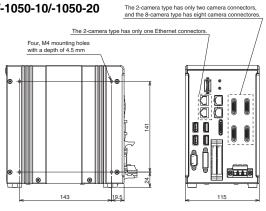
Dimensions

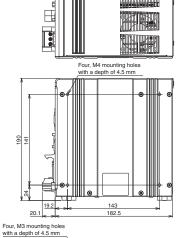
Sensor Controllers

High-speed Controllers/Standard Controllers Box-type

FH-3050/-3050-10/-3050-20

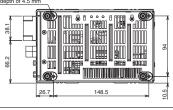
FH-1050/-1050-10/-1050-20



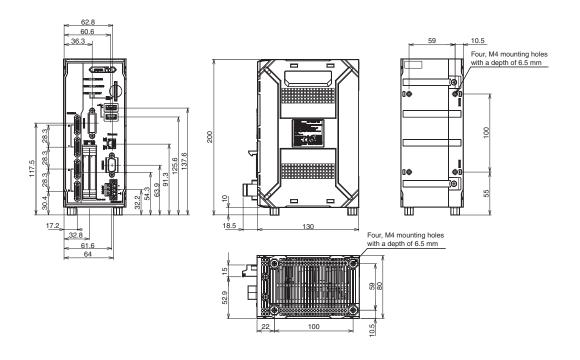




(Unit: mm)

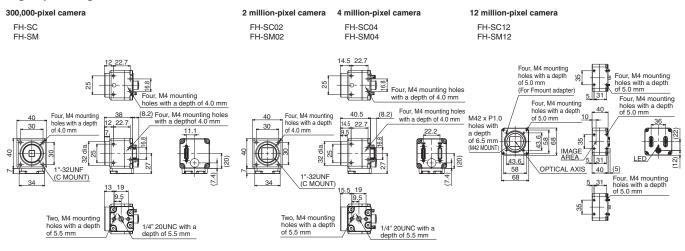


Lite Controllers BOX type FH-L550/-L550-10

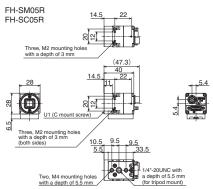


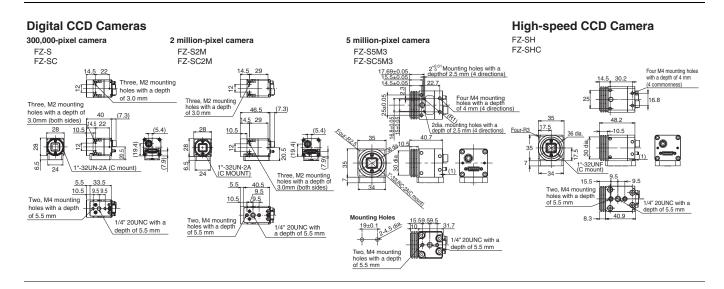
Cameras

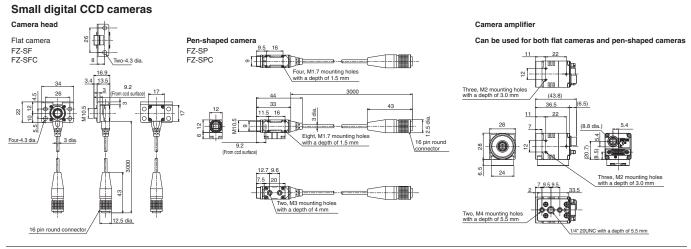
High-speed Digital CMOS Camera

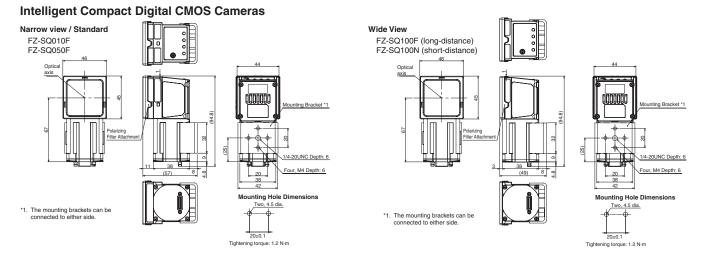


Digital CMOS Cameras







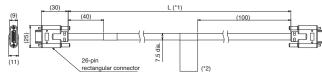


Cables

Camera Cable

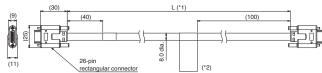
Camera Cable

FZ-VS3

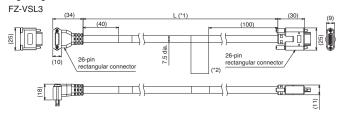


Bend resistant Camera Cable

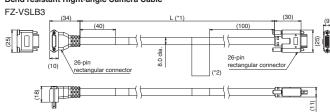
FZ-VSB3



Right-angle Camera Cable

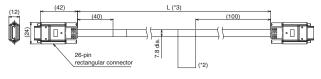


Bend resistant Right-angle Camera Cable



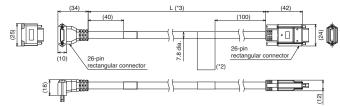
Long-distance Camera Cable

FZ-VS4



Long-distance Right-angle Camera Cable

FZ-VSL4



- *1. Cable is available in 2m/3m/sm/10m.

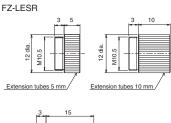
 *2. Each camera cables has polarity.
 Please ensure that the name plate side of the cable is connected to the controller.

 *3. Cable is available in 15m.

Camera Cable Extension Unit

FZ-VSJ Camera Cable Connector (Camera side) POWER LED Power terminal

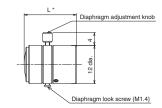
Extension Tubes for Small Camera





Lens for Small Camera

FZ-LES Series



* Overall length is available in 16.4mm/19.7mm/23.1mm/25.5mm.

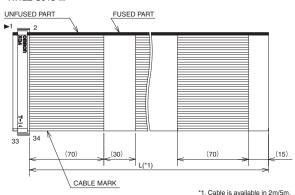
Encoder Cable

*1. Cable is available in 1.5 m

FH-VR L1 (*1) 100 11.7

Parallel I/O Cable

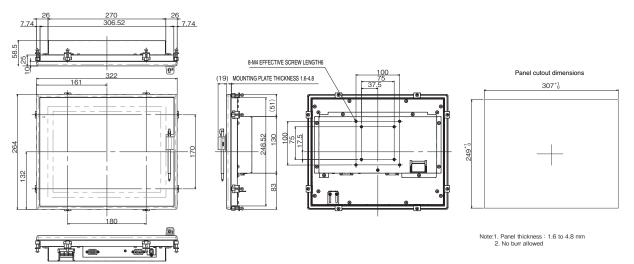
XW2Z-S013-□



Touch Panel Monitor

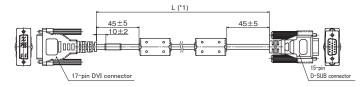
FH-MT12

Panel cutout dimensions



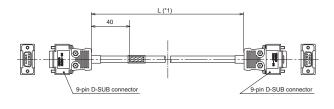
DVI-Analog Conversion Cable for Touch Panel Monitor

FH-VMDA



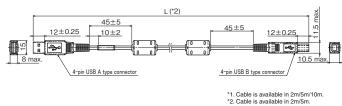
RS-232C Cable for Touch Panel Monitor

XW2Z-UUDPP-1



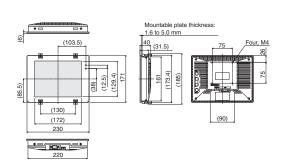
USB Cable for Touch Panel Monitor

FH-VUAB



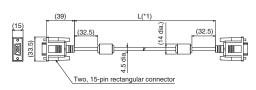
LCD Monitor

FZ-M08



LCD Monitor Cable

FZ-VM



*1. Cable is available in 2m/5m.

DVI-I -RGB Conversion Connector

FH-VMRGB

63.8

63.8

63.8

63.8

63.8

63.8

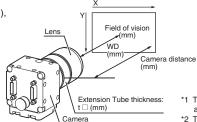
63.8

Optical Chart

Meaning of Optical Chart

The X axis of the optical chart shows the field of vision (mm) (*1), and the Y axis of the optical chart shows

the camera installation distance (mm) (*2).



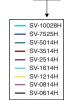
- *1 The lengths of the fields of vision given in the optical charts are the lengths of the Y axis
- are the lengths of the Y axis.
 *2 The vertical axis represents WD for small cameras.

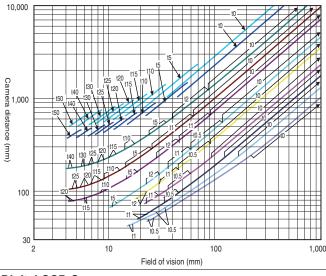
Normal Lenses

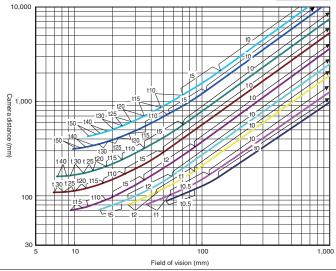
High-speed Digital CMOS Camera FH-S□,
High-speed Digital CCD Camera FZ-SH□,
Digital CCD Camera FZ-S□,
300,000-pixel
(Using 3Z4S-LE SV-V Series)

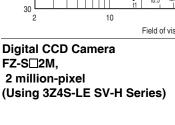


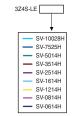


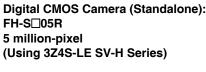


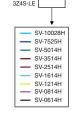


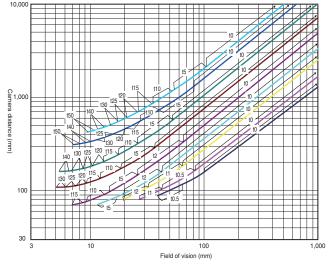


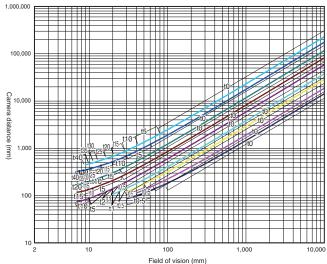


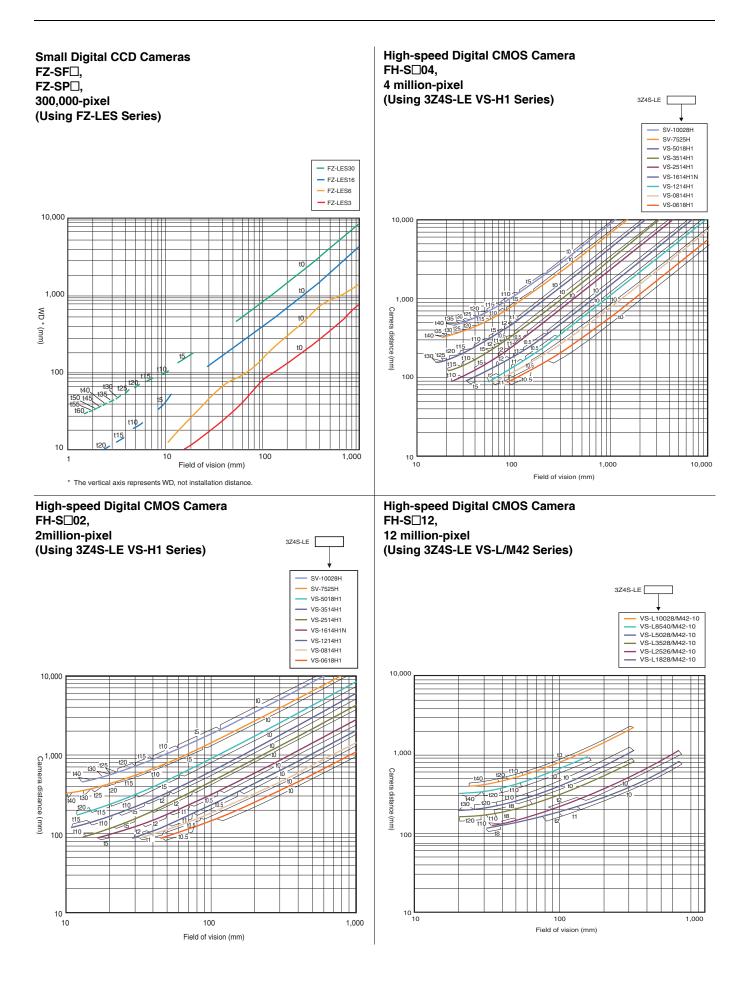








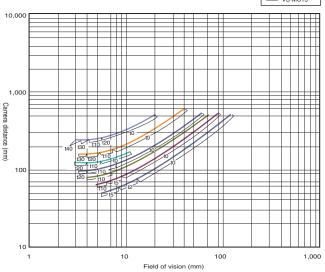




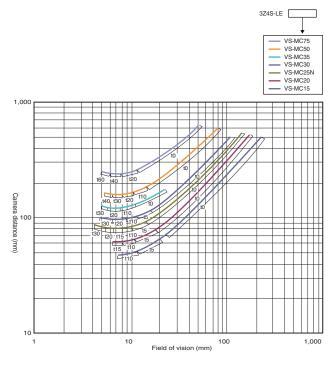
Vibration/Shock-resistance Lens

High-speed Digital CMOS Camera FH-S□,
High-speed Digital CCD Camera FZ-SH□,
Digital CCD Camera FZ-S□,
300,000-pixel
(Using 3Z4S-LE VS-MC Series)

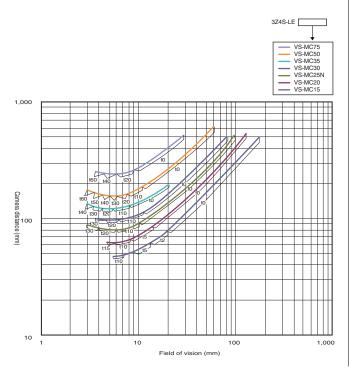


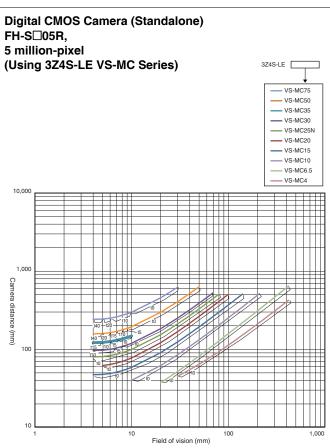


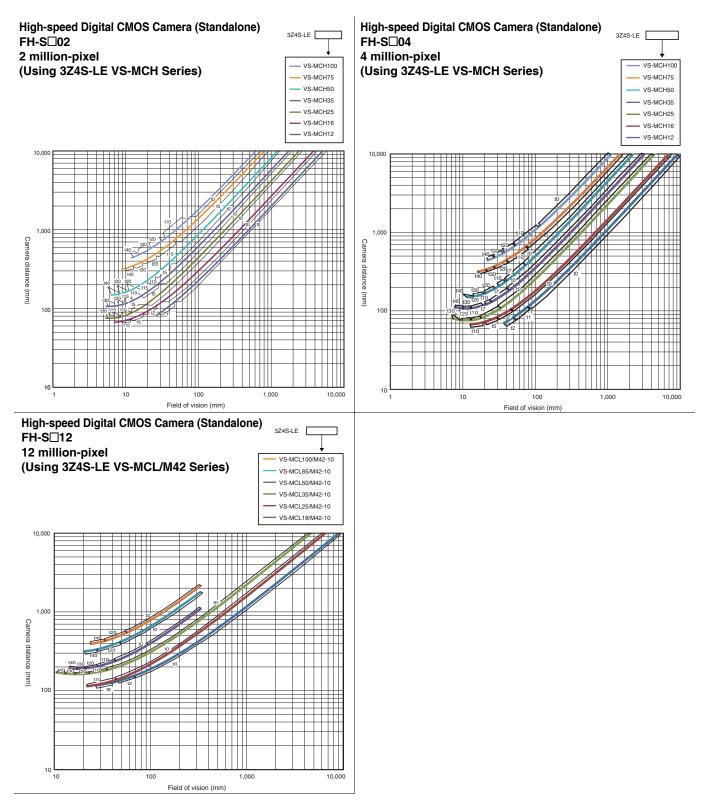
Digital CCD/CMOS Camera FZ-S□5M3, 5 million-pixel (Using 3Z4S-LE VS-MC Series)



Digital CCD Camera FZ-S□2M, 2 million-pixel (Using 3Z4S-LE VS-MC Series)







Related Manuals

Man.No.	Model number	Manual
Z365	FH/FZ5	Vision System FH/FZ5 Series User's Manual
Z341	FH/FZ5	Vision System FH/FZ5 series Processing Item Function Reference Manual
Z342	FH/FZ5	Vision System FH/FZ5 Series User's Manual for Communications Settings
Z343	FH	Vision System FH Series Operation Manual for Sysmac Studio
Z366	FH/FZ5	Vision System FH/FZ5 series Hardware Setup Manual
Z367	FH/FZ5	Vision System FH/FZ5 series Macro Customize Functions Programming Manual

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