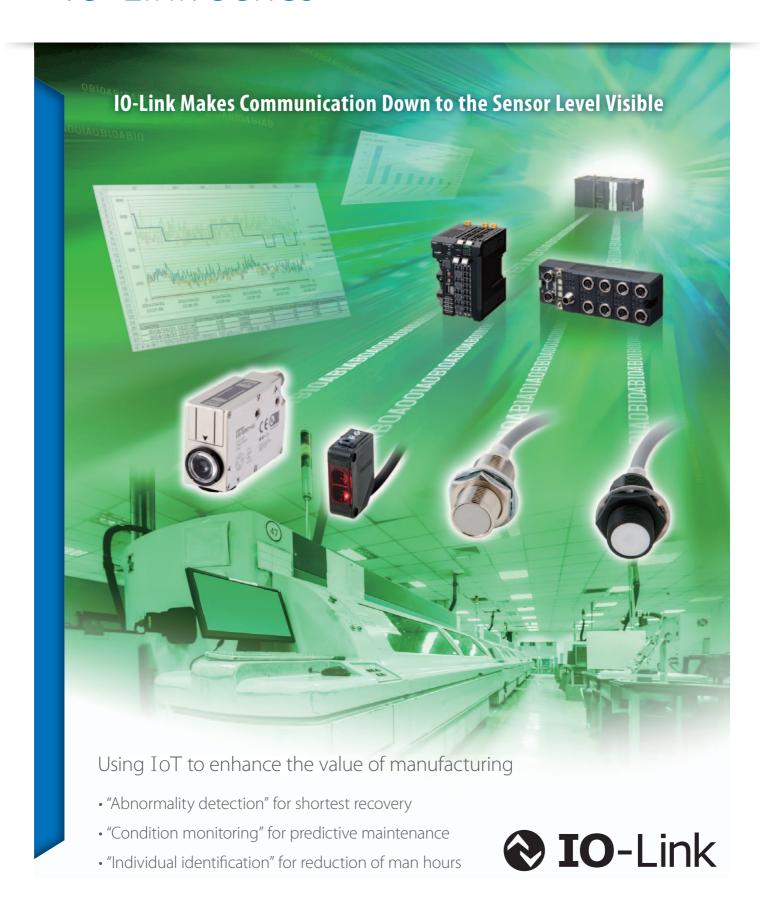


IO-Link Series



Toward the Factory of the Future with Onsite IoT

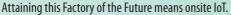
Today's manufacturing industry is facing the need for high-mix low-volume production and advanced manufacturing. On the other hand, with the technology of digital fields, ICT and analysis technology are advancing by leaps and bounds. We aim to achieve the Factory of the Future through the use of the IoT (Internet of Things) in order to respond to such changes in the environment.

What we are aiming for is

the Factory of the Future in which human intention and equipment converge

Using the IoT to connect things at the manufacturing site with each other and with people from equipment down to the individual components incorporated into devices makes it possible to detect signs that may indicate problems before the equipment stops and for the equipment to handle this autonomously and analyze the causes of defects. The result is that machines and equipment move and stop as people intend. This allows personnel to concentrate on higher added-value work without the need for

emergency maintenance or for going back over work already completed.









Automation in Manufacturing with Intelligence

With OMRON, you can collect a wide variety of data at the manufacturing site level simply and without omission or excess effort.

The implicit knowledge of proficient skills and manufacturing know-how is turned into explicit knowledge and fed back to the manufacturing site to improve productivity. We are aiming to further use data for automation in manufacturing with intelligent equipment, including achieving production lines that do not stop and equipment that learns and evolves.

The Strength of the Manufacturing Site Developed by OMRON

Three Forms of Know-how Moving IoT Forward

At OMRON, we have the product know-how of a manufacturer who has produced control components for decades, the manufacturing know-how of a user who uses these control components on its own lines, and the know-how to handle open network environments.

With these three types of know-how, nurtured with the strength of manufacturing sites as only OMRON can, the customer's application is achieved and onsite IoT is moved forward powerfully.

Attaining the Factory of the Future Makes

Manufacturing More Enjoyable

Production Technology

Predictive control of the production line as a whole

which generates improvements

Concentrating on work that creates innovative products

From emergency maintenance to planned maintenance,





Step 2 **Data Analysis**

Improvement Cycle

Through the IoT

The First Step to the Factory of the Future Informationization of the Manufacturing Site

Attaining the Factory of the Future through the IoT starts with informationization of manufacturing sites.

OMRON itself started with visualization of the production lines in its own factories.

Data collected through EtherNet/IP™, EtherCAT, and other open networks is accumulated on the server and analyzed, and the results are used at the manufacturing site to improve productivity and quality.

We have already achieved major improvements by repeating this cycle of improvements through the IoT.





The Cycle of Improvements Through the IoT Has Been Verified in OMRON's Own Factories

We provide our customers with the know-how to achieve this and the results.

Productivity Improvement

Examples from Kusatsu Factory and Shanghai Factory

Through High-Speed Collection of Big Data

Improved Operating Rates

Improvement Results

- · Time to identify areas for improvement reduced to 1/6 or less*
- Productivity improved by 30%*

*In-house comparison.



Predictive Maintenance

Example from Ayabe Factory

Through Application of Big Data **Improved Equipment Maintenance** with Less Waste

Improvement Results

- · Productivity improved by avoiding intermittent stops
- · Costs reduced through accurate parts replacement









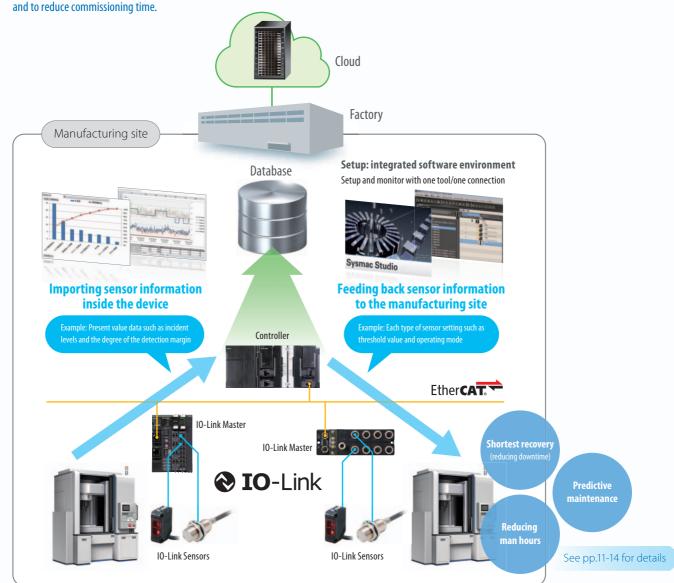
The IoT at the Component Level Is Necessary for Manufacturing Site Informationization

At many manufacturing sites, the adoption of the IoT is being promoted at the controller and HMI levels through EtherNet/IP or EtherCAT, but not at the component level.

Therefore, at OMRON, we early on created a lineup of devices for IO-Link, which is a sensor-level open network to promote sensor-level informationization.

Using IO-Link to Make Communications Down to the Sensor Level Visible

As our first round of IO-Link products, we now provide IO-Link Photoelectric Sensors, IO-Link Color Mark Photoelectric Sensors, IO-Link Proximity Sensors, and IO-Link Masters. By connecting Sensors and Controllers to an IO-Link Master, not only ON/OFF signals but also information required for stable operation, such as incident light levels, are made visible. We are making it possible to monitor the conditions of sensors and detect any abnormalities to shorten the recovery time for devices and equipment, to enable predictive maintenance,



IO-Link Is

Communication Technology That Realizes the Informationization of Sensor Levels



10-Link, which is specified as international standard IEC 61131-9,

is an open information technology (interface technology) between the Sensor/Actuator and the I/O Terminal.

It collects information held by the sensor/actuator through the IO-Link Master and via a fieldbus network into the host controller.

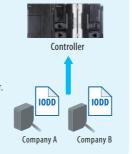
The IO-Link enables communication within the whole system and reduce time required for commissioning and maintenance.

An Open International Standard

As of December 2015, over 100 companies, including major sensor manufacturers, have joined the IO-Link Consortium.

Responding to Global Development

All IO-Link Sensors have an IODD (IO Data Description) file that lists what kind of instrument they are and what parameters need to be set for them. IODD files are globally common, so 10-Link Sensors can be used in the same way with any manufacturer.





Communications of the ON/OFF Signals and Sensor Information

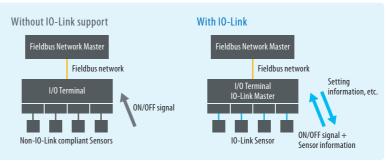
10-Link can send and receive in both directions not just ON/OFF signals but also sensor information.

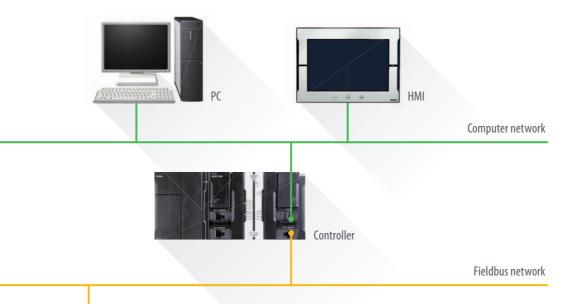
The IO-Link baud rates*1 of COM 1, 2, and 3 are specified in the IO-Link specifications.

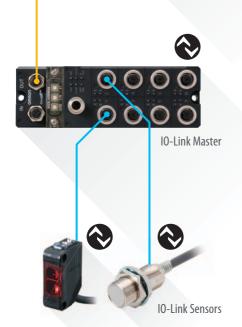
Omron's IO-Link components are compatible with COM 2 and COM 3, and are capable of high speed communications.

Condition Monitoring/Batch Data Input is Available

The IO-Link master has multiple ports and an IO-Link Sensor is connected to each port. Unlike a fieldbus network, communication is one-to-one.

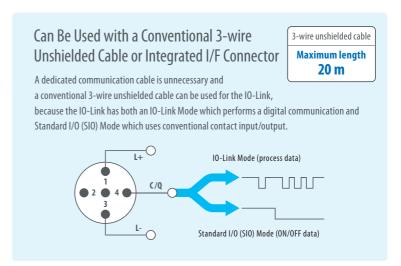






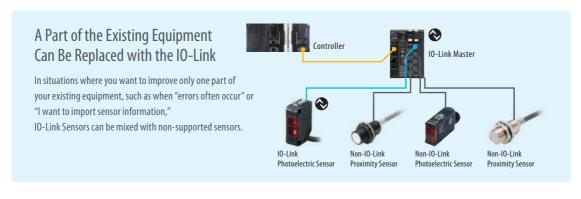
Uses 3-wire Unshielded Cable

No dedicated communication cable required. A communication system that can be used both as an ON/OFF line and a communication line.



Capable of Intermixing IO-Link Sensors and Sensors That Are Not Compliant with IO-Link

You can connect an IO-Link Sensor and a Sensor/Actuator that is not compliant with IO-Link to a single IO-Link Master.



Omron's IO-Link Compliant Equipment

Masters and Sensors Can Be Chosen to Match Your Setup Situation

Omron provides two types of Masters, a Master Unit with screw-less clamp terminal blocks and a Master Unit for M12 Smartclick connectors, as IO-Link compliant devices and Sensors for connecting to the screw-less clamp terminals or to the M12 connector terminals that support each Master.



IO-Link







Smartclick

Note: Smartclick is a registered trademark of Omron.



The Unit for M12 Smartclick Connector Can Be **Used in Watery, and Dusty Environments**

Environment-resistant Unit IP67 Type GX-ILM08C 8-port/M12 Smartclick connector

Note: Eight sensors can be connected to one device.

IO-Link



Value Provided by IO-Link

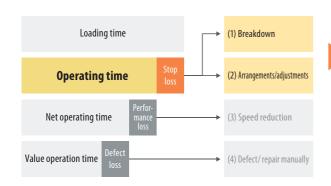
Supporting Solutions to Management Issues in the Manufacturing Industry Through Abnormality Detection/Condition Monitoring/Individual Identification

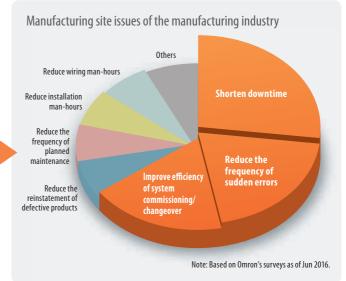
"Improving an equipment operation rate" is a universal management issue at manufacturing sites. As the calculation formula below shows, an overall equipment operation rate is determined by how stops, drops in speed and defects are avoided.

Overall Equipment Effectiveness*1 = Availability (stop loss) \times speed performance (performance loss) \times quality (defect loss)

*1. OEE: overall equipment effectiveness. An index that stratifies the effectiveness of production equipment developed and advocated by the Japan Institute of Plant Maintenance

These three loss occurrence factors are divided into the following (1) to (4). Of these, the occurrence factors for stop loss are the same as for the three major issues (right diagram) at the manufacturing sites, and it can be seen that the issue happening at a site becomes a stop loss factor.







Omron's IO-Link Compliant Components Solve "Stop Loss" Issues and Improve Equipment Operation Rate



What makes the shortening of downtime possible is...

"Abnormality detection" for the shortest recovery





What makes the reduction of the frequency of sudden errors possible is...

"Condition monitoring" for predictive maintenance





What makes the improvement of changeover efficiency possible is...

"Individual identification" for the reduction of man-hours

To those in charge of maintenance "Abnormality detection" for the shortest recovery



Detects Wiring Cable Disconnections and Errors and Improves Equipment Operation Rate Through Quick Maintenance

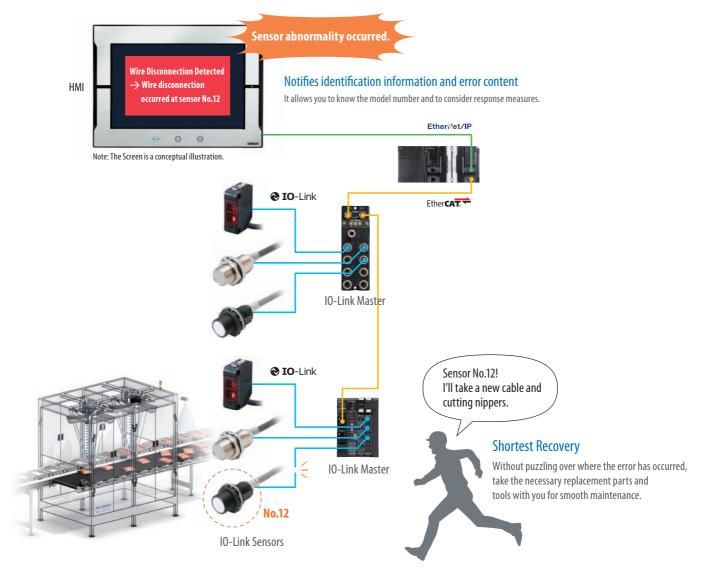
- · An abnormality was displayed on the abnormality display screen, but upon going to look at the equipment, no external error was detected and the cause of the stop was not understood...
- · Those responsible for maintenance investigated the cause of the abnormality from the activity of the stopped equipment, but because the maintenance person relied on the skill he or she has to identify the abnormality and replace the failed sensor, stoppages from 2 hours to several days occur...



With an IO-Link Photoelectric Sensor/Proximity Sensor

Abnormal area and phenomenon of sensors are reported in real time

When an abnormality occurs in a sensor, because you can see where the abnormality occurred and the factors estimated for it, you can go to where the abnormality occurred and recover the equipment in the shortest amount of time. Also with wire disconnection detection, not only output wires, but also power lines can be detected unconditionally.



Predictive maintenance

To those in charge of maintenance

"Condition monitoring" for predictive maintenance (1)

The Proximity Sensor Indicates an Excessive Proximity to the Sensing Object.

Understand the Changes in Device Condition in Advance and Reduce Sudden Stops

Existing problems

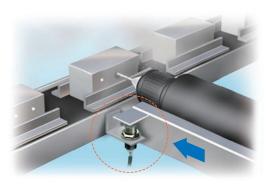
The detection position changes due to wear and vibration in the device's mechanical parts and as a result, false detection and collision with the sensor have a negative impact on the device...

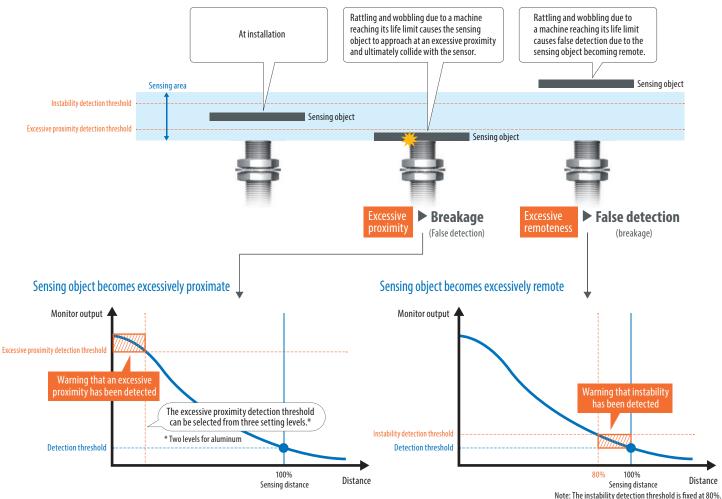


With an IO-Link Proximity Sensor

You are notified of excessive remoteness or proximity, and the occurrence of sudden defects is greatly reduced

Constantly monitoring the position of the sensing object and notifying of excessive remoteness or proximity can be used for predictive maintenance of the device.





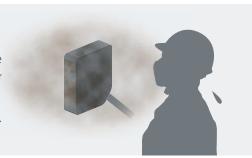


To those in charge of maintenance

"Condition monitoring" for predictive maintenance (2)

Understand Unstable Situations in the Incident Level of the Photoelectric Sensor in Advance and Reduce Sudden Stops

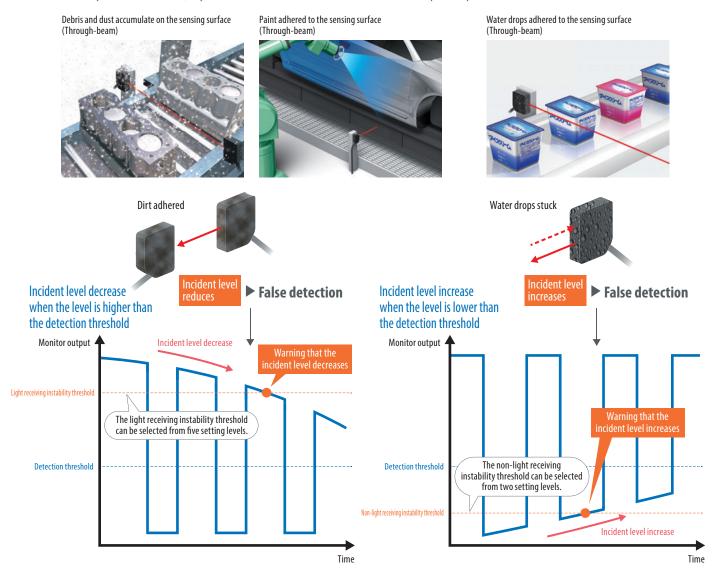
- · In a conveyance process operating for 24 hours, dust or dirt accumulated on the detection surface of the photoelectric sensor, leading to a decline in the light incident level that causes the sensor to make false detection and the device to stop...
- · Water drops stick to the sensing surface of the reflective sensor causing reflected light to enter...



With an IO-Link Photoelectric Sensor

A light incident level monitor prevents false detection

With a response time of 1 ms, Photoelectric Sensor's light incident level is output for monitoring. It is output when the light incident level exceeds the instability detection threshold, so you can check the site before false detection occurs and perform predictive maintenance.





To those in charge of production engineering "Individual identification" for the reduction of man-hours

Improving System Commissioning and Changeover Efficiency by Checking Identifications in Batches

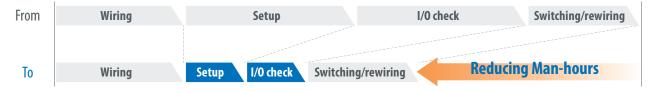
- · During system start-up or changeover, operators had to perform the I/O check for each of the thousands of sensors installed on the line, and it took an enormous amount of time...
- · When a sensor is installed wrong or an error occurs, wasteful work occurred that would normally be unnecessary...



With an IO-Link Photoelectric Sensor/Proximity Sensor

Without going to the site, you can check individual sensor identifications in batches, resulting in a sharp reduction of commissioning time

By checking the sensor identification (manufacturer/sensor type/model number), you can easily check mistakes such as misconnected or unconnected sensors and installation mistakes. Also, because it is possible to program multiple sensors at once using the command language used only for the controller, it is also possible to reduce commissioning time sharply.



Note: The graph above is a conceptual illustration.

Setup

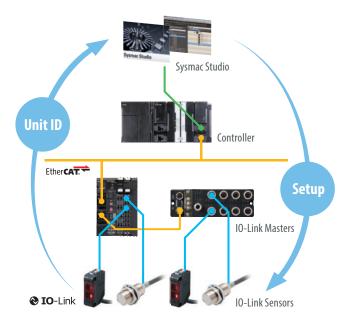
Setting all sensors from a host device at the same time

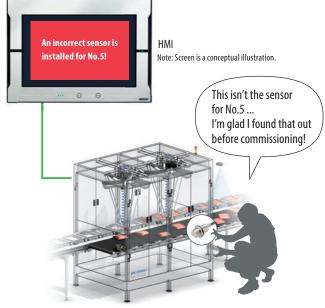
Program all at once to reduce commissioning time and inconsistent settings

I/O check

Use identification checks with HMI to prevent installation mistakes

Makes it possible to check for sensor installation mistakes before commissioning





IO-Link Masters

| Product name | | Number of IO-Link ports | External connection terminal | Environment tolerance | Model |
|--|------|-------------------------|------------------------------|-----------------------|-----------|
| NX Series 10-Link Master Unit ^{*1} | | 4 | Screw-less clamp terminals | IP20 | NX-ILM400 |
| GX Series 10-Link Master Unit | 0000 | 8 | M12 Smartclick Connector | IP67 | GX-ILM08C |

^{*1.} Ether CAT Communication Coupler Unit NX-ECC2 $\Box\Box$ is necessary for the system configuration.

IO-Link Sensors

Photoelectric Sensor

| Product name | | System | Model | |
|--------------|-----------------------------------|--|-----------------------|--|
| E3Z-□-IL□ | | Pre-wired Models (2m) | E3Z-T81-IL□ 2M | |
| | Through-beam | M12 Pre-wired Smartclick Connector Models (0.3m) | E3Z-T81-M1TJ-IL□ 0.3M | |
| | | Standard M8 Connector Models | E3Z-T86-IL□ | |
| | | Pre-wired Models (2m) | E3Z-R81-IL□ 2M | |
| V V S | Retro-reflective | M12 Pre-wired Smartclick Connector Models (0.3m) | E3Z-R81-M1TJ-IL□ 0.3M | |
| | | Standard M8 Connector Models | E3Z-R86-IL□ | |
| | Diffuse-reflective | Pre-wired Models (2m) | E3Z-D82-IL□ 2M | |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E3Z-D82-M1TJ-IL□ 0.3M | |
| | | Standard M8 Connector Models | E3Z-D87-IL□ | |
| | | Pre-wired Models (2m) | E3Z-L81-IL□ 2M | |
| | Diffuse-reflective Narrow-beam | M12 Pre-wired Smartclick Connector Models (0.3m) | E3Z-L81-M1TJ-IL□ 0.3M | |
| | bediii | Standard M8 Connector Models | E3Z-L86-IL□ | |

Color Mark Photoelectric Sensor

| Product name | | System | | Model | |
|---------------|---|--------------------|----------------------|---------------|--|
| E3S-DCP21-IL□ | 0 | Diffuse-reflective | M12 Connector Models | E3S-DCP21-IL□ | |

Standard Proximity Sensor (DC 3-wire Shielded Model)

| Product name | System | | Model |
|--------------|------------|--|-------------------------|
| E2E-□-IL□ | M12 | Pre-wired Models (2m) | E2E-X3B4-IL□ 2M |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E2E-X3B4-M1TJ-IL□ 0.3M |
| 3 3 | M18 M30 | Pre-wired Models (2m) | E2E-X7B4-IL□ 2M |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E2E-X7B4-M1TJ-IL□ 0.3M |
| | | Pre-wired Models (2m) | E2E-X10B4-IL□ 2M |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E2E-X10B4-M1TJ-IL□ 0.3M |

Spatter-resistant Proximity Sensor (DC 3-wire Shielded Model)

| Product name | System | | Model |
|--------------|--------|--|--------------------------|
| E2EO-□-IL□ | M12 | Pre-wired Models (2m) | E2EQ-X3B4-IL□ 2M |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E2EQ-X3B4-M1TJ-IL□ 0.3M |
| N. W. W. | M18 | Pre-wired Models (2m) | E2EQ-X7B4-IL□ 2M |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E2EQ-X7B4-M1TJ-IL□ 0.3M |
| | M30 | Pre-wired Models (2m) | E2EQ-X10B4-IL□ 2M |
| | | M12 Pre-wired Smartclick Connector Models (0.3m) | E2EQ-X10B4-M1TJ-IL□ 0.3M |

Software

| Product name | Model |
|------------------|---------------|
| Sysmac Studio *2 | SYSMAC-SE2□□□ |

| MEMO |
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| E2EQ- 🗆 - IL 🗆 | 69 |

Communications Specifications

| Item | Specification |
|-------------------------|---|
| Communications protocol | IO-Link protocol |
| Baud rate | COM1 (4.8 kbps), COM2 (38.4 kbps), or COM3 (230.4 kbps) |
| Topology | 1:1 |
| Communications media | Unshielded cable |
| Communications distance | 20 m max. |
| Compliant standards | IO-Link Interface and System Specification Version1.1.2 * IO-Link Test Specification Version1.1.2 |

^{*} OMRON IO-Link products do not support the IO-Link preoperate state.

NX-series IO-Link Master Unit

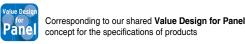
NX-ILM400

IO-Link makes sensor level information visible and solves the three major issues at manufacturing sites!

The screwless clamping terminal block reduces wiring work.

- Downtime can be reduced.
 Notifies you of faulty parts and such phenomena in the Sensor in real
- The frequency of sudden failure can be decreased.
 Condition monitoring of sensors and equipment to prevent troubles.
- The efficiency of changeover can be improved.
 The batch check for individual sensor IDs significantly decreases commissioning time.





Features

- The host controller can cyclically read control signals, status*1, wiring, and power supply status of IO-Link sensors. Because an IO-Link System can cyclically read analog data such as the amount of incident light in addition to ON/OFF information, it can be used for predictive maintenance based on detection of such things as decreases in the amount of light.
- User-specified data in IO-Link devices can be read and written from the host controller when necessary.
- Digital signals can be input rapidly from IO-Link sensors*2 during IO-Link communications.
- · IO-Link sensors can be combined with non-IO-Link sensors.
- Incorrect connections of IO-Link sensors can be checked when IO-Link communications start.
- Backup and restoration of IO-Link device parameters*3 make replacement of IO-Link sensors easier.
- Sensors can report their errors to the master, which facilitates locating errors from the host.
- The total number of retries in cyclic communications can be recorded. You can use this value to check for the influences of noise and other problems.

(When EtherCAT is used as the host communication interface) *3

- Up to four sensors can be connected.
- *1. Examples for Photoelectric Sensors: Instability detection and sensor errors
- *2. IO-Link sensors that support digital inputs that use pin 2 of IO-Link Master Unit ports
- *3. When the Omron IO-Link master unit is used

Sysmac is a trademark or registered trademark of OMRON Corporation in Japan and other countries for OMRON factory automation products. EtherCAT® is a registered trademark of Beckhoff Automation GmbH for their patented technology.

EtherNet/IP™ is the trademarks of ODVA.

Other company names and product names in this document are the trademarks or registered trademarks of their respective companies.

NX-ILM400

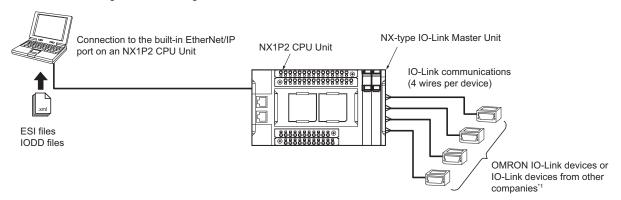
System Configuration

Controller Communications with NX Bus

NX bus communications can be used only when the controller is an NX1P2 CPU Unit.

Support Software:

- IO-Link Master Unit settings: Use the Sysmac Studio.
- IO-Link device settings: Use CX-ConfiguratorFDT.



*1. You can also connect a combination of general-purpose sensors and other devices.

Applicable Support Software

| | IO-Link Master | Applicable Support Software | | | |
|------------------|----------------|-----------------------------|------------------|--|--|
| Function | Unit type | | | Setting and monitoring the connected IO-Link devices | |
| Applicable | NX | Sysmac Studio *1 | Sysmac Studio *1 | CX-ConfiguratorFDT *2 | |
| Support Software | GX | Sysmac Studio *1 | Sysmac Studio *1 | CX-ConfiguratorFDT *2 | |

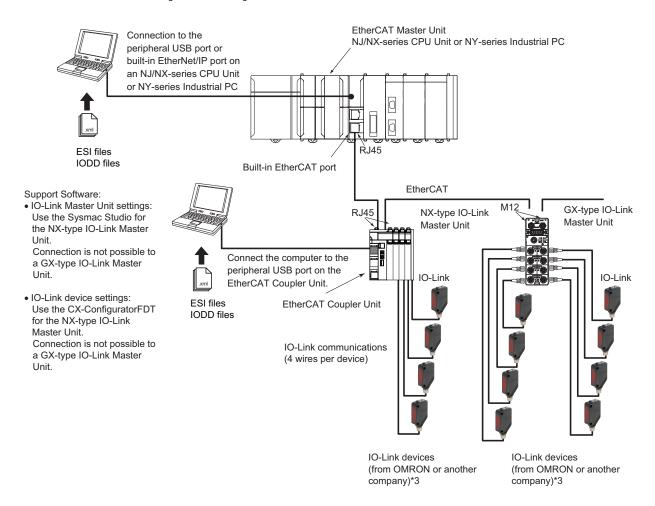
^{*1.} Sysmac Studio version 1.17 or higher is required.

^{*2.} CX-ConfiguratorFDT version 2.2 or higher is required.

Controller Communications with EtherCAT

Support Software:

- IO-Link Master Unit settings: Use the Sysmac Studio.*1
- IO-Link device settings: Use CX-ConfiguratorFDT.*2



- *1. When a host controller from another company is used with EtherCAT host communications, use the EtherCAT software application from the other company for a GX-type IO-Link Master Unit.
 - Note. For an NX-type IO-Link Master Unit, connect the Sysmac Studio to the EtherCAT Coupler Unit, as shown above.
- *2. When a host controller from another company is used with EtherCAT host communications, for a GX-type IO-Link Master Unit, make the IO-Link device settings with message communications from the host controller from the other company.
- Note. For an NX-type IO-Link Master Unit, connect CX-ConfiguratorFDT to the EtherCAT Coupler Unit, as shown above.
- *3. You can also connect a combination of general-purpose sensors and other devices.

Applicable Support Software

| | Applicable Support Software | | | |
|-----------------------------|---|--|--|--|
| IO-Link Master Unit type | PDO allocation settings (GX) I/O allocation settings (NX) | IO-Link Master Unit settings (IO-Link device connection configuration settings) *1 | Setting and monitoring the IO-Link devices | |
| NX | Sysmac Studio *1 | Sysmac Studio *1 | CX-ConfiguratorFDT *2 | |
| GX | Sysmac Studio *1 | Sysmac Studio *1 | CX-ConfiguratorFDT *2 | |

^{*1.} The device configuration settings are included in the IO-Link Master Unit settings.

^{*2.} CX-ConfiguratorFDT version 2.2 or higher is required.

NX-ILM400

Ordering Information

International Standards

- The standards are abbreviated as follows: U: UL, U1: UL(Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, CE: EU Directives, RCM: Regulatory Compliance Mark, and KC: KC Registration.
- Contact your OMRON representative for further details and applicable conditions for these standards.

NX-series IO-Link Master Unit

| | Specification | | | | |
|-------------------------------|-------------------------|-----------------------|-----------------------------------|-----------|------------------------|
| Product name | Number of IO-Link ports | I/O refreshing method | I/O connection terminals | Model | Standards |
| NX-series IO-Link Master Unit | 4 | Free-Run refreshing | Screwless clamping terminal block | NX-ILM400 | UC1, CE, N, RCM, KC |

Peripheral Devices

Sensor I/O Connectors

Order a cable with a connector on one end to connect a sensor. Refer to the *Ordering Information* in the catalog of the sensor to connect or the *Sensor I/O Connectors/Sensor Controllers* on your local OMRON website for recommended products.

Optional Products

| Product name | Specification | Model | Standards |
|---------------------------------|--|----------|-----------|
| Unit/Terminal Block Coding Pins | Pins for 10 Units (30 terminal block pins and 30 Unit pins) | NX-AUX02 | |

| | | Specif | | | | |
|----------------|------------------|-----------------------------|----------------------|---------------------------|-----------|-----------|
| Product name | No. of terminals | Terminal number indications | Ground terminal mark | Terminal current capacity | Model | Standards |
| Terminal Block | 16 | A/B | Not provided | 10 A | NX-TBA162 | |

Software

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

| | Specification | | | | |
|------------------------------|---|-----------------------|-------|---------------|-----------|
| Product name | | Number of licenses | Media | Model | Standards |
| Sysmac Studio | The Sysmac Studio is the software that provides an integrated environment for setting, programming, debugging and maintenance of machine automation controllers including the NJ/NX-series CPU Units, NY-series Industrial PC, EtherCAT Slave, and the HMI. Sysmac Studio runs on the following OS. | (Media only) | DVD | SYSMAC-SE200D | |
| Standard Edition Ver.1.□□ | Windows 7(32-bit/64-bit version)/Windows 8(32-bit/64-bit version)/Windows 8.1(32-bit/64-bit version)/Windows 10(32-bit/64-bit version) The Sysmac Studio Standard Edition DVD includes CX-Configurator FDT to set up IO-Link Master Units and IO-Link devices. For details, refer to the Sysmac Integrated Catalogue (P072). | 1 license * | | SYSMAC-SE201L | |

^{*} Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

General Specification

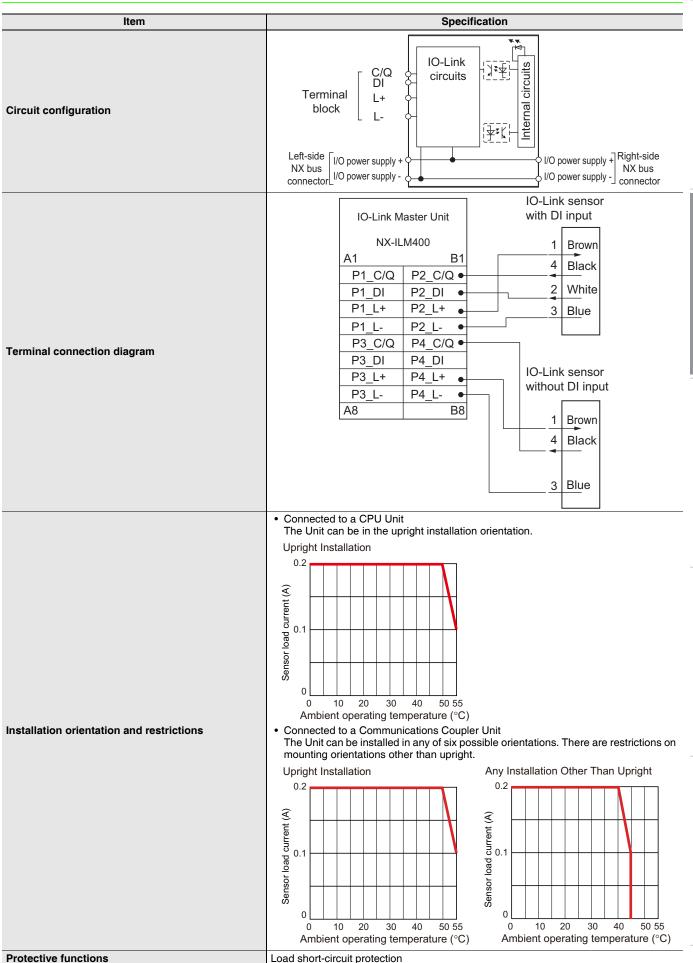
| Item | | Specification |
|--------------------------|-------------------------------|--|
| Enclosure | | Must be built into a panel. |
| Grounding methods | | Ground to 100 Ω or less. |
| | Ambient operating temperature | 0 to 55°C |
| | Ambient operating humidity | 10% to 95% (with no condensation or icing) |
| | Atmosphere | Must be free from corrosive gases. |
| | Ambient storage temperature | −25 to 70°C (with no condensation or icing) |
| | Altitude | 2,000 m max. |
| Operating environment | Pollution degree | Pollution degree 2 or less: Conforms to JIS B3502 and IEC 61131-2. |
| | Noise immunity | Conforms to IEC 61000-4-4, 2 kV (power line). |
| | Overvoltage category | Category: Conforms to JIS B3502 and IEC 61131-2. |
| | EMC immunity level | Zone B |
| | Vibration resistance | Conforms to IEC 60068-2-6. 5 to 8.4 Hz with amplitude of 3.5 mm, 8.4 to 150 Hz, acceleration of 9.8 m/s² 100 min each in X, Y, and Z directions (10 sweeps of 10 min each = 100 min total) |
| | Shock resistance | Conforms to IEC 60068-2-27. 147 m/s², 3 times each in X, Y, and Z directions |
| Applicable sta | andards * | UL 61010-2-201, ANSI/ISA 12.12.01, EU: EN 61131-2, RCM, KC, and IO-Link conformance |

^{*} Refer to the OMRON website (www.ia.omron.com) or ask your OMRON representative for the most recent applicable standards for each model.

NX-ILM400

Function Specification

| lte | em | Specification | | | |
|---------------------------------------|--------------------------------------|---|--|--|--|
| Unit name | /*** | IO-Link Master Unit | | | |
| Model | | NX-ILM400 | | | |
| Number of ports | | 4 | | | |
| Trainbor or porto | Communications | | | | |
| | protocol | IO-Link protocol | | | |
| Communications specifications | Baud rate | COM1: 4.8kbps COM2: 38.4kbps COM3: 230.4kbps | | | |
| · | Topology | 1:1 | | | |
| | Compliant standards | IO-Link Interface and System Specification Version1.1.2 IO-Link Test Specification Version1.1.2 | | | |
| Power supply to | Rated voltage | 24 VDC (20.4 to 28.8 VDC) | | | |
| devices* in IO-Link Mode | Maximum load current | 0.2 A/port | | | |
| or SIO (DI) Mode | Short-circuit protection | Provided. | | | |
| | Internal I/O common | PNP | | | |
| | Rated voltage | 24 VDC (20.4 to 28.8 VDC) | | | |
| Digital inputs (in SIO (DI) Mode) | Input current | 5 mA typical (24 VDC) | | | |
| | ON voltage/ON current | 15 VDC min., 2 mA min. | | | |
| | OFF voltage | 5 VDC max. | | | |
| | Input filter time | No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms | | | |
| | Internal I/O common | PNP | | | |
| | Output type | Push-pull | | | |
| Dinital autouta | Rated voltage | 24 VDC (20.4 to 28.8 VDC) | | | |
| Digital outputs (in SIO (DO) Mode) | Maximum load current | 0.1 A/port | | | |
| | Short-circuit protection | Provided. | | | |
| | Leakage current | 0.1 mA max. | | | |
| | Residual voltage | 1.5 V max. | | | |
| | Internal I/O common | PNP | | | |
| | Rated voltage | 24 VDC (20.4 to 28.8 VDC) | | | |
| Digital inputs for pin 2 | Input current | 2 mA typical (24 VDC) | | | |
| (in IO-Link Mode) | ON voltage/ON current | 15 VDC min., 2 mA min. | | | |
| | OFF voltage | 5 VDC max. | | | |
| | Input filter time | No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, 256 ms | | | |
| | Cable type | Unshielded | | | |
| 2 | Length | 20 m max. | | | |
| Cable specifications | Electrostatic capacity between lines | 3 nF max. | | | |
| | Loop resistance | 6Ω max. | | | |
| External connection term | inals | Screwless Clamping Terminal Block (16 terminals) | | | |
| I/O refreshing method | | Free-Run refreshing | | | |
| Dimensions | | 12 × 100 × 71 mm (W×H×D) | | | |
| Isolation method | | Photocoupler isolation | | | |
| Insulation resistance | | 20 MΩ min. at 100 VDC (between isolated circuits) | | | |
| Dielectric strength | | 510 VAC for 1 min, leakage current: 5 mA max. (between isolated circuits) | | | |
| NX Unit power consumpt | | Supply from the NX bus Connected to a CPU Unit 1.05 W max. Connected to a Communications Coupler Unit 0.80 W max. | | | |
| Current consumption from | m I/O power supply | 50 mA | | | |
| Weight | | 67 g | | | |
| | | ·· 8 | | | |



NX-ILM400

Function Specifications

| Fu | ınction | Description | | |
|---|-----------------------------|--|--|--|
| | Cyclic communications | I/O data (process data) in the IO-Link devices is cyclically shared with the IO-Link Master Unit as the IO-Link communications master. At the same time, this data and the status of the IO-Link Master Unit is cyclically shared with the host communications master, with the IO-Link Master Unit operating as a slave of the controller. Cyclic communications can be used to check the amount of detection performance deterioration in devices, and to check changes in usage conditions, such as the amount of incident light for photoelectric sensors, stability detection margins, and excessive proximity for proximity sensors. | | |
| Communications | Message communications | The controller can send messages (commands) to the IO-Link Master Unit and receive the response from the IO-Link Master Unit. The IO-Link Master Unit can also function as a gateway to send messages (commands and responses) between the controller and the IO-Link devices. During operation, you can change and adjust device parameters, such as threshold settings, tuning execution, and ON-delay time changes, from a program. Or, during operation, you can check the internal status, such as the operating times of devices. | | |
| Communications mode | settings | You can select any of the following modes for each port: IO-Link Mode, SIO (DI) Mode, SIO (DO) Mode, or Disable Port This allows you to combine IO-Link communications and digital I/O in a single terminal or unit. | | |
| Digital inputs for pin 2 | | In IO-Link Mode, you can perform digital input with pin 2 while performing IO-Link communications. | | |
| Automatic baud rate se communications | tting for IO-Link | The IO-Link Master Unit automatically matches the specific baud rates (COM1, COM2, or COM3) of the IO-Link devices to communicate with the IO-Link devices. Therefore, it is not necessary to set the baud rate of the connected device for each port. | | |
| Connected device verif | ication | This function is used to verify the configuration of IO-Link devices that are connected to the IO-Link Master Unit against the registered IO-Link device configuration settings when the power supply is turned ON. The user can enable or disable connected device verification. | | |
| IO-Link communication | s error detection | This function detects IO-Link cable breaks, disconnections from IO-Link device ports, error-level device events, device configuration verification errors, and IO-Link device malfunctions. | | |
| Detection of short-circu | uits in I/O cables | This function detects short-circuits in I/O cables | | |
| Notification of input dat | ta validity | The controller can use the Input Data Enabled Flags to determine whether input data * is valid. | | |
| Load rejection for contr | roller communications error | This function turns OFF outputs from the IO-Link Master Unit when an error occurs in communications with the controller in IO-Link Mode or in an SIO mode. This prevents output operations with incorrect values from host communications. | | |
| Reading IO-Link total communications retries | | The IO-Link total communications retries can be read from the CX-ConfiguratorFDT. You can use this function to determine communications status as affected by I/O communications noise or other factors. | | |
| Digital input filter | | You can set a filter processing time interval for digital inputs in SIO (DI) Mode or for digital inputs for pin 2 in IO-Link Mode. This lets you eliminate data corruption that can result from noise or switch chattering. This function can also be used to implement an ON delay and an OFF delay. | | |
| Backup and restoration of parameter settings in IO-Link devices | | This function is used to back up parameter settings in IO-Link devices in the IO-Link Master Unit or restore them to IO-Link devices. This eliminates the need to set parameters again after replacing an IO-Link device. | | |
| Event log | | The event log records events (including errors) that occur in the IO-Link Master Unit and the IO-Link devices. This enables partial troubleshooting for NJ/NX-series Controllers and NY-series Industrial PCs. | | |

^{*} The input data includes IO-Link input data in IO-Link communications, the digital input data that is input with pin 2, and digital input data in SIO (DI) Mode.

Version Information

Connecting with CPU Units

Refer to the user's manual for the CPU Unit for the CPU Unit to which NX Units can be connected.

| NX | Unit | Corresponding versions * | | | |
|-----------|--------------|--------------------------|---------------------|-------------------|--|
| Model | Unit version | CPU Unit | CX-Configurator FDT | | |
| NX-ILM400 | Ver.1.0 | Ver.1.13 or later | Ver.1.17 or higher | Ver.2.3 or higher | |

^{*} Some Units do not have all of the versions given in the above table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.

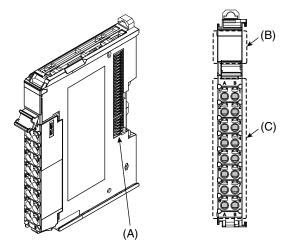
Connecting with Coupler Units

| NX U | nit | Corresponding versions * | | | | | | |
|-----------|-----------------|--------------------------------|---|--------------------|------------------------|--------------------------------|--------------------|------------------------|
| NA U | ını | EtherCAT | | | | EtherNet/IP | | |
| Model | Unit version | Communications Coupler Unit | NJ/NX-series CPU Units or NY-series Industrial PCs | Sysmac Studio | CX-Configurator FDT | Communications Coupler Unit | Sysmac Studio | CX-Configurator FDT |
| NX-ILM400 | Ver.1.0 | Ver.1.0 or later | Ver.1.12 or later | Ver.1.16 or higher | Ver.2.2 or higher | Ver.1.0 or later | Ver.1.16 or higher | Ver.2.2 or higher |

^{*} Some Units do not have all of the versions given in the above table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.

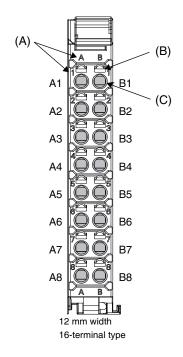
External Interface

NXILM-400



| Letter | Name | Function | | | |
|--------|------------------|--|--|--|--|
| (A) | NX bus connector | This connector is used to connect each Unit. | | | |
| (B) | Indicators | The indicators show the current operating status of the Unit. | | | |
| (C) | Terminal block | The terminal block is used to connect external devices. The number of terminals depends on the type of Unit. | | | |

Terminal Blocks



| Letter | Name | Function |
|--------|-----------------------------|--|
| (A) | Terminal number indications | Terminal numbers for which A and B indicate the column, and 1 to 8 indicate the line are displayed. The terminal number is a combination of column and line, i.e. A1 to A8 and B1 to B8. The terminal number indications are the same regardless of the number of terminals on the terminal block. |
| (B) | Release holes | Insert a flat-blade screwdriver into these holes to connect and remove the wires. |
| (C) | Terminal holes | The wires are inserted into these holes. |

Applicable Terminal Blocks for Each Unit Model

| | Terminal Blocks | | | | | |
|------------|-----------------|------------------|-----------------------------|----------------------|---------------------------|--|
| Unit model | Model | No. of terminals | Terminal number indications | Ground terminal mark | Terminal current capacity | |
| NX-ILM400 | NX-TBA162 | 16 | A/B | Not provided | 10A | |

Applicable Wires

Using Ferrules

If you use ferrules, attach the twisted wires to them.

Observe the application instructions for your ferrules for the wire stripping length when attaching ferrules.

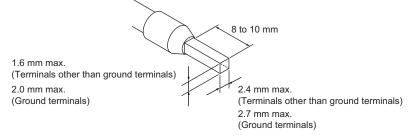
Always use plated one-pin ferrules. Do not use unplated ferrules or two-pin ferrules.

The applicable ferrules, wires, and crimping tool are given in the following table.

| Terminal types | Manufacturer | Ferrule model | Applicable wire (mm² (AWG)) | Crimping tool |
|---------------------|--------------|---------------|-----------------------------|--|
| Terminals other | Phoenix | AI0,34-8 | 0.34 (#22) | Phoenix Contact (The figure in parentheses is the applicable wire |
| than ground | Contact | AI0,5-8 | 0.5 (#20) | size.) |
| terminals | | AI0,5-10 | | CRIMPFOX 6 (0.25 to 6 mm ² , AWG 24 to 10) |
| | | AI0,75-8 | 0.75 (#18) | |
| | | AI0,75-10 | | |
| | | Al1,0-8 | 1.0 (#18) | |
| | | Al1,0-10 | | |
| | | Al1,5-8 | 1.5 (#16) | 1 |
| | | Al1,5-10 | | |
| Ground terminals | 1 | Al2,5-10 | 2.0 *1 | |
| Terminals other | Weidmuller | H0.14/12 | 0.14 (#26) | Weidmueller (The figure in parentheses is the applicable wire size.) |
| than ground | | H0.25/12 | 0.25 (#24) | PZ6 Roto (0.14 to 6 mm ² , AWG 26 to 10) |
| terminals | | H0.34/12 | 0.34 (#22) | |
| | | H0.5/14 | 0.5 (#20) | 1 |
| | | H0.5/16 | | |
| | | H0.75/14 | 0.75 (#18) | |
| | | H0.75/16 | | |
| | | H1.0/14 | 1.0 (#18) | 1 |
| | | H1.0/16 | | |
| | | H1.5/14 | 1.5 (#16) | |
| | | H1.5/16 | 1 ' ' | |

^{*1.} Some AWG 14 wires exceed 2.0 mm² and cannot be used in the screwless clamping terminal block.

When you use any ferrules other than those in the above table, crimp them to the twisted wires so that the following processed dimensions are achieved.



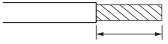
Using Twisted Wires/Solid Wires

If you use the twisted wires or the solid wires, use the following table to determine the correct wire specifications.

| Terminals | | | Wire | type | | | 0 | |
|---------------------------------------|-------------------------------------|----------------|----------|-----------------|----------------|--|-------------------------------------|--|
| | | Twisted wires | | Solid wire | | Wire size | Conductor length (stripping length) | |
| Classification | Current capacity | Plated | Unplated | Plated | Unplated | | (ourphing length) | |
| | 2 A max. | | Possible | Possible | Possible | | | |
| All terminals except ground terminals | Greater than 2 A and 4 A or less | Possible | e Not | Possible *1 | Not | 0.08 to 1.5 mm ² AWG28 to 16 | 8 to 10 mm | |
| | Greater than 4 A | Possible *1 | Possible | Not Possible | Possible | 7,117,020 to 10 | | |
| Ground terminals | | Possible | Possible | Possible *2 | Possible *2 | 2.0 mm ² | 9 to 10 mm | |

^{*1.} Secure wires to the screwless clamping terminal block. Refer to the Securing Wires in the USER'S MANUAL for how to secure wires.

^{*2.} With the NX-TB□□□1 Terminal Block, use twisted wires to connect the ground terminal. Do not use a solid wire.

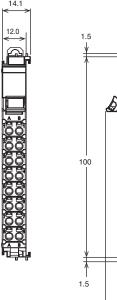


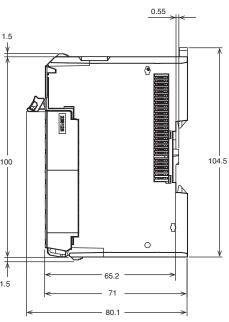
Conductor length (stripping length)

< Additional Information > If more than 2 A will flow on the wires, use plated wires or use ferrules.

Dimensions (Unit: mm)

NX-ILM400 12 mm Width





NX-ILM400

Related Manuals

| Man.No | Model | Manual | Application | Description |
|--------|--|--|--|--|
| W567 | NX-ILM400 | IO-Link Master Unit User's Manual | Learning hardware information, wiring, and specifications for the NX-series IO-Link Master Unit and checking a list of NX objects. | Describes detailed part specifications, installation, and wiring and also provides tables of specifications and NX objects for the NX-series IO-Link Master Unit. |
| W570 | NX-ILM400 GX-ILM08C | IO-Link System User's Manual | Learning everything from an introduction to details about IO-Link Systems, including mainly software information common to all IO-Link masters, Support Software operating methods, and troubleshooting. | Provides an overview of IO-Link Systems and explains the system configuration, communications specifications, communications methods, I/O data, parameters, models, Support Software, and troubleshooting. Refer to the following manuals for the individual IO-Link Master Units for hardware information and specifications specific to each Master Unit and a list of the objects for each Master Unit. NX-series IO-Link Master Unit: W568 GX-series IO-Link Master Unit: W488-E1-05 or later |
| W488 | GX-ID | EtherCAT Slave Units User's Manual | Learning hardware information on the GX-series IO-Link Master Unit and checking a list of objects (W488-E1-05 or later). Or, learning how to use GX-series EtherCAT Slave Terminals. | Describes part names, functions, installation, and wiring and also provides tables of specifications and objects for the GX-series IO-Link Master Unit (W488-E1-05 or later). Also describes the hardware, setup methods, and functions of the EtherCAT Remote I/O Terminals. |
| W502 | NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□ | NJ/NX-series Instructions Reference Manual | Learning detailed specifications on the basic instructions of an NJ/NXseries CPU Unit. | The instructions in the instruction set (IEC 61131-3 specifications) are described. When programming, use this manual together with the <i>NX-series CPU Unit Hardware User's Manual</i> (Cat. No. W535) or <i>NJ-series CPU Unit Hardware User's Manual</i> (Cat. No. W500) and <i>NJ/NX-series CPU Unit Software User's Manual</i> (Cat. No. W501). |
| W505 | NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□ NX1P2-□□□□ | NJ/NX-series CPU Unit Built-in EtherCAT® Port User's Manual | Using the built-in EtherCAT port on an NJ/NX-series CPU Unit. | Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup. |
| W503 | NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□ NX1P2-□□□□ | NJ/NX-series Troubleshooting Manual | Learning about the errors that may be detected in an NJ/NX-series Controller. | Concepts on managing errors that may be detected in an NJ/NX-series Controller and information on individual errors are described. |
| W525 | NX- 🗆 🗆 🗆 🗆 | NX-series Data Reference Manual | Referencing lists of the data that is required to configure systems with NX-series Units | Lists of the power consumptions, weights, and other NX Unit data that is required to configure systems with NX-series Units are provided. |
| W519 | NX-ECC | NX-series EtherCAT® Coupler Unit User's Manual | Learning how to use an NX-series EtherCAT Coupler Unit and EtherCAT Slave Terminals | The system and configuration of EtherCAT Slave Terminals, which consist of an NX-series EtherCAT Coupler Unit and NX Units, are described along with the hardware, setup, and functions of the EtherCAT Coupler Unit that are required to configure, control, and monitor NX Units through EtherCAT. |
| W504 | SYSMAC-SE2□□□ | Sysmac Studio Version 1 Operation Manual | Learning about the operating procedures and functions of the Sysmac Studio. | Describes the operating procedures of the Sysmac Studio. |
| W562 | NY532-1 □ □ □ NY512-1 □ □ □ | NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in Ether-CAT® Port User's Manual | Using the built-in EtherCAT port in an NY-series Industrial PC. | Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup. |
| W560 | NY532-1□□□ NY512-1□□□ | NY-series Instructions Reference Manual | Learning detailed specifications on the basic instructions of an NY-series Industrial PC. | The instructions in the instruction set (IEC 61131-3 specifications) are described. |

Note: Refer to the instructions for the individual Sensors for information on IO-Link Sensors.

GX-series IO-Link Master Unit

GX-ILM08C

IO-Link makes sensor level information visible and solves the three major issues at manufacturing sites!

The unit for M12 Smartclick connector can be used in watery, and dusty environments.



- Downtime can be reduced.
 Notifies you of faulty parts and such phenomena in the Sensor in real time.
- The frequency of sudden failure can be decreased.
 Condition monitoring of sensors and equipment to prevent troubles.
- The efficiency of changeover can be improved.
 The batch check for individual sensor IDs significantly decreases commissioning time.

Features

- The host controller can cyclically read control signals, status*1, wiring, and power supply status of IO-Link sensors. Because an IO-Link System can cyclically read analog data such as the amount of incident light in addition to ON/OFF information, it can be used for predictive maintenance based on detection of such things as decreases in the amount of light.
- · User-specified data in IO-Link devices can be read and written from the host controller when necessary.
- Digital signals can be input rapidly from IO-Link sensors*2 during IO-Link communications.
- IO-Link sensors can be combined with non-IO-Link sensors.
- Incorrect connections of IO-Link sensors can be checked when IO-Link communications start.
- · Backup and restoration of IO-Link device parameters*3 make replacement of IO-Link sensors easier.
- Sensors can report their errors to the master, which facilitates locating errors from the host.
- The total number of retries in cyclic communications can be recorded. You can use this value to check for the influences of noise and other problems.
 - (When EtherCAT is used as the host communication interface) *3
- Up to eight sensors can be connected. IP67 protection.
- *1. Examples for Photoelectric Sensors: Instability detection and sensor errors
- *2. IO-Link sensors that support digital inputs that use pin 2 of IO-Link Master Unit ports
- *3. When the Omron IO-Link master unit is used

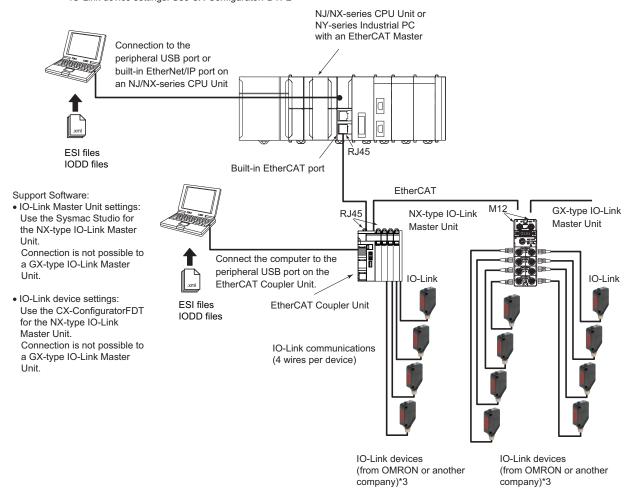
Sysmac is a trademark or registered trademark of OMRON Corporation in Japan and other countries for OMRON factory automation products. EtherCAT® is a registered trademark of Beckhoff Automation GmbH for their patented technology. EtherNet/IPTM is the trademarks of ODVA.

Other company names and product names in this document are the trademarks or registered trademarks of their respective companies.

System Configuration



- IO-Link Master Unit settings: Use the Sysmac Studio.*1
- IO-Link device settings: Use CX-ConfiguratorFDT.*2



- *1. When a host controller from another company is used with EtherCAT host communications, use the EtherCAT software application from the other company for a GX-type IO-Link Master Unit.
- Note. For an NX-type IO-Link Master Unit, connect the Sysmac Studio to the EtherCAT Coupler Unit, as shown above.
- *2. When a host controller from another company is used with EtherCAT host communications, for a GX-type IO-Link Master Unit, make the IO-Link device settings with message communications from the host controller from the other company.

Note. For an NX-type IO-Link Master Unit, connect CX-ConfiguratorFDT to the EtherCAT Coupler Unit, as shown above.

*3. You can also connect a combination of general-purpose sensors and other devices.

Ordering Information

International Standards

- The standards are abbreviated as follows: U: UL, U1: UL(Class I Division 2 Products for Hazardous Locations), C: CSA, UC: cULus, UC1: cULus (Class I Division 2 Products for Hazardous Locations), CU: cUL, N: NK, L: Lloyd, CE: EU Directives, RCM: RCM mark, and KC: KC Registration.
- Contact your OMRON representative for further details and applicable conditions for these standards.

EtherCAT Slave Terminals IO-Link Master Unit

| | | Specif | | | |
|-------------------------------|--------------------------|----------------------------|-----------------------------------|------------------------------|-------------|
| Product Name | Environmental resistance | Number of IO-Link ports | I/O connection terminals | O connection terminals Model | |
| GX-series IO-Link Master Unit | IP67 | 8 | M12 connector (A-cording, female) | GX-ILM08C | CE, RCM, KC |

Peripheral Devices

Recommended EtherCAT Communications Cables

Use Straight STP (shielded twisted-pair) cable of category 5 or higher with double shielding (braiding and aluminum foil tape) for EtherCAT.

| Item | Appearance | Recommended manufacturer | Cable length (m) | Model |
|---|-----------------------------|--------------------------|------------------|------------------|
| | Smartclick | | 0.5 | XS5W-T421-BM2-SS |
| Salata saidh Cannasadana an Balla Forda | (M12 Straight/M12 straight) | | 1 | XS5W-T421-CM2-SS |
| Cable with Connectors on Both Ends Chield Strengthening cable | | OMRON | 2 | XS5W-T421-DM2-SS |
| Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black | NEW NEW | OMHON | 3 | XS5W-T421-EM2-SS |
| | | | 5 | XS5W-T421-GM2-SS |
| | | | 10 | XS5W-T421-JM2-SS |
| | Smartclick | OMBON | 0.5 | XS5W-T421-BMC-SS |
| able with Connectors on Both Ends | 0 | | 1 | XS5W-T421-CMC-SS |
| ugged type | | | 2 | XS5W-T421-DMC-SS |
| Shield Strengthening cable Wire Gauge and Number of Pairs: AWG22, 2-pair Cable Cable color: Black | | OMRON | 3 | XS5W-T421-EMC-SS |
| | | | 5 | XS5W-T421-GMC-SS |
| | <u>NEW</u> | | 10 | XS5W-T421-JMC-SS |

Note: For details, Contact your OMRON representative.

Power Supply Cables

| Item | Appearance | Recommended manufacturer | Cable length (m) | Model |
|---|---|--------------------------|------------------|-----------------|
| | | | 1 | XS5F-D421-C80-F |
| Connector connected to cable, socket on one cable end Fire-retardant, Robot cable | | | 2 | XS5F-D421-D80-F |
| | Smartclick (M12 Straight) | OMRON | 3 | XS5F-D421-E80-F |
| | | | 5 | XS5F-D421-G80-F |
| | | | 10 | XS5F-D421-J80-F |
| | Smartclick (M12 Straight/M12 straight) | | 1 | XS5W-D421-C81-F |
| Connectors connected to cable. | | | 2 | XS5W-D421-D81-F |
| socket and plug on cable ends Fire-retardant, Robot cable | | OMRON | 3 | XS5W-D421-E81-F |
| | | | 5 | XS5W-D421-G81-F |
| | | | 10 | XS5W-D421-J81-F |

Note: Refer to the Round Water-resistant Connectors in the category of Sensor I/O Connector/Sensor Controller on your local OMRON website for details.

Sensor I/O Connectors

Order a cable with a connector on both ends to connect a sensor.

| Item | Appearance | Recommended manufacturer | Cable length (m) | Model |
|---|--|--------------------------|------------------|-----------------|
| Connectors connected to cable, M8 socket and M12 plug on cable ends Fire-retardant, Robot cable | M8 screw- M12 Smartclick (M8 Straight/M12 straight) | OMRON | 0.2 | XS3W-M42C-4C2-A |
| | Smartclick (M12 Straight/M12 straight) | OMRON | 1 | XS5W-D421-C81-F |
| Connectors connected to cable, | | | 2 | XS5W-D421-D81-F |
| socket and plug on cable ends Fire-retardant, Robot cable | | | 3 | XS5W-D421-E81-F |
| | | | 5 | XS5W-D421-G81-F |
| | | | 10 | XS5W-D421-J81-F |

Note: Refer to the Ordering Information in the catalog of the sensor to connect or the Sensor I/O Connectors/Sensor Controllers on your local OMRON website for details.

Power Supply T-Joint Connector

This connector is used when branching a GX-type Unit power supply.

| Item | Appearance | Specification | Connector type | Model |
|---------------------------------------|------------|---------------|----------------------|-------------|
| XS5R Plug/Socket T-Joint Connector | | M12 | Smartclick connector | XS5R-D427-5 |

Waterproof Cover for Connectors

This is a waterproof cover for unused M12 GX connectors (female).

When you use this waterproof cover, you can maintain the IP67 protective structure.

The following two types of covers are available. Either one can be mounted on an EtherCAT communications connector or I/O connector.

| Item | Appearance | Specification | Connector type | Materials | Model |
|-------------------------------------|------------|---------------|-------------------------|------------------------|---------|
| M12 Threaded Waterproof Cover *1 | | M12 | Screw-type connector | Brass/nickel plated | XS2Z-22 |
| Smartclick Waterproof Cover *2 | | M12 | Smartclick connector | PBT | XS5Z-11 |

^{*1.} When mounting the M12 Threaded Waterproof Cover on a connector, always tighten it to a torque of 0.39 to 0.49 N·m.

Tool for M12 Threaded Connectors

The tool for tightening M12 Threaded Connectors is used when tightening to a specified torque.

| Item | Appearance | Model |
|---------------|------------|-----------|
| Torque Wrench | | XY2F-0004 |

Software

Automation Software Sysmac Studio

Please purchase a DVD and required number of licenses the first time you purchase the Sysmac Studio. DVDs and licenses are available individually. Each model of licenses does not include any DVD.

| | Specification | | | | |
|---------------|---|--------------------------|-----|---------------|-----------|
| Product name | | Number of licenses Media | | Model | Standards |
| Sysmac Studio | indard Edition Windows 7(32-bit/64-bit version)/Windows | | DVD | SYSMAC-SE200D | |
| Ver.1.□□ | | | | SYSMAC-SE201L | |

^{*} Multi licenses are available for the Sysmac Studio (3, 10, 30, or 50 licenses).

^{*2.} When mounting a Smartclick Waterproof Cover on a connector, torque management is not required.

General Specification

| Item | Specification | | | |
|-----------------------------------|--|--|--|--|
| Unit power supply voltage | 20.4 to 26.4 VDC (24 VDC –15%/+10%) | | | |
| I/O power supply | 20.4 to 26.4 VDC (24 VDC –15%/+10%) | | | |
| Noise resistance | onforms to IEC 61000-4-4, 2 kV (power line). | | | |
| Vibration resistance | Malfunction: 10 to 60 Hz with amplitude of 0.7 mm, 60 to 150 Hz and 50 m/s 2 for 80 minutes each in X, Y, and Z direction | | | |
| Shock resistance | 150 m/s ² with amplitude of 0.7 mm | | | |
| Dielectric strength | 600 VAC (between isolated circuits) | | | |
| Insulation resistance | 20 M $Ω$ min. (between isolated circuits) | | | |
| Ambient operating temperature | −10 to 55°C | | | |
| Ambient operating humidity | 25% to 85% (with no condensation) | | | |
| Ambient operating atmosphere | No corrosive gases | | | |
| Altitude | 2,000 m max. | | | |
| Storage temperature | −25 to 65°C | | | |
| Storage humidity | 25% to 85% (with no condensation) | | | |
| Degree of protection | IP67 | | | |
| Mounting | M5 screw mounting | | | |
| Mounting strength | 100 N | | | |
| Communications connector strength | 30 N | | | |
| Connector types | Connectors for EtherCAT communications: M12 (D-coding, female) × 2 Power supply connector: M12 (A-coding, male) × 1 I/O connectors: M12 (A-coding, female)*1 × 8 | | | |
| Screw tightening torque *2 | Round connectors (communications connector, power supply, and I/O): 0.39 to 0.49 N·m M5 (Unit mounted from the front):1.47 to 1.96 N·m Cover for node address setting switches: 0.4 to 0.6 N·m | | | |
| Applicable standards *3 | EU: EN 61131-2, RCM, KC, IO-Link conformance, and EtherCAT conformance | | | |

^{*1.} Confirms to Class A when used as an IO-Link connector.
*2. For SmartClick Connectors, insert the Connector all the way and turn it approx. 1/8 of a turn. Torque management is not required.
*3. Refer to the OMRON website (www.ia.omron.com) or ask your OMRON representative for the most recent applicable standards for each

GX-ILM08C

Function Specification

| 14 | em | Specification | | | | |
|--|---------------------------------------|--|--|--|--|--|
| | em | Specification | | | | |
| Unit name | | IO-Link Master Unit | | | | |
| Model | | GX-ILM08C | | | | |
| Number of IO-Link ports | | 8 | | | | |
| | Communications protocol | IO-Link protocol | | | | |
| Communications | Baud rate | COM1: 4.8 kbps COM2: 38.4 kbps | | | | |
| specifications | | COM3: 230.4 kbps | | | | |
| | Topology | 1:1 | | | | |
| | Compliant standards | IO-Link Interface and System Specification Version1.1.2 IO-Link Test Specification Version1.1.2 | | | | |
| Device power supply* in | Rated voltage | 24 VDC (20.4 to 26.4 VDC) | | | | |
| IO-Link Mode or SIO (DI) Mode | Maximum load current | 0.2 A/port | | | | |
| Wode | Short-circuit protection | Yes | | | | |
| | Internal I/O common | PNP | | | | |
| | Rated voltage | 24 VDC (20.4 to 26.4 VDC) | | | | |
| Digital inputs | Input current | 5 mA typical (at 24 VDC) | | | | |
| (in SIO (DI) Mode) | ON voltage/ON current | 15 VDC min., 5 mA min. | | | | |
| | OFF voltage | 5 VDC max. | | | | |
| | Input filter time | No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, or 256 ms | | | | |
| | Internal I/O common | PNP | | | | |
| | Output type | Push-pull | | | | |
| | Rated voltage | 24 VDC (20.4 to 26.4 VDC) | | | | |
| Digital outputs | Maximum load current | 0.3 A/port | | | | |
| (in SIO (DIO) Mode) | Short-circuit protection | Provided. | | | | |
| | Leakage current | 0.1 mA max. | | | | |
| | Residual voltage | 1.5 V max. | | | | |
| | Internal I/O common | PNP | | | | |
| | Rated voltage | 24 VDC (20.4 to 26.4 VDC) | | | | |
| Digital inputs for pin 2 (in IO-Link Mode) | Input current | 2 mA (24 VDC) | | | | |
| | ON voltage/ON current | 15 VDC min., 2 mA min. | | | | |
| | OFF voltage | 5 VDC max. | | | | |
| | Input filter time | No filter, 0.25 ms, 0.5 ms, 1 ms (default), 2 ms, 4 ms, 8 ms, 16 ms, 32 ms, 64 ms, 128 ms, or 256 ms | | | | |
| | Cable type | Unshielded Unshielded | | | | |
| | Cable length | 20 m max. | | | | |
| Cable specifications | Electrostatic capacity | 20 III IIIdx. | | | | |
| | between lines | 3 nF max. | | | | |
| | Loop resistance | 6 Ω max. | | | | |
| Dimensions | 1 | 175 × 33 × 60 mm (W×H×D) (The height is 49.1 mm when the connectors are included.) | | | | |
| Isolation method | | Photocoupler isolation | | | | |
| I/O power supply method | | Supplied from the power supply connector. | | | | |
| Unit power supply current c | onsumption | 60 mA | | | | |
| I/O power supply current co | · · · · · · · · · · · · · · · · · · · | 100 mA | | | | |
| Weight | | 430 g | | | | |
| Circuit layout | | Internal connector OUT communications connector OUT communications connector Unit power supply Unit power supply Unit power supply connector Power supply connector Internal circuits circuit IO-LINK circuits IO-LINK circuits IO-LINK circuits I/O power supply circuits I/O power supply 24 V I/O power supply 24 V I/O power supply 0 V | | | | |
| Installation orientation and r | restrictions | Installation orientation: 6 possible orientations Restrictions: No restrictions | | | | |
| Protective functions | | Load short-circuit protection | | | | |
| | | · ' | | | | |

Function Specifications

| F | unction | Description | | |
|---|-----------------------------|--|--|--|
| O-manusia stina | Cyclic communications | I/O data (process data) in the IO-Link devices is cyclically shared with the IO-Link Master Unit as the IO-Link communications master. At the same time, this data and the status of the IO-Link Master Unit is cyclically shared with the host communications master, with the IO-Link Master Unit operating as a slave of the controller. Cyclic communications can be used to check the amount of detection performance deterioration in devices, and to check changes in usage conditions, such as the amount of incident light for photoelectric sensors, stability detection margins, and excessive proximity for proximity sensors. | | |
| Communications | Message communications | The controller can send messages (commands) to the IO-Link Master Unit and receive the response from the IO-Link Master Unit. The IO-Link Master Unit can also function as a gateway to send messages (commands and responses) between the controller and the IO-Link devices. During operation, you can change and adjust device parameters, such as threshold settings, tuning execution, and ON-delay time changes, from a program. Or, during operation, you can check the internal status, such as the operating times of devices. | | |
| Communications mode | e settings | You can select any of the following modes for each port: IO-Link Mode, SIO (DI) Mode, SIO (DO) Mode, or Disable Port This allows you to combine IO-Link communications and digital I/O in a single terminal or unit. | | |
| Digital inputs for pin 2 | | In IO-Link Mode, you can perform digital input with pin 2 while performing IO-Link communications. | | |
| Automatic baud rate se communications | etting for IO-Link | The IO-Link Master Unit automatically matches the specific baud rates (COM1, COM2, or COM3) of the IO-Link devices to communicate with the IO-Link devices. Therefore, it is not necessary to set the baud rate of the connected device for each port. | | |
| Connected device verif | fication | This function is used to verify the configuration of IO-Link devices that are connected to the IO-Link Maste Unit against the registered IO-Link device configuration settings when the power supply is turned ON. The user can enable or disable connected device verification. | | |
| IO-Link communication | ns error detection | This function detects IO-Link cable breaks, disconnections from IO-Link device ports, error-level device events, device configuration verification errors, and IO-Link device malfunctions. | | |
| Detection of short-circ | uits in I/O cables | This function detects short-circuits in I/O cables | | |
| Notification of input da | ta validity | The controller can use the Input Data Enabled Flags to determine whether input data * is valid. | | |
| Load rejection for cont | roller communications error | This function turns OFF outputs from the IO-Link Master Unit when an error occurs in communications with the controller in IO-Link Mode or in an SIO mode. This prevents output operations with incorrect values from host communications. | | |
| Reading IO-Link total of | communications retries | The IO-Link total communications retries can be read from the CX-ConfiguratorFDT. You can use this function to determine communications status as affected by I/O communications noise or other factors. | | |
| Digital input filter | | You can set a filter processing time interval for digital inputs in SIO (DI) Mode or for digital inputs for pin 2 in IO-Link Mode. This lets you eliminate data corruption that can result from noise or switch chattering. This function can also be used to implement an ON delay and an OFF delay. | | |
| Backup and restoration of parameter settings in IO-Link devices | | This function is used to back up parameter settings in IO-Link devices in the IO-Link Master Unit or restore them to IO-Link devices. This eliminates the need to set parameters again after replacing an IO-Link device. | | |
| Event log | | The event log records events (including errors) that occur in the IO-Link Master Unit and the IO-Link devices. This enables partial troubleshooting for NJ/NX-series Controllers and NY-series Industrial PCs. | | |

^{*} The input data includes IO-Link input data in IO-Link communications, the digital input data that is input with pin 2, and digital input data in SIO (DI) Mode.

GX-ILM08C

EtherCAT Communications Specifications

| Item | Specification |
|-----------------------------|---|
| Communications protocol | EtherCAT protocol |
| Modulation | Baseband |
| Baud rate | 100 Mbps |
| Physical layer | 100BASE-TX (IEEE 802.3) |
| Connectors | M12 (D-coding, female) × 2 (shielded) CN IN: EtherCAT input CN OUT: EtherCAT output |
| Communications media | Category 5 or higher (cable with double, aluminum tape and braided shielding is recommended.) |
| Communications distance | Distance between nodes (Slave Units): 100 m max. |
| Noise resistance | Conforms to IEC 61000-4-4, 1 kV or higher. |
| Node address setting method | Set on hexadecimal node address switches or with a Configuration Tool. |
| Node address range | 000 to FFF hex (0 to 4,095 decimal): Set on node address switches or with a Configuration Tool. |
| Indicators | UNIT PWR × 1 IO PWR × 1 L/A IN (Link/Activity IN) × 1 L/A OUT (Link/Activity OUT) × 1 RUN × 1 ERR × 1 |
| Process data | Variable PDO mapping |
| PDO size/node | 2 to 270 bytes |
| Mailbox | Emergency messages, SDO requests, SDO responses, and SDO information |
| Synchronization mode | Free Run Mode (asynchronous) |

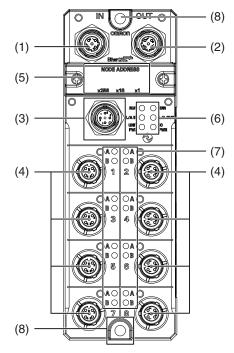
Version Information

| GV | Unit | Corresponding versions * | | | |
|--------------------|---------|--------------------------|--------------------|---------------------|--|
| GA. | Omit | EtherCAT | | | |
| Model Unit version | | CPU Units | Sysmac Studio | CX-Configurator FDT | |
| GX-ILM08C | Ver.1.0 | Ver.1.12 or later | Ver.1.16 or higher | Ver.2.2 or higher | |

^{*} Some Units do not have all of the versions given in the above table. If a Unit does not have the specified version, support is provided by the oldest available version after the specified version. Refer to the user's manuals for the specific Units for the relation between models and versions.

Component Names and Functions

GX-ILM08C

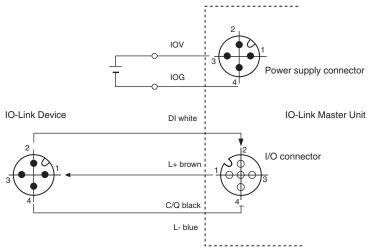


| No. | Name | Function |
|-----|--|--|
| (1) | EtherCAT communications connector, IN | EtherCAT cable connection: IN side M12 connector (D-coding, female) |
| (2) | EtherCAT communications connector, OUT | EtherCAT cable connection: OUT side M12 connector (D-coding, female) |
| (3) | Power supply connector | Connects to Unit power supply and I/O power supply cable. M12 connector (A-coding, male) |
| (4) | I/O connectors | Connect to IO-Link sensor cables (IO-Link connector type: Class A) M12 connectors (A-coding, female) |
| (5) | Node address setting switches | Used to set the EtherCAT node address. |
| (6) | Status indicators | Indicate the current status of the EtherCAT Slave Unit. (RUN, ERR, L/A IN, L/A OUT, UNIT PWR, and I/O PWR) |
| (7) | I/O indicators | Indicate the I/O status. (C/E and C/Q) |
| (8) | Mounting holes | Used to mount the Unit with M5 screws. |

GX-ILM08C

Wiring

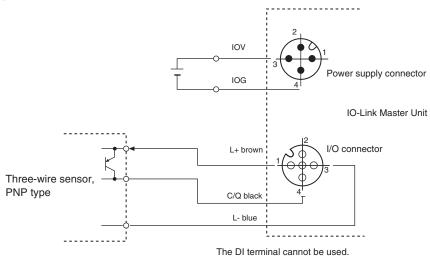
IO-Link Mode



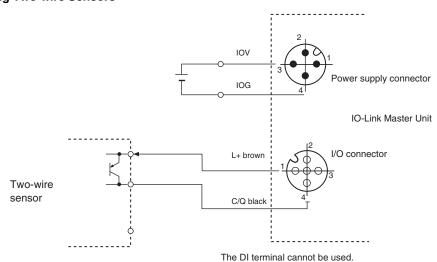
Note: Even if you connect to IO-Link devices without digital inputs for pin 2, connect pin 2 as shown in the above figure. This is because connectors on the IO-Link devices and the cable with connectors on both ends connect pin 2. However, because no data enters pin 2 of the IO-Link Master Unit, digital IO-Link input data is always OFF.

SIO (DI) Mode

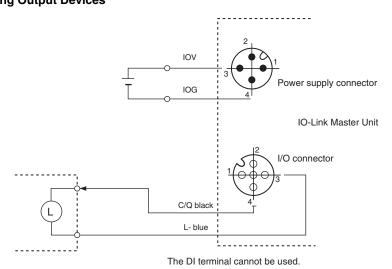
Wiring Three-wire Sensors



Wiring Two-wire Sensors

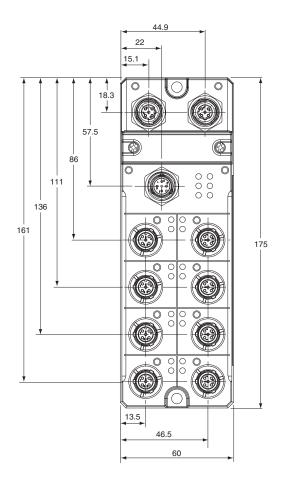


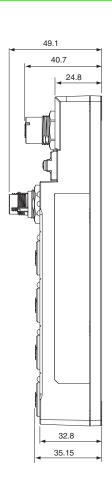
SIO (DO) Mode Wiring Output Devices

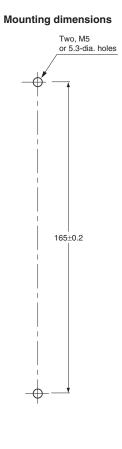


Dimensions (Unit: mm)

GX-ILM08C







GX-ILM08C

Related Manuals

| Man.No | Model | Manual | Application | Description |
|--------|--|--|--|---|
| W488 | GX-ID | EtherCAT Slave Units User's Manual | Learning hardware information on the GX-series IO-Link Master Unit and checking a list of objects. (W488-E1-05 or later). Or, learning how to use GX-series EtherCAT Slave Terminals. | Describes part names, functions, installation, and wiring and also provides tables of specifications and objects for the GX-series IO-Link Master Unit (W488-E1-05 or later). Also describes the hardware, setup methods, and functions of the EtherCAT Remote I/O Terminals. |
| W570 | NX-ILM400 GX-ILM08C | IO-Link System User's Manual | Learning everything from an introduction to details about IO-Link Systems, including mainly software information common to all IO-Link masters, Support Software operating methods, and troubleshooting. | Provides an overview of IO-Link Systems and explains the system configuration, communications specifications, communications methods, I/O data, parameters, models, Support Software, and troubleshooting. Refer to the following manuals for the individual IO-Link Master Units for hardware information and specifications specific to each Master Unit and a list of the objects for each Master Unit. NX-series IO-Link Master Unit: W568 GX-series IO-Link Master Unit: W488-E1-05 or later |
| W567 | NX-ILM400 | IO-Link Master Unit User's Manual | Learning hardware information, wiring, and specifications for the NX-series IO-Link Master Unit and checking a list of NX objects. | Describes detailed part specifications, installation, and wiring and also provides tables of specifications and NX objects for the NX-series IO-Link Master Unit. |
| W502 | NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□ | NJ/NX-series Instructions Reference Manual | Learning detailed specifications on the basic instructions of an NJ/ NXseries CPU Unit. | The instructions in the instruction set (IEC 61131-3 specifications) are described. When programming, use this manual together with the <i>NX-series CPU Unit Hardware User's Manual</i> (Cat. No. W535) or <i>NJ-series CPU Unit Hardware User's Manual</i> (Cat. No. W500) and <i>NJ/NX-series CPU Unit Software User's Manual</i> (Cat. No. W501). |
| W505 | NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□ | NJ/NX-series CPU Unit Built-in EtherCAT® Port User's Manual | Using the built-in EtherCAT port on an NJ/NX-series CPU Unit. | Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup. |
| W503 | NX701-□□□□ NJ501-□□□□ NJ301-□□□□ NJ101-□□□□ NX1P2-□□□□ | NJ/NX-series Troubleshooting Manual | Learning about the errors that may be detected in an NJ/NX-series Controller. | Concepts on managing errors that may be detected in an NJ/NX-series Controller and information on individual errors are described. |
| W519 | NX-ECC | NX-series EtherCAT® Coupler Unit User's Manual | Learning how to use an NX-series EtherCAT Coupler Unit and EtherCAT Slave Terminals. | The system and configuration of EtherCAT Slave Terminals, which consist of an NX-series EtherCAT Coupler Unit and NX Units, are described along with the hardware, setup, and functions of the EtherCAT Coupler Unit that are required to configure, control, and monitor NX Units through EtherCAT. |
| W504 | SYSMAC-SE2□□□ | Sysmac Studio Version 1 Operation Manual | Learning about the operating procedures and functions of the Sysmac Studio. | Describes the operating procedures of the Sysmac Studio. |
| W562 | NY532-1 □ □ □ NY512-1 □ □ □ | NY-series IPC Machine Controller Industrial Panel PC / Industrial Box PC Built-in Ether-CAT® Port User's Manual | Using the built-in EtherCAT port in an NY-series Industrial PC. | Information on the built-in EtherCAT port is provided. This manual provides an introduction and provides information on the configuration, features, and setup. |
| W560 | NY532-1□□□ NY512-1□□□ | NY-series Instructions Reference Manual | Learning detailed specifications on the basic instructions of an NY-series Industrial PC. | The instructions in the instruction set (IEC 61131-3 specifications) are described. |

IO-Link Photoelectric Sensor

E3Z-U-IL

IO-Link Makes Sensor Level Information Visible and Solves the Three Major Issues at Manufacturing Sites! Standard Photoelectric Sensor.

- Downtime can be reduced.
 Notifies you of faulty parts and such phenomena in the Sensor in real time.
- The frequency of sudden failure can be decreased. The light incident level monitor prevents false detection before it happens.
- The efficiency of changeover can be improved.

 The batch check for individual sensor IDs significantly decreases commissioning time.
- Three types of sensing methods and three types of connection methods are available.



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.



Be sure to read *Safety Precautions* on page 51.

Ordering Information

IO-Link Model / Sensors [Refer to Dimensions on page 52.]

| Sensing method | Appearance | Connection method | Sensing distance | IO-Link | Model |
|--|------------|-------------------------|------------------------------|----------------------|--|
| | • • | | | baud rate | PNP |
| Through-beam (Emitter + Receiver) *3 | | Pre-wired (2 m) | | | E3Z-T81-IL2 2M Emitter E3Z-T81-L-IL2 2M Receiver E3Z-T81-D-IL2 2M |
| | | Pre-wired M12 connector | | COM2 (38.4 kbps) | E3Z-T81-M1TJ-IL2 0.3M Emitter E3Z-T81-L-M1TJ-IL2 0.3M Receiver E3Z-T81-D-M1TJ-IL2 0.3M |
| | | Standard M8 connector | | | E3Z-T86-IL2 Emitter E3Z-T86-L-IL2 Receiver E3Z-T86-D-IL2 |
| | | Pre-wired (2 m) | | 1 | E3Z-T81-IL3 2M Emitter E3Z-T81-L-IL3 2M Receiver E3Z-T81-D-IL3 2M |
| | | Pre-wired M12 connector | | COM3 (230.4 kbps) | E3Z-T81-M1TJ-IL3 0.3M Emitter E3Z-T81-L-M1TJ-IL3 0.3M Receiver E3Z-T81-D-M1TJ-IL3 0.3M |
| | | Standard M8 connector | | | E3Z-T86-IL3 Emitter E3Z-T86-L-IL3 Receiver E3Z-T86-D-IL3 |
| | | Pre-wired (2 m) | | | E3Z-R81-IL2 2M |
| | *1 | Pre-wired M12 connector | *2 | COM2 (38.4 kbps) | E3Z-R81-M1TJ-IL2 0.3M |
| Retro-reflective with | ្រា 🔊 | Standard M8 connector | 4 m | (30.4 KDPS) | E3Z-R86-IL2 |
| MSR function | | Pre-wired (2 m) | (100 mm) When using E39-R1S) | 00140 | E3Z-R81-IL3 2M |
| | * | Pre-wired M12 connector | vinen using Ess-F15) | COM3 (230.4 kbps) | E3Z-R81-M1TJ-IL3 0.3M |
| | | Standard M8 connector | | (230.4 KDPS) | E3Z-R86-IL3 |

Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

- 1. The Reflector is sold separately. Select the Reflector model most suited to the application.
- *2. The sensing distance specified is possible when the E39-R1S is used. Values in parentheses indicate the minimum required distance between the Sensor and Reflector.
- *3. Through-beam Sensors are normally sold in sets that include both the Emitter and Receiver.

| | | | | | | | Red light Infrared light |
|--------------------|------------|-------------------------|-------|------------------|----------------------|----------------------|--------------------------|
| Sensing method | Appearance | Connection method | Sone | Sensing distance | | IO-Link | Model |
| Sensing method | Appearance | Connection method | 36113 | ing distant | | baud rate | PNP |
| | | Pre-wired (2 m) | | | | COMO | E3Z-D82-IL2 2M |
| | | Pre-wired M12 connector | | | | COM2 (38.4 kbps) | E3Z-D82-M1TJ-IL2 0.3M |
| | ∑ | Standard M8 connector | 1 m | | | | E3Z-D87-IL2 |
| | | Pre-wired (2 m) | | ı m | COM3 (230.4 kbps) | COMO | E3Z-D82-IL3 2M |
| | | Pre-wired M12 connector | | | | (230.4 kbps) | E3Z-D82-M1TJ-IL3 0.3M |
| Diffuse-reflective | | Standard M8 connector | | | | (200.1 (1000) | E3Z-D87-IL3 |
| Diliuse-reliective | | Pre-wired (2 m) | | | | COMO | E3Z-L81-IL2 2M |
| | | Pre-wired M12 connector | | | | COM2 (38.4 kbps) | E3Z-L81-M1TJ-IL2 0.3M |
| | | Standard M8 connector | 90 mm | , | | (00.4 Kbps) | E3Z-L86-IL2 |
| | | Pre-wired (2 m) | | v beam) | | 00140 | E3Z-L81-IL3 2M |
| | | Pre-wired M12 connector | , | 1 | | COM3 (230.4 kbps) | E3Z-L81-M1TJ-IL3 0.3M |
| | | Standard M8 connector | | | | (200.4 Kbpb) | E3Z-L86-IL3 |

Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

Accessories (Sold Separately)

Slit (A Slit is not provided with Through-beam Sensors) Order a Slit separately if required.

| Slit width | Sensing distance | Minimum detectable object | Model | Contents | |
|-------------|------------------|---------------------------|----------|--------------------------------------|--|
| Siit Widtii | E3Z-T | E3Z-T (Reference value) | | Contents | |
| 0.5-mm dia. | 50 mm | 0.2-mm dia. | E39-S65A | | |
| 1-mm dia. | 200 mm | 0.4-mm dia. | E39-S65B | | |
| 2-mm dia. | 800 mm | 0.7-mm dia. | E39-S65C | One set (contains Slits for both the | |
| 0.5 × 10 mm | 1 m | 0.2-mm dia. | E39-S65D | Emitter and Receiver) | |
| 1 × 10 mm | 2.2 m | 0.5-mm dia. | E39-S65E | | |
| 2×10 mm | 5 m | 0.8-mm dia. | E39-S65F | | |

Reflectors (Reflector required for Retroreflective Sensors) A Reflector is not provided with the Sensor. Be sure to order a Reflector separately.

| | Sensing | | Quantity | Remarks | |
|------------------------|--------------|-----------------|----------|---------|--|
| Name | E | Model | | | |
| | Rated value | Reference value | | | |
| | 3 m (100 mm) | | E39-R1 | 1 | |
| | 4 m (100 mm) | | E39-R1S | 1 | |
| Reflector | | 5 m (100 mm) | E39-R2 | 1 | Reflectors are not |
| | | 2.5 m (100 mm) | E39-R9 | 1 | provided with |
| | | 3.5 m(100 mm) | E39-R10 | 1 | Retro-reflective models. |
| Fog Preventive Coating | | 3 m (100 mm) | E39-R1K | 1 | The MSR function of |
| Small Reflector | | 1.5 m (50 mm) | E39-R3 | 1 | the E3Z-R□ is |
| | | 700 mm (150 mm) | E39-RS1 | 1 | enabled. |
| Tape Reflector | | 1.1 m (150 mm) | E39-RS2 | 1 | |
| | | 1.4 m (150 mm) | E39-RS3 | 1 | |

Note:1. If you use the Reflector at any distance other than the rated distance, make sure that the stability indicator lights properly when you install the Sensor.

^{2.} Refer to Reflectors on E39-L/E39-S/E39-R on your OMRON website for details.

^{*} Values in parenthese indicate the minimum required distance between the Sensor and Reflector.

Mounting Brackets A Mounting Bracket is not enclosed with the Sensor. Order a Mounting Bracket separately if required.

| Appearance | Model (material) | Quantity | Remarks | Appearance | Model (material) | Quantity | Remarks |
|------------|-------------------------|----------|--|------------|-------------------------|----------|--|
| | E39-L153 (SUS304) *1 | 1 | | | E39-L98 (SUS304) *2 | 1 | Metal Protective Cover Bracket |
| 5 | E39-L104 (SUS304) *1 | 1 | Mounting Brackets | *** | E39-L150 (SUS304) | 1 | (Sensor adjuster) |
| 3 | E39-L43 (SUS304) *2 | 1 | Horizontal Mounting Brackets | | E39-L151 | 1 | Easily mounted to the aluminum frame rails of conveyors and easily adjusted. |
| | E39-L142 (SUS304) *2 | 1 | Horizontal Protective Cover Bracket | * | (SUS304) | ' | For left to right adjust- ment |
| | E39-L44 (SUS304) | 1 | Rear Mounting Bracket | | E39-L144 (SUS304) *2 | 1 | Compact Protective Cover Bracket (For E3Z only) |

Note: 1. When using Through-beam models, order one bracket for the Receiver and one for the Emitter.

- Refer to Mounting Brackets on E39-L/E39-S/E39-R on your OMRON website for details.
 Cannot be used for Standard Connector models with mounting surface on the bottom. In that case, use Pre-wired Connector models.
- *2. Cannot be used for Standard Connector models.

Sensor I/O Connectors

(Models for Connectors and Pre-wired Connectors: A Connector is not provided with the Sensor. Be sure to order a Connector separately.)

| Size | Туре | Appearance | е | Cable length | Model |
|------------------------|-------------------------------|---|--------|--------------|-----------------|
| | | Smartclick connector Straight *2 | ~ | | XS5F-D421-D80-F |
| | Socket on one cable | Ottaight 2 | | 5 m | XS5F-D421-G80-F |
| | end | Smartclick connector L-shape *2 *3 | | 2 m | XS5F-D422-D80-F |
| M12 | | L'inape 2 0 | | 5 m | XS5F-D422-G80-F |
| | | Smartclick connector Straight/ | | 2 m | XS5W-D421-D81-F |
| | Socket and plug on | Straight *2 | C Bear | 5 m | XS5W-D421-G81-F |
| | cable ends *1 | Smartclick connector L-shape/L-shape *2 *3 | | 2 m | XS5W-D422-D81-F |
| | | | | 5 m | XS5W-D422-G81-F |
| | | Straight *3 | | 2 m | XS3F-M421-402-A |
| M8 | Socket on one cable | | O ME | 5 m | XS3F-M421-405-A |
| | end | L-shape *3 *4 | | 2 m | XS3F-M422-402-A |
| | | | | 5 m | XS3F-M422-405-A |
| M8 socket/ M12 plug | Socket and plug on cable ends | M8-M12 (Smartclick) conversion cable *2 | | 0.2 m | XS3W-M42C-4C2-A |

Note: 1. When using Through-beam models, order one connector for the Receiver and one for the Emitter.

2. Refer to Sensor I/O Connectors/Sensor Controllers on your OMRON website for details.

^{*1.} Straight type/L-shape type combinations are also available.
*2. The connectors will not rotate after they are connected.
*3. The cable is fixed at an angle of 180° from the sensor emitter/receiver surface.

Ratings and Specifications

IO-Link Model

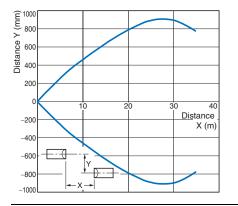
| | | Sensing method | Through-beam | Retro-reflective with MSR function | Diffuse-reflective | Narrow-beam Models | | |
|--------------------------|---------------|---------------------------|---|--|---------------------------------------|--|--|--|
| | | Pre-wired | E3Z-T81-IL□ | E3Z-R81-IL□ | E3Z-D82-IL□ | E3Z-L81-IL□ | | |
| Model | PNP output | Pre-wired connector (M12) | E3Z-T81-M1TJ-IL□ | E3Z-R81-M1TJ-IL□ | E3Z-D82-M1TJ-IL□ | E3Z-L81-M1TJ-IL□ | | |
| tem | | Connector (M8) | E3Z-T86-IL□ | E3Z-R86-IL□ | E3Z-D87-IL□ | E3Z-L86-IL□ | | |
| Sensing o | listance | • | 15 m | 4 m (100 mm) * (when using E39-R1S) 3 m (100 mm) * (when using E39-R1) | 1 m (white paper: 300 × 300 mm) | 90 + 30 mm (white paper: 100 × 100 mm) | | |
| Spot diam | neter (re | eference value) | | | | 2.5 dia. and sensing distance of 90 mm | | |
| Standard | sensin | g object | Opaque: 12-mm dia. min. | Opaque: 75-mm dia. min. | - | | | |
| Minimum (reference | | ible object | | | | 0.1 mm (copper wire) | | |
| Differentia (represer | | | | | 20% max. of setting distance | Refer to Engineering data on page 48. | | |
| Directiona | al angle | • | Both emitter and receiver: 3 to 15° | 2 to 10° | - | | | |
| Light sou | rce (wa | velength) | Infrared LED (870 nm) | Red LED (660 nm) | Infrared LED (860 nm) | Red LED (650 nm) | | |
| Power su | pply vo | Itage | 10 to 30 VDC (including 1 | 0% ripple (p-p)) | | | | |
| Current c | onsump | otion | 50 mA max. (Emitter: 25 mA max., Receiver: 25 mA max.) | 30 mA max. | | | | |
| Control o | utput | | Load power supply voltage: 30 VDC max., Load current: 100 mA max. Residual voltage: Load current of less than 10 mA: 1 V max. Load current of 10 to 100 mA: 2 V max. PNP open collector output Light-ON/Dark-ON selectable | | | | | |
| Indicators | 3 | | In the Standard I/O mode (SIO mode): Operation indicator (orange, lit) and stability indicator (green, lit) In the IO-Link Mode: Operation indicator (orange, lit) and communication indicator (green, blinking at 1 s intervals) | | | | | |
| Protection circuits | | | Reversed power supply polarity protection, out- put short-circuit protec- tion, and reversed output polarity protection | Reversed power supply polarity protection, output short-circuit protection, output short-circuit protection, reversed output polarity protection, and mutual interference prevention | | | | |
| Response | time | | Operate or reset: 1 ms max. | | | | | |
| Sensitivit | y adjus | tment | Sensitivity adjuster / IO-Link communications | | | | | |
| Ambient i (Receiver | | tion | Incandescent lamp: 3,000 lx max. Sunlight: 10,000 lx max. | | | | | |
| Ambient t | empera | ture range | Operating: -25 to 55°C (with no icing or condensation) Storage: -40 to 70°C (with no icing or condensation) | | | | | |
| Ambient h | numidit | y range | Operating: 35% to 85%, Storage: 35% to 95% (with no condensation) | | | | | |
| Insulation | resista | ance | 20 MΩ min. at 500 VDC | | | | | |
| Dielectric | strengt | th | 1,000 VAC, 50/60 Hz for 1 min | | | | | |
| Vibration | resista | nce | Destruction: 10 to 55 Hz, 1.5 mm double amplitude for 2 hours each in X, Y, and Z directions | | | | | |
| Shock res | istance |) | Destruction: 500 m/s ² 3 ti | mes each in X, Y , and Z di | irections | | | |
| Degree of | protec | tion | IEC 60529 IP67 | | | | | |
| Connection | | | Pre-wired cable (standard cable length 2 m), M12 pre-wired connector (standard cable length 0.3 m), M8 connector | | | | | |
| Weight | | red cable (2 m) | Approx. 120 g | Approx. 65 g | | | | |
| (packed | | ed connector (M12) | Approx. 60 g | Approx. 30 g | | | | |
| state) | Conne | ctor (M8) | Approx. 30 g | Approx. 20 g | | | | |
| | | Case | Polybutylene terephthalat | e (PBT) | | | | |
| Material | | Display | Modified polyarylate | I | | | | |
| | | Lens | Modified polyarylate | Methacrylate resin (PMMA) | | | | |
| Main IO-L | ink fund | ctions | Operation mode switching between Light ON and Dark ON, setup of the instability detection level for light receiving and non-light receiving, timer function of the control output and timer time selecting, instability output (IO-Link mode) ON delay timer time selecting, setup of a teaching level and execution of teaching, setup of light receiving sensitivity level, monitor output, operating hours read-out, and initial reset | | | | | |
| | | IO-Link specification | Ver 1.1 | | | | | |
| Communic | ation | Baud rate | -IL3: COM3 (230.4 kbps), | -IL2: COM2 (38.4 kbps) | | | | |
| specification | ons | Data length | PD size: 2 bytes, OD size | : 1 byte (M-sequence type | e: TYPE_2_2) | | | |
| | | Minimum cycle time | -IL3 (COM3): 1 ms, -IL2 (| COM2): 2.3 ms | | | | |
| Accessor | ies | | Instruction manual (Neithe | er Reflectors nor Mounting | Brackets are provided with | any of the above models. | | |
| | | | m required distance between t | | | | | |

^{*} Values in parentheses indicate the minimum required distance between the Sensor and Reflector.

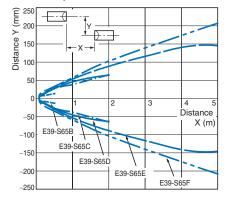
Engineering Data (Reference Value)

Parallel Operating Range

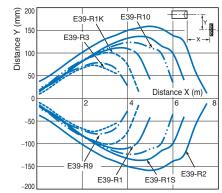
Through-beam Models E3Z-T8□-IL□



Through-beam Models E3Z-T8□-IL□ and Slit (A Slit is mounted to the Emitter and Receiver.)

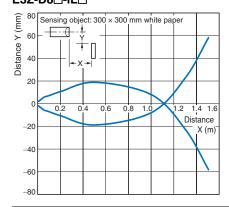


Retro-reflective Models E3Z-R8□-IL□ and Reflector

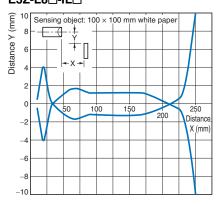


Operating Range

Diffuse-reflective Models E3Z-D8□-IL□

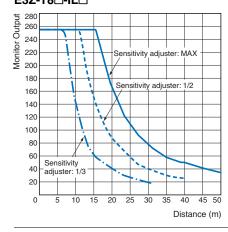


Narrow-beam Reflective Models E3Z-L8□-IL□

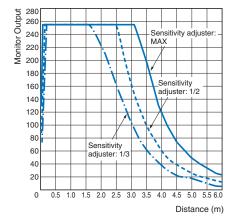


Monitor Output vs. Sensing Distance

Through-beam Models E3Z-T8□-IL□

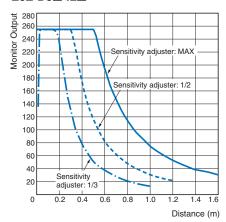


Retro-reflective Models E3Z-R8□-IL□ and E39-R1 Reflector

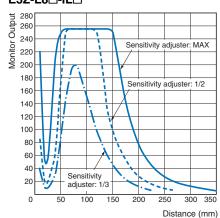


Monitor Output vs. Sensing Distance

Diffuse-reflective Models E3Z-D8□-IL□

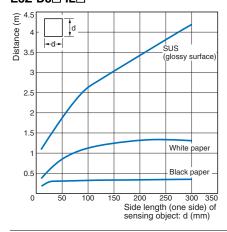


Narrow-beam Reflective Models E3Z-L8□-IL□

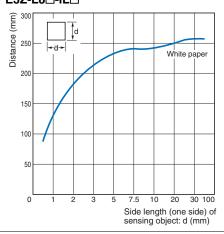


Sensing Object Size vs. Sensing Distance

Diffuse-reflective Models E3Z-D8□-IL□

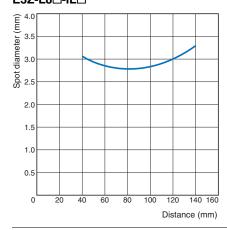


Narrow-beam Reflective Models E3Z-L8□-IL□



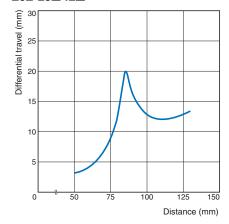
Spot Diameter vs. Sensing Distance

Narrow-beam Reflective Models E3Z-L8□-IL□

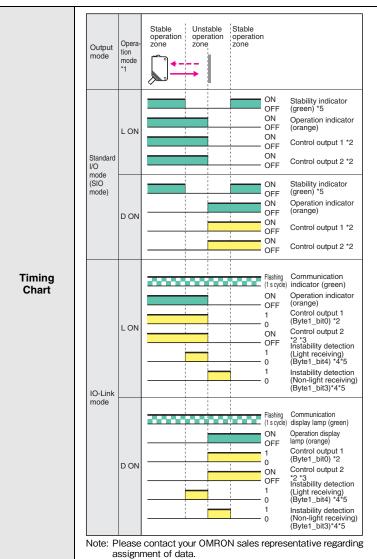


Differential Travel vs. Sensing Distance

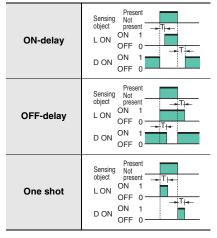
Narrow-beam Reflective Models E3Z-L8□-IL□



I/O Circuit Diagrams



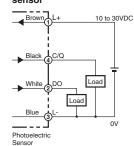
- *1. The operation mode can be changed by the IO-Link communications.
 *2. The timer function can be set up using the IO-Link communications for control output 1 and 2 separately. (It is able to select ON delay, OFF delay, or one-shot function and select a timer time of 1 to 4000 ms (T).)
 *3. In the IO-Link mode, if the ON/OFF speed of the sensor is slow, high
- *3. In the IO-Link mode, if the ON/OFF speed of the sensor is slow, highspeed response of 1 ms or less can be realized using control output 2 as a sensor.
- *4. The judgment time for the instability detection diagnosis can be selected using the IO-Link communications. (For the ON delay timer function to detect instability, the setting can be selected from 0 (invalid), 10, 50, 100, 300, 500, or 1000 ms.
- The judgment condition for the light receiving/non-light receiving instability detection function can be selected using the IO-Link communications. (Setting of light receiving instability detection threshold: 500%/400%/300%/200%/140%, setting of non-light receiving instability detection threshold: 70%/50%)



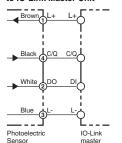
Reflective / Receiver of Through-beam Model

E3Z-□8□-IL□

When using as a general sensor



When using the Sensor connected to IO-Link Master Unit



Connector Pin Arrangement

Pre-wired M12 connector E3Z-\(\B1-\M1TJ-IL\) E3Z-\(\B2-\M1TJ-IL\) E3Z-T81-D-M1TJ-IL\(\)



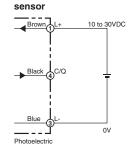
Standard M8 connector E3Z-□86-IL□ E3Z-□87-IL□ E3Z-T86-D-IL□



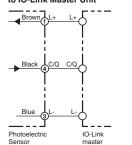
Output circuit

Emitter of Through-beam Model

E3Z-T8□-L-IL□ When using as a general



When using the Sensor connected to IO-Link Master Unit



Connector Pin Arrangement

E3Z-T81-L-M1TJ-IL



Note: Pins 2 is not used.

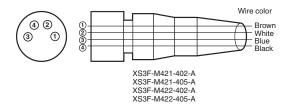
E3Z-T86-L-IL□



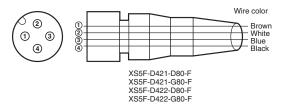
Note: Pins 2 is not used.

Plugs (Sensor I/O Connectors)

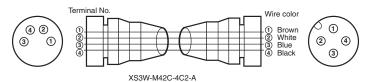
M8 connector



M12 connector



M8-M12 (Smartclick) conversion cable



Through-beam Models (Emitter)

Pin arrangement

| Classifi- cation | Wire color | Connector pin No. | Application | |
|---------------------|---------------|-------------------|--------------------|--|
| | Brown | 1 | Power supply (+V) | |
| | White | 2 | - | |
| DC | Blue | 3 | Power supply (0 V) | |
| | Black | 4 | Output C/Q | |

Note: Pins 2 is not used.

Through-beam Models (Receiver) Retro-reflective Models Diffuse-reflective Models

Pin arrangement

| | Classifi- cation | Wire color | Connector pin No. | Application | |
|--|---------------------|------------|----------------------|--------------------|--|
| | | Brown | 1 | Power supply (+V) | |
| | DC | White | 2 | Output DO | |
| | | Blue | 3 | Power supply (0 V) | |
| | | Black | 4 | Output C/Q | |

Nomenclature

Through-beam Models E3Z-T8□-IL□ (Receiver)

Retro-reflective Models

E3Z-R8□-IL□

Diffuse-reflective Models

E3Z-D8 - IL E3Z-L8 - IL

In the Standard I/O mode (SIO mode):
Stability indicator (green)
In the IO-Link mode:
IO-Link communication indicator (green)
Operation selector

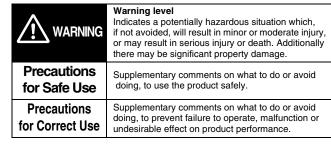


Operation indicator (orange)Sensitivity adjuster

Safety Precautions

Be sure to read the precautions for all models in the website at: http://www.ia.omron.com/.

Warning Indications



Meaning of Product Safety Symbols



General prohibition

Indicates the instructions of unspecified prohibited action



Caution, explosion

Indicates the possibility of explosion under specific conditions.



Caution, fire

Indicates the possibility of fires under specific conditions.

↑ WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



The maximum power supply voltage is 30 VDC. Before turning the power ON, make sure that the power supply voltage does not exceed the maximum voltage.



Never use the product with an AC power supply. Otherwise, explosion may result.



Do not use the product with voltage in excess of the rated voltage.

Excess voltage may result in malfunction or fire.



Do not use the product above rated load.



Precautions for Safe Use

Be sure to follow the safety precautions below for added safety.

- Do not use the sensor under the environment with explosive or ignition gas.
- 2. Never disassemble, repair nor tamper with the product.

Precautions for Correct Use

- 1. Do not use the product under the following conditions.
 - (1) In the place exposed to the direct sunlight.
 - (2) In the place where humidity is high and condensation may occur.
 - (3) In the place where vibration or shock is directly transmitted to the product.
- 2. Connection and Mounting
 - (1) If the sensor wiring is placed in the same conduits or ducts as high-voltage or high-power lines, inductive noise may cause malfunction or damage. Wire the cables separately or use a shielded cable.
 - (2) Use an extension cable less than 100 m long for Standard I/O mode and less than 20 m for IO-Link mode.
 - (3) Do not exceed the following force values applied to the cable. Tensile: 80 N max., torque: 0.1 Nm max., pressure: 20 N max., flexure: 3 kg max.

M8 metal connectors

- (4) Fasten a fixed implement by hand. If you use pliers, it may cause malfunction or damage to it.
- 3. Cleaning

Do not use thinner, alcohol, or other organic solvents. Otherwise, the optical properties and degree of protection may be degraded.

4. Power supply

When using a commercially available switching regulator, be sure to ground the FG (Frame Ground) terminals.

5. Power supply reset time

The photoelectric sensor will begin sensing no later than 100 ms after the power is turned on. If the load and the photoelectric sensor is connected to different power supply, the photoelectric sensor must be always turned on first.

6. Turning off the power supply

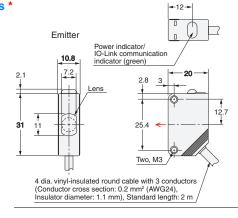
When turning off the power, output pulse may be generated. We recommend turning off the power supply of the load or load line first.

- 7. Water resistance
 - Though this is type IP67, do not use in the water, rain or outdoors.
- 8. Please process it as industrial waste.

Dimensions

Sensors

Through-beam Models * **Pre-wired Models** E3Z-T81-IL□



| Terminal No. | Specifi- cations |
|-----------------|---------------------|
| 1 | +V |
| 2 | |
| 3 | 0V |
| 4 | Output C/O |

Pins 2 is not used.

Terminal No.

1

2

3

4

Specifi-cations

+V

Output DO

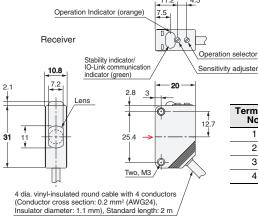
0V

Output C/Q

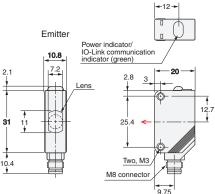
Pre-wired M12 connector (E3Z-T□□-M1TJ)







Through-beam Models * **Connector Models** E3Z-T86-IL□



| Terminal No. | Specifi- cations | | |
|-------------------|---------------------|--|--|
| 1 | +V | | |
| 2 | | | |
| 3 | 0V | | |
| 4 | Output C/Q | | |
| ins 2 is not used | | | |



| | Operation | Indicator (orange) | 7.5 | Operation selector | n - | |
|-----|-----------|--|-------------|------------------------|------------|-----------------|
| | Receiver | | | | | |
| 2.1 | 7.2 | Stability indicator/ IO-Link communication indicator (green) | on 20 - | Sensitivit adjuster | y _ | |
| + | Le | 1 . | 3- - | | Terminal | Specifi- |
| 1 | | - + | 0 | - | No. | cations |
| 1 | | _ | • | 12.7 | | |
| 31 | 1 13 | 25.4 | → | 12.7 | | cations |
| 31 | 11 | | > | 12.7 | No. | cations +V |
| 31 | 111 | | > | 12.7 | No. 1 2 | +V Output DO |

^{*} Models numbers for Through-beam Sensors (E3Z-T□□) are for sets that include both the Emitter and Receiver.

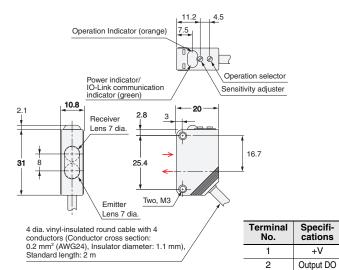
The model number of the Emitter is expressed by adding "-L" to the set model number (example: E3Z-T81-IL□-L 2M), the model number of the Receiver, by adding "-D" (example: E3Z-T81-IL□-D 2M.) Refer to *Ordering Information* to confirm model numbers for Emitter and Receivers.

Retro-reflective Models

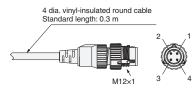
Pre-wired Models E3Z-R81-IL□ E3Z-D82-IL□

E3Z-L81-IL□





Pre-wired M12 connector (E3Z-□8□-M1TJ)



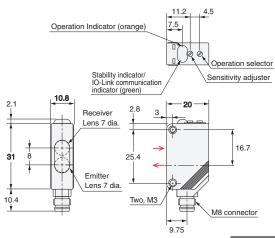
Retro-reflective Models

Connector Models E3Z-R86-IL□

E3Z-D87-IL□

E3Z-L86-IL□





| Terminal No. | Specifi- cations |
|-----------------|---------------------|
| 1 | +V |
| 2 | Output DO |
| 3 | 0V |
| 4 | Output C/Q |

3

4

0V

Output C/Q

Note: The lens for the E3Z-D□2/D□7 is black.

Accessories (Order Separately)

E39-S65B

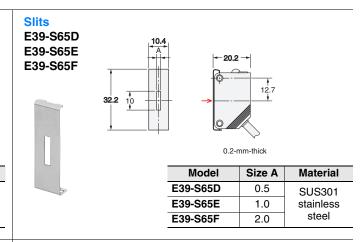
E39-S65C

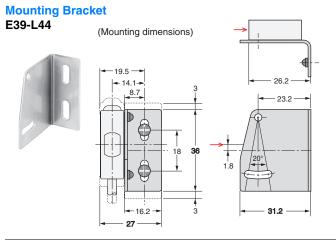
1.0 dia.

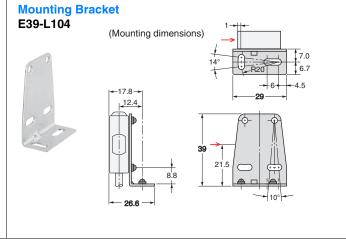
2.0 dia.

stainless

steel







Reflectors

Refer to E39-R on your OMRON website for details.

Sensor I/O Connectors

Refer to XS3 or XS5 on your OMRON website for details.

IO-Link Color Mark Photoelectric Sensors

E3S-DCP21-IL

Color Mark Detection on Any Type of Packaging.

Narrow Beam and Large Lens for Stable Detection of Workpieces Tilted at Various Angles.

- Detects subtle color differences.
 High luminance, three-element (RGB) LED light source for greater light intensity. Highly efficient optics technology provides high power and enables stable detection even of subtle color
- Handles glossy workpieces.
- Thorough noise reduction.
- High dynamic range covers everything from black to mirror surfaces.
- IoT compatible.

differences.

- Sends RGB information to host with high-speed IO-Link communications.
- Optimum threshold set to reduce false detection.



Refer to Safety Precautions on page 60.





For the most recent information on models that have been certified for safety standards, refer to your OMRON website.

Red light, Green light, Blue light

Ordering Information

Sensors (Refer to Dimensions on page 61.)

Connection IO-Link Sensing method **Appearance** Sensing distance Output Model method baud rate COM₂ E3S-DCP21-IL2 (38.4 kbps) Diffuse-reflective M12 connector Push-pull (mark detection) СОМЗ 10±3 mm E3S-DCP21-IL3 (230.4 kbps)

Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

Accessories (Sold Separately)

Sensor I/O Connectors (Required for a Sensor with a connector.)

Connectors are not provided with the Sensors. Be sure to order a Connector separately.

| Size | Туре | Арро | earance | Cable length | Model |
|---------|--------------------|----------------------|--|-----------------|-----------------|
| | | Straight | | 2 m | XS2F-D421-D80-F |
| | Socket on one | | | | XS2F-D421-G80-F |
| | cable end | L-shape | *2 | 2 m | XS2F-D422-D80-F |
| M12 | | | 6 / | 5 m | XS2F-D422-G80-F |
| IVI I Z | | Smartclick connector | 2 m | XS5W-D421-D81-F | |
| | Socket and plug on | Straight/straight | The second secon | 5 m | XS5W-D421-G81-F |
| | cable ends *1 | Smartclick connector | | 2 m | XS5W-D422-D81-F |
| | | L-shape/L-shape | shape/L-shape *2 | | XS5W-D422-G81-F |

Note: 1. Refer to Sensor I/O Connectors/Sensor Controllers on your OMRON website for details.

- The XS2W (Socket and Plug on Cable Ends) and XS5F (Socket on One Cable End) are also available.
- 2. The connectors will not rotate after they are connected.
- ***1.** There are also straight type/L-shape type combinations available.
- ***2.** The cable is fixed at an angle of 180° from the sensor emitter/receiver surface.

E3S-DCP21-IL□

Ratings and Specifications

| | Sensing method | d Diffuse-reflective (mark detection) | | | |
|-----------------------------------|-----------------------|---|--|--|--|
| | Output | Push-pull | | | |
| Item | Model | E3S-DCP21-IL2 E3S-DCP21-IL3 | | | |
| Sensing distance | | 10 ±3 mm (White paper 10 ×10 mm) | | | |
| Spot size (reference | e value) | 1 × 4 mm | | | |
| Light source (wave | length) | Red LED (635 nm), Green LED (525 nm), Blue LED (465 nm) | | | |
| Power supply volta | ge | 10 to 30 VDC±10% (Ripple (p-p) 10% max.) | | | |
| Power consumptio | n | 960 mW max. (Reference: Power supply voltage 24 V, Current consumption 40 mA max.) | | | |
| Control output | | Load current: 100 mA max. (30 VDC max.) | | | |
| Indications | | Operation indicator (orange), RUN indicator (green), 7-segment indicator (white), Key lock indicator (white), Timer indicator (white), 1-point teaching mode indicator (white) | | | |
| Operation mode | | High when mark is detected. | | | |
| Protection circuits | | Power supply reverse polarity protection, output short-circuit protection and output incorrect connection protection | | | |
| Response time | | Operate or reset: 50 μs max. for each (2-point teaching mode) Operate or reset: 150 μs max. for each (1-point teaching mode) | | | |
| Sensitivity adjustm | ent | Teaching method | | | |
| Ambient illumination | on | Incandescent lamp: 3,000 lx max. | | | |
| Ambient temperatu | re range | Operating: -10 to 55°C; Storage: -25 to 70°C (with no icing or condensation) | | | |
| Ambient humidity range | | Operation: 35% to 85%, Storage: 35% to 95% (with no condensation) | | | |
| Insulation resistant | ce | 20 MΩ min. (at 500 VDC) | | | |
| Dielectric strength | | 1,000 VAC, 50/60 Hz for 1 min | | | |
| Vibration resistanc | е | Destruction: 10 to 55 Hz with double amplitude of 1.5 mm for 2 hours each in X, Y, and Z directions | | | |
| Shock resistance | | Destruction: 500 m/s ² 3 times each in X, Y, and Z directions | | | |
| Degree of protection | n | IEC 60529 IP67 | | | |
| Connection method | į | M12, 4-pin connector | | | |
| Weight (packed state/Sensor only) | Model with connector | Approx. 370 g/approx. 320 g | | | |
| | Case | Diecast zinc (nickel-plated brass) | | | |
| | Lens | Methacrylic resin (PMMA) | | | |
| Materials | Indicators | ABS | | | |
| | Buttons | Elastomers | | | |
| | Connector | Diecast zinc (nickel-plated brass) | | | |
| Main IO-Link functions | | Operation mode switching between NO and NC Timer function of the control output and timer time selecting function (Select a function from disabled, ON delay, OFF delay, one-shot or ON/OFF delay.) (Select a timer time of 1-5000 ms Selecting function of ON delay timer time for instability (0 (disabled)-1000 ms) Monitor output function (PD output indicating a relative detection quantity) Energizing time read-out function (unit: h) Initialize the settings function "Restore the factory settings" | | | |
| | IO-Link specification | Version 1.1 | | | |
| Communication | Baud rate | E3S-DCP21-IL3: COM3 (230.4 kbps), E3S-DCP21-IL2: COM2 (38.4 kbps) | | | |
| specifications | Data length | PD size: 8 bytes, OD size: 1 byte (M-sequence type: TYPE_2_2) | | | |
| | Minimum cycle time | E3S-DCP21-IL3 (COM3): 1.5 ms, E3S-DCP21-IL2 (COM2): 4.8 ms | | | |
| Accessories | | Instruction manual | | | |

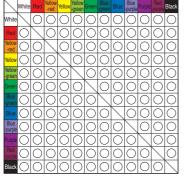
* Standard Sensing Object for the Mark Sensor

| Color | Munsell code | |
|--------------|--------------|--|
| White | N9.5 | |
| Red | 4R 4.5/12.0 | |
| Yellow-red | 4YR 6.0/11.5 | |
| Yellow | 5Y 8.5/11.0 | |
| Yellow-green | 3GY 6.5/10.0 | |
| Green | 3G 6.5/9.0 | |
| Blue-green | 5BG 4.5/10.0 | |
| Blue | 3PB 5.0/10.0 | |
| Blue-purple | 9PB 5.0/10.0 | |
| Purple | 7P 5.0/10.0 | |
| Red-purple | 6RP 4.5/12.5 | |
| (Black) | (N2.0) | |

Engineering Data (Reference Value)

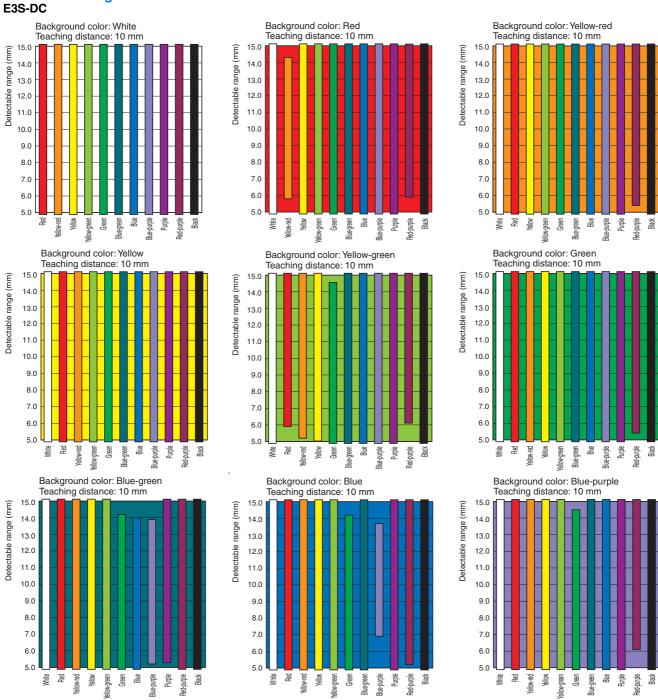
Color vs. Detection Capability E3S-DC

Teaching Capabilities

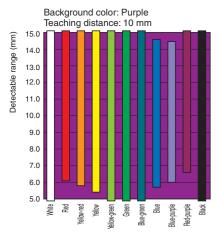


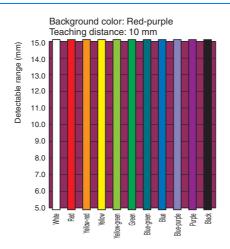
Note: The above chart shows the combinations of colors for which teaching is possible at a sensing distance of 10 mm.

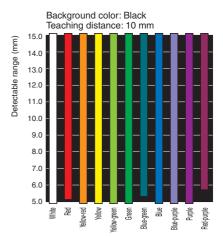
Detectable Ranges



E3S-DCP21-IL□

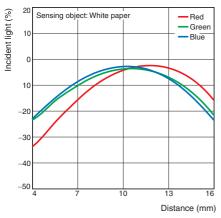


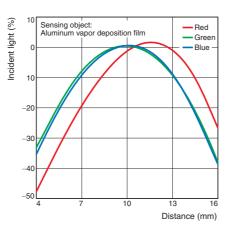




Excess Gain vs. Distance

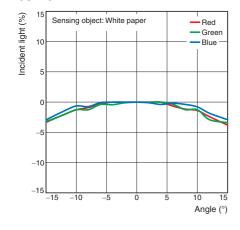
E3S-DC

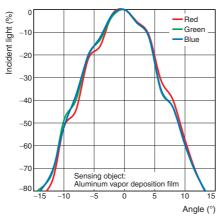




Angle vs. Incident Characteristics

E3S-DC





I/O Circuit Diagrams

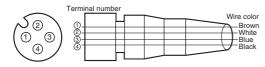
Push-Pull Output

| Model | Output mode | NO/NC setting *4 | Timing chart | Output circuit | |
|--------------------------------|--|------------------|--|---|--|
| | Standard I/O mode | NO * 5 | Sensing object Background Mark RUN indicator (Green) Operation indicator (Orange) Pin 4 output (NO) Pin 2 output (NO) Low HIGH Load current (PNP connection) Load current (NPN connection) | Using Pin 2 as an external input *1 (enabled by default) Brown Brown Brown White 2 White 2 Blue 30 V | |
| E3S-DCP21-IL2 E3S-DCP21-IL3 | (SIO mode) (Pin 2 Output Settings) | NC | Sensing object Background Mark RUN indicator (Green) Operation indicator (Orange) Pin 4 output (NC) Pin 2 output (NC) Load current (PNP connection) Load current (NPN connection) New York (Name of the connection) Mark Mark Mark Mark Mark Not Lighting Not Lighting Not Lighting Not Lighting Not Lighting ON OFF ON OFF ON OFF | Using Pin 2 with a control output *1 (set for IO-Link) Brown Brown White OUT2 PNP PNP PNP Blue Blue | |
| | IO-Link mode (Pin 2 Output Settings) | | NO * 5 | Sensing object RUN indicator (Green) (1 sec cycles Flashing) Operation indicator (Orange) Pin 4 output (NO) (IO-Link communications) Pin 2 output (NO) LOW Mark Mark Lighting Lighting Lighting Lighting | Brown 1+V Brown 1+V Black 4 C/Q Black 4 C/Q White OUT2 White DI/DO |
| | | NC | Sensing object RUN indicator (Green) (1 sec cycles Flashing) Operation indicator (Orange) Pin 4 output (NC) (IO-Link communications) Pin 2 output (NC) HIGH LOW Mark Mark Mark Mark Mort Lighting Not Lighting Not Lighting | White 20172 White 2017DO Blue 30 V IO-Link Master | |

- *1. Pin 2 input/output can be switched with the IO-Link communication command "Switchpoint Pin 2".
- *2. In case of NPN connection, please connect the load between Pin 1 and Pin 4.
- *3. In case of PNP connection, please connect the load between Pin 3 and Pin 4.
- *4. It can be switched in IO-Link.
- ***5.** Factory default
- Note: 1. You can use IO-Link communications to reverse the operation logic, set an output delay, and change between an input and output.
 - 2. Please contact your OMRON sales representative regarding assignment of data.

Plugs (Sensor I/O Connectors)

M12, 4-pin Connector



| | | | Application |
|----------------|------------|-------------------|--------------------------------|
| Classification | Wire color | Connector pin No. | E3S-DCP21-IL2 E3S-DCP21-IL3 |
| | Brown | 0 | Power supply (+V) |
| DC | White | 2 | External input * |
| DC | Blue | 3 | Power supply (0 V) |
| | Black | 4 | Output C/Q |

^{*} It can be set as the control output with IO-Link.

Nomenclature

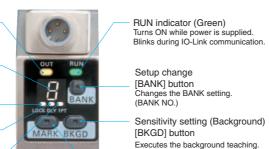
Operation indicator (Orange)
Turns ON when the mark is detected.
(when Pin 4 is set as NO)

7-segment indicator (White) Displays the BANK No. being selected.

Key lock indicator (White) Turns ON when key locksetting is activated.

Timer indicator (White) Turns ON when timersetting is activated.

1-point teaching mode indicator (White)
Turns ON when 1-point teaching mode.



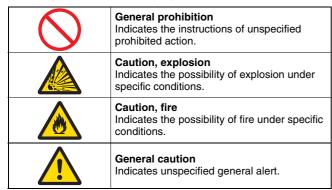
Sensitivity setting (Mark)
[MARK] button
Executes the mark teaching.

Safety Precautions

Be sure to read the precautions for all models in the website at: http://www.ia.omron.com/. Warning Indications

Warning level Indicates a potentially hazardous situation which, if not avoided, will result in minor or **∕**NWARNING moderate injury, or may result in serious injury or death. Additionally, there may be significant property damage. **Precautions** Supplementary comments on what to do or for Safe Use avoid doing, to use the product safely. **Precautions** Supplementary comments on what to do or avoid doing, to prevent failure to operate, for Correct malfunction or undesirable effect on product Use performance.

Meaning of Product Safety Symbols



↑ WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purpose.



Never use the product with an AC power supply. Otherwise, explosion may result.



Do not use the product with voltage in excess of the rated voltage.

Excess voltage may result in malfunction or fire.



Be sure to tighten the external lens until it reaches the chassis.



Precautions for Safe Use

The following precautions must be observed to ensure safe operation of the product.

- 1. Do not install the product in the following locations.
 - · Locations subject to direct sunlight
 - · Locations subject to condensation due to high humidity
 - · Locations subject to corrosive gas
 - In the place where vibration or shock is directly transmitted to the product.
- Do not use the product in environments subject to flammable or explosive gases.
- 3. Do not use the product in any atmosphere or environment that exceeds the ratings.
- 4. Do not pull on the cable with excessive strength.
- Do not attempt to disassemble, repair, or modify the product in any way.
- Do not use the product with the main unit damaged.
- 7. Be sure that before making supply the supply voltage is less than the maximum rated supply voltage (30 VDC).
- 8. Do not apply any load exceeding the ratings.
- 9. Do not short the load. Otherwise damage or fire may result.
- 10. Connect the load correctly.
- 11. Do not use the product under a chemical or an oil environment without prior evaluation.
- 12. Though this is type IP67, do not use in the water, rain or outdoors.
- Do not use thinner, alcohol, or other organic solvents. Otherwise, the optical properties and degree of protection may be degraded.
- 14. When disposing of the product, treat it as industrial waste.
- 15. These Sensors are certificated for the UL standard on the assumption of usage in a Class 2 circuit. Use them with Class 2 power supplies in the United States or Canada. Use the OMRON XS2F-D4-series or XS5F-D4-series Cables. Cables that have wires less than AWG24 (0.2 mm²) are for connection to terminal blocks and are not for field splicing. External overcurrent protection of 1 A for AWG26, 2 A for AWG24, or 3 A for AWG22 wire must be provided for cable protection.

Precautions for Correct Use

- Note that the water-resistant function is impaired if installing the Photoelectric Sensor by hitting it with a hammer and so on.
- 2. Be sure to tighten the external lens until it reaches the chassis.
- If the Sensor wiring is placed in the same conduits or ducts as high-voltage or high-power lines, inductive noise may cause malfunction or damage. Wire the cables separately or use a shielded cable.
- To extend a cable in the standard I/O mode, use a cable of 0.3 mm² or more and keep the length 100 m or less. Keep the length 20 m or less if using the Sensor in the IO-Link mode.
- 5. Apply a screw tightening torque of 2.0 N·m or less.

- If a commercial switching regulator is used, ground the FG (frame ground) terminal.
- The Sensor will be able to detect objects 100 ms after the power supply is tuned ON. Start using the Sensor 100 ms or more after turning ON the power supply. If the load and the Sensor are connected to separate power supplies, be sure to turn ON the Sensor first.
- Do not press the button with anything sharp such as a screwdriver because it might be damaged.
- Output pulses may occur when the power supply is turned OFF. We recommend that you turn OFF the power supply to the load or load line first.

(Unit: mm)

Tolerance class IT16 applies to dimensions in this data sheet unless otherwise specified.

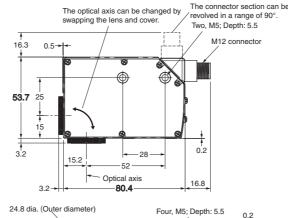
Sensors

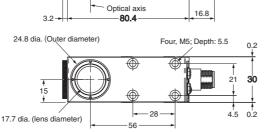
Dimensions

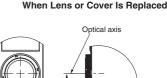
Diffuse-reflective Models

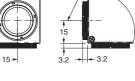
E3S-DCP21-IL2 E3S-DCP21-IL3













Note: 1. Apply a screw tightening torque of 2.0 N⋅m or less.

2. Be sure to tighten the external lens or cover until it reaches the chassis.

| МЕМО |
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CE

IO-Link Proximity Sensor (Standard Models)

E2E-IL

IO-Link Makes Sensor Level Information Visible and Solves the Three Major Issues at Manufacturing Sites! Standard Proximity Sensor.

- Downtime can be reduced.
 Notifies you of faulty parts and such phenomena in the Sensor in real time.
- The frequency of sudden failure can be decreased. Notifies you of objects being too far or too close.
- The efficiency of changeover can be improved.
 The batch check for individual sensor
 IDs significantly decreases commissioning time.
- Standard Sensor for detecting ferrous metals.



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.



Be sure to read *Safety Precautions* on page 67.

Ordering Information

Sensors [Refer to Dimensions on page 68.]

DC 3-wire IO-Link Models

| Appear | rance | Sensing distance | Connection method | Pin arrangement | IO-Link baud rate | Model PNP |
|----------|-------|------------------|---|--------------------|----------------------|-------------------------|
| | | | Pre-wired Models | | COM2 (38.4 kbps) | E2E-X3B4-IL2 2M |
| | | | (2 m) | _ | COM3 (230.4 kbps) | E2E-X3B4-IL3 2M |
| _ | M12 | 3 mm | M12 Pre-wired Smartclick Connector Models | | COM2 (38.4 kbps) | E2E-X3B4-M1TJ-IL2 0.3M |
| | | | (0.3 m) | 4: C/Q output | COM3 (230.4 kbps) | E2E-X3B4-M1TJ-IL3 0.3M |
| | | 7 mm | Pre-wired Models (2 m) | | COM2 (38.4 kbps) | E2E-X7B4-IL2 2M |
| Shielded | | | | _ | COM3 (230.4 kbps) | E2E-X7B4-IL3 2M |
| — | M18 | | M12 Pre-wired Smartclick Connector Models (0.3 m) | 1: +V 3: 0 V | COM2 (38.4 kbps) | E2E-X7B4-M1TJ-IL2 0.3M |
| | | | | 4: C/Q output | COM3 (230.4 kbps) | E2E-X7B4-M1TJ-IL3 0.3M |
| | | | Pre-wired Models | | COM2 (38.4 kbps) | E2E-X10B4-IL2 2M |
| N | | | (2 m) | _ | COM3 (230.4 kbps) | E2E-X10B4-IL3 2M |
| | M30 | 10 mm | M12 Pre-wired Smartclick Connector Models | 1: +V 3: 0 V | COM2 (38.4 kbps) | E2E-X10B4-M1TJ-IL2 0.3M |
| | | | (0.3 m) | 4: C/Q output | COM3 (230.4 kbps) | E2E-X10B4-M1TJ-IL3 0.3M |

Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

Accessories (Sold Separately)

Sensor I/O Connectors

(Models with Pre-wired Connectors: A Connector is not provided with the Sensor. Be sure to order a Connector separately.)

| Туре | Appearance | Cable length | Sensor I/O Connector model number | Applicable Proximity Sensor model number |
|-----------------|-------------------|--------------|--------------------------------------|--|
| | Straight | 2 m | XS5F-D421-D80-F | |
| Socket on one | | 5 m | XS5F-D421-G80-F | |
| cable end | L-shape | 2 m | XS5F-D422-D80-F | |
| | | 5 m | XS5F-D422-G80-F | E2E-X□B4-M1TJ-IL□ |
| | Straight/straight | 2 m | XS5W-D421-D81-F | E2E-∧□D4-INITIO-IL□ |
| Socket and plug | | 5 m | XS5W-D421-G81-F | |
| on cable ends * | L-shape/L-shape | 2 m | XS5W-D422-D81-F | |
| | | 5 m | XS5W-D422-G81-F | |

Note: Refer to Sensor I/O Connector/Sensor Controller on your OMRON website for details.

^{*} There are also straight type/L-shape type combinations available.

Ratings and Specifications

DC 3-wire IO-Link Models (E2E-X B4-IL)

| | Size | M12 | M18 | M30 | | | | | |
|--------------------------|--------------------|--|--|--|--|--|--|--|--|
| Shielded | | | Shielded | | | | | | |
| Item | Model | E2E-X3B4-IL□ | E2E-X3B4-IL□ | | | | | | |
| Sensing dist | ance | 3 mm ±10% | 7 mm ±10% | 10 mm ±10% | | | | | |
| Set distance | | 0 to 2.4 mm | 0 to 5.6 mm | 0 to 8 mm | | | | | |
| Differential t | ravel | 10% max. of sensing distance | | | | | | | |
| Detectable o | bject | Ferrous metal (The sensing distance decreases | s with non-ferrous metal. Refer to I | Engineering Data on pages 65.) | | | | | |
| Standard sei | nsing object | Iron, 12 × 12 × 1 mm | Iron, 18 × 18 × 1 mm | Iron, 30 × 30 × 1 mm | | | | | |
| Response fro | equency *2 | 1 kHz | 0.5 kHz | 0.4 kHz | | | | | |
| Power suppl | y voltage | 10 to 30 VDC (including 10% rip | ple (p-p)) | | | | | | |
| Current cons | sumption | 20 mA max. | * | | | | | | |
| Control | Load current | 100 mA max. | | | | | | | |
| output | Residual voltage | 2 V max. (Load current: 100 mA | Cable length: 2 m) | | | | | | |
| Indicators *1 | | | de): Operation indicator (orange, lit) dicator (orange, lit) and communication | and stability indicator (green, lit) on indicator (green, blinking at 1 s intervals) | | | | | |
| Operation m | ode | PNP NO/NC switching type (Factory setting: NO) Refer to the timing charts under I/O Circuit Diagrams on page 66 for details. | | | | | | | |
| Protection circuits | | Power supply reverse polarity protection, output reverse polarity protection, surge suppressor, and output short-circuit protection | | | | | | | |
| Ambient tem | perature range | Operating/Storage: -25 to 70°C (with no icing or condensation) | | | | | | | |
| Ambient hun | nidity range | Operating/Storage: 35% to 95% (with no condensation) | | | | | | | |
| Temperature | influence | ±10% max. of sensing distance at 23°C in the temperature range of -25 to 70°C | | | | | | | |
| Voltage influ | ence | ±1% max. of sensing distance at rated voltage in the rated voltage ±15% range | | | | | | | |
| Insulation re | sistance | 50 M $Ω$ min. (at 500 VDC) between current-carrying parts and case | | | | | | | |
| Dielectric str | rength | 1,000 VAC, 50/60 Hz for 1 minut | e between current-carrying parts a | and case | | | | | |
| Vibration res | sistance | Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions | | | | | | | |
| Shock resist | ance | Destruction: 1,000 m/s² 10 times each in X, Y, and Z directions | | | | | | | |
| Degree of pr | otection | IEC 60529 IP67, in-house standards: oil-resistant *3 | | | | | | | |
| Connection | method | Pre-wired Models (Standard cable length: 2 m), Pre-wired Connector Models (Standard cable length: 0.3 m) | | | | | | | |
| | Case | Nickel-plated brass | | | | | | | |
| Materials | Sensing surface | PBT | | | | | | | |
| wateriais | Clamping nuts | Nickel-plated brass | | | | | | | |
| | Toothed washer | Zinc-plated iron | Zinc-plated iron | | | | | | |
| Main IO-Link functions | | Operation mode switching between NO and NC, self diagnosis enabling, excessive proximity judgment distance selecting, timer function of the control output and timer time selecting, instability output (IO-Link mode) ON delay timer time selecting function, monitor output, operating hours read-out, and initial reset | | | | | | | |
| IO-Link specification | | Ver 1.1 | | | | | | | |
| Communication | Baud rate | -IL3: COM3 (230.4 kbps), -IL2: C | COM2 (38.4 kbps) | | | | | | |
| specifications | Data length | PD size: 2 bytes, OD size: 1 byte | | | | | | | |
| | Minimum cycle time | -IL3 (COM3): 1 ms, -IL2 (COM2) | | | | | | | |
| Accessories | | Instruction manual | | | | | | | |
| | | The decrease of the state of th | | | | | | | |

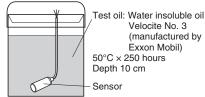
Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

- *1. In the Standard I/O mode (SIO mode), use the product in a range that the green stability indication lamp is lit. (Although the lamp is turned off when the object detected has approached excessively, the detection performance is stable.) In the IO-Link mode, use the product in a range that the Byte1_bit4 for instability detection is zero. (Although the Byte1_bit5 for excessive proximity detection is one if the object detected has approached excessively, the detection performance is stable.)
- Please contact your OMRON sales representative regarding assignment of data. *2. The response frequency is an average value. Measurement conditions are as follows: standard sensing object, a distance of twice the standard sensing object, and a set distance of half the sensing distance.
- *3. Oil resistance in-house standard: Performance with respect to water insoluble oil. (Test at right)

Oil resistance test

After the test time elapses, the characteristics below are checked for problems.

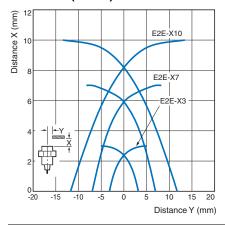
- (1) Visual appearance (no damage that affects product characteristics)
- (2) Operation check (ON/OFF)
- (3) Insulation resistance (50 $M\Omega$ min. at 500 VDC)
- (4) Dielectric strength (500 VAC, 1 min.)
- (5) Water resistance (IP67)



Engineering Data (Reference Value)

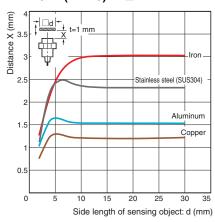
Sensing Area

E2E-X□B4 (-M1TJ) -IL□

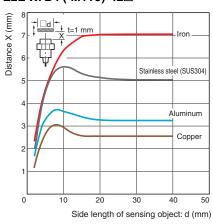


Influence of Sensing Object Size and Material

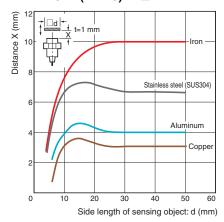
E2E-X3B4 (-M1TJ) -IL□



E2E-X7B4 (-M1TJ) -IL□

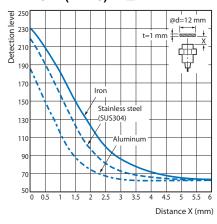


E2E-X10B4 (-M1TJ) -IL□

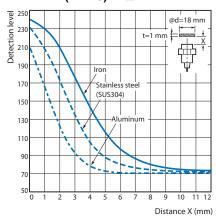


Monitor Output

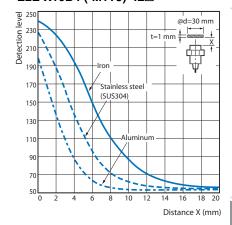
E2E-X3B4 (-M1TJ) -IL□



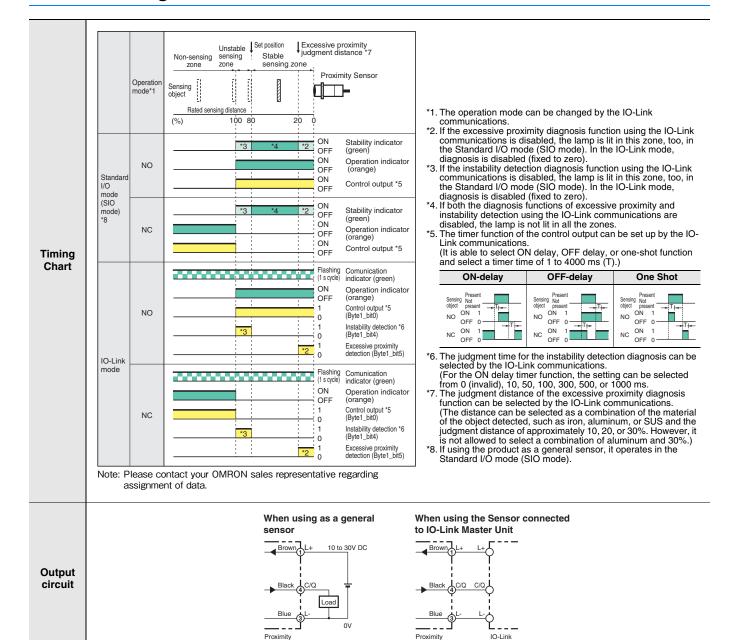
E2E-X7B4 (-M1TJ) -IL□



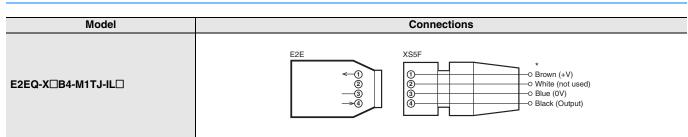
E2E-X10B4 (-M1TJ) -IL□



I/O Circuit Diagrams



Pre-wired Connector Model Connections

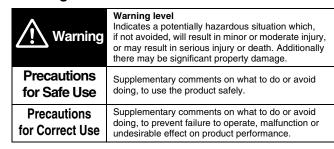


^{*} If the XS5W-D42 -- 81-F Connector which has a socket and plug on the cable ends is connected to the Sensor, this part will be a plug.

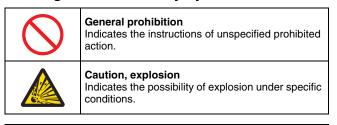
Safety Precautions

Be sure to read the precautions for all models in the website at: http://www.ia.omron.com/.

Warning Indications



Meaning of Product Safety Symbols



/ Warning

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Risk of explosion.

Do not connect sensor to AC power supply.



Precautions for Safe Use

The following precautions must be observed to ensure safe operation.

- Do not use the product in an environment where flammable or explosive gas is present.
- 2. Do not attempt to disassemble, repair, or modify the product.
- 3. Power Supply Voltage

Do not use a voltage that exceeds the rated operating voltage range. Applying a voltage that is higher than the operating voltage range may result in damage or burnout.

4. Incorrect Wiring

Be sure that the power supply polarity and other wiring is correct. Incorrect wiring may cause explosion or burnout.

5. Connection without a Load

If the power supply is connected directly without a load, the internal elements may explode or burn. Be sure to insert a load when connecting the power supply.

6. Dispose of this product as industrial waste.

Precautions for Correct Use

Do not use this product under ambient conditions that exceed the ratings

Operating Environment

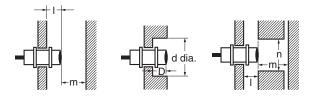
- Do not install the product in the following locations.
 Doing so may result in product failure or malfunction.
 - Outdoor locations directly subject to sunlight, rain, snow, water droplets, or oil.
 - (2) Locations subject to atmospheres with chemical vapors, in particular solvents and acids.
 - (3) Locations subject to corrosive gases.
- 2. The Sensor may malfunction if used near ultrasonic cleaning equipment, high-frequency equipment, transceivers, cellular phones, inverters, or other devices that generate a high-frequency electric field. Please refer to the Precautions for Correct Use on the OMRON website (www.ia.omron.com) for typical measures.
- 3. Laying the Proximity Sensor wiring in the same conduit or duct as high-voltage wires or power lines may result in incorrect operation and damage due to induction. Wire the Sensor using a separate conduit or independent conduit.

Never use thinner or other solvents. Otherwise, the Sensor surface may be dissolved.

Design

Influence of Surrounding Metal

When mounting the Sensor within a metal panel, ensure that the clearances given in the following table are maintained. Failure to maintain these distances may cause deterioration in the performance of the Sensor.

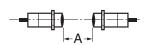


(Unit: mm)

| Model Item | ı | d | D | m | n |
|------------------------|---|----|---|----|----|
| E2E-X3B4 (-M1TJ) -IL□ | | 12 | | 8 | 18 |
| E2E-X7B4 (-M1TJ) -IL□ | 0 | 18 | 0 | 20 | 27 |
| E2E-X10B4 (-M1TJ) -IL□ | | 30 | | 40 | 45 |

Mutual Interference

When installing Sensors face-to-face or side-by-side, ensure that the minimum distances given in the following table are maintained.





(Unit: mm)

| Model | Item | Α | В |
|-----------------------|------|-----|----|
| E2E-X3B4 (-M1TJ) -IL□ | | 30 | 20 |
| E2E-X7B4 (-M1TJ) -IL□ | | 50 | 35 |
| E2E-X10B4 (-M1TJ) -IL | | 100 | 70 |

Mounting

Tightening Force

Do not tighten the nut with excessive force. A washer must be used with the nut. Do not use tightening force that exceeds the values in the following table.



| Model Ite | em | Torque |
|------------------------|----|---------|
| E2E-X3B4 (-M1TJ) -IL□ | | 30 N⋅m |
| E2E-X7B4 (-M1TJ) -IL□ | | 70 N⋅m |
| E2E-X10B4 (-M1TJ) -IL□ | | 180 N⋅m |

Wiring

In the IO-Link mode, the cable between the IO-link Master and Sensor must have a length of 20m or less.

Dimensions

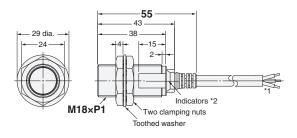
Pre-wired Models



E2E-X3B4-IL□ - 21 dia. -33-Indicators *2 Two clamping nuts M12xP1 Toothed washer

- *1. 4-dia. vinyl-insulated round cable with 3 conductors (Conductor cross section: 0.3 mm², Insulator diameter: 1.3 mm), Standard length: 2 m *2. Operation indicator (orange), stability indicator/
- communication indicator (green)

E2E-X7B4-IL□



- *1. 6-dia. vinyl-insulated round cable with 3 conductors (Conductor cross section: 0.5 mm², Insulator diameter: 1.9 mm), Standard length: 2 m
- *2. Operation indicator (orange), stability indicator/ communication indicator (green)

E2E-X10B4-IL□ 60 48 42 dia. 43 + 10 36 Indicators *2 Two clamping nuts M30×P1.5

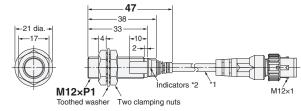
Toothed washer

- *1. 6-dia. vinyl-insulated round cable with 3 conductors (Conductor cross section: 0.5 mm², Insulator diameter: 1.9 mm), Standard length: 2 m *2. Operation indicator (orange), stability indicator/ communication indicator (green)

Pre-wired Connector Models



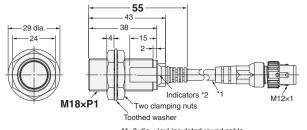
E2E-X3B4-M1TJ-IL



- *1. 4-dia. vinyl-insulated round cable

 - 1. 4-dua. viriyi-iistaaca coond caasa
 Standard length: 0.3 m
 *2. Operation indicator (orange), stability indicator/
 communication indicator (green)

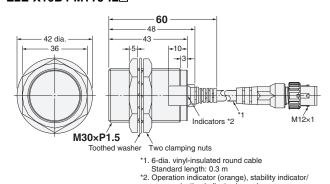
E2E-X7B4-M1TJ-IL□



- *1. 6-dia. vinyl-insulated round cable

Standard length: 0.3 m *2. Operation indicator (orange), stability indicator/communication indicator (green)

E2E-X10B4-M1TJ-IL□



communication indicator (green)

Mounting Hole Dimensions



| Dimension | M12 | M18 | M30 |
|-----------|--|--|--|
| F (mm) | 12.5 ₀ ^{+0.5} dia. | 18.5 ₀ ^{+0.5} dia. | 30.5 ₀ ^{+0.5} dia. |

IO-Link Makes Sensor Level Information Visible and Solves the Three Major Issues at Manufacturing Sites! A Proximity Sensor That Can Be Used in a Spatter Environment.

- Downtime can be reduced.
 Notifies you of faulty parts and such phenomena in the Sensor in real time.
- The frequency of sudden failure can be decreased.
 Notifies you of objects being too far or too close.
- The efficiency of changeover can be improved.
 The batch check for individual sensor
 IDs significantly decreases commissioning time.
- The fluororesin coating provides exceptional spatter resistance.



For the most recent information on models that have been certified for safety standards, refer to your OMRON website.



Be sure to read *Safety Precautions* on page 73.

Ordering Information

Sensors [Refer to Dimensions on page 74.]

DC 3-wire IO-Link Models

| Appear | rance | Sensing distance | Connection method | Pin arrangement | IO-Link baud rate | Model |
|----------|-------|----------------------|---|----------------------------------|-------------------------|--------------------------|
| | | | Pre-wired Models | | COM2 (38.4 kbps) | E2EQ-X3B4-IL2 2M |
| | | | (2 m) | _ | COM3 (230.4 kbps) | E2EQ-X3B4-IL3 2M |
| | M12 | 3 mm | M12 Pre-wired Smartclick Connector Models (0.3 m) 1: +V 3: 0 V 4: C/Q output | COM2 (38.4 kbps) | E2EQ-X3B4-M1TJ-IL2 0.3M | |
| | | | | | COM3 (230.4 kbps) | E2EQ-X3B4-M1TJ-IL3 0.3M |
| | | 7 mm | Pre-wired Models (2 m) | | COM2 (38.4 kbps) | E2EQ-X7B4-IL2 2M |
| hielded | | | | _ | COM3 (230.4 kbps) | E2EQ-X7B4-IL3 2M |
| — | M18 | | M12 Pre-wired Smartclick Connector Models (0.3 m) | 1: +V 3: 0 V 4: C/Q output | COM2 (38.4 kbps) | E2EQ-X7B4-M1TJ-IL2 0.3M |
| | | | | | COM3 (230.4 kbps) | E2EQ-X7B4-M1TJ-IL3 0.3M |
| | | WITZ FIE-WITEU SITIA | Pre-wired Models | | COM2 (38.4 kbps) | E2EQ-X10B4-IL2 2M |
| | | | (2 m) | _ | COM3 (230.4 kbps) | E2EQ-X10B4-IL3 2M |
| M | M30 | | M12 Pre-wired Smartclick Connector Models | | COM2 (38.4 kbps) | E2EQ-X10B4-M1TJ-IL2 0.3M |
| | | | (0.3 m) | 3: 0 V 4: C/Q output | COM3 (230.4 kbps) | E2EQ-X10B4-M1TJ-IL3 0.3M |

Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

Accessories (Sold Separately)

Sensor I/O Connectors

(Models with Pre-wired Connectors: A Connector is not provided with the Sensor. Be sure to order a Connector separately.)

| Туре | Appearance | Cable length | Sensor I/O Connector model number | Applicable Proximity Sensor model number |
|-----------------|-------------------|--------------|--------------------------------------|--|
| | Straight | 2 m | XS5F-D421-D80-F | |
| Socket on one | | 5 m | XS5F-D421-G80-F | |
| cable end | L-shape | 2 m | XS5F-D422-D80-F | |
| | | 5 m | XS5F-D422-G80-F | E2EQ-X□B4-M1TJ-IL□ |
| | Straight/straight | 2 m | XS5W-D421-D81-F | = EZEQ-AUD4-IVITIJ-ILU |
| Socket and plug | | 5 m | XS5W-D421-G81-F | |
| on cable ends * | L-shape/L-shape | 2 m | XS5W-D422-D81-F | |
| | | 5 m | XS5W-D422-G81-F | |

Note: Refer to Sensor I/O Connector/Sensor Controller on your OMRON website for details.

^{*} There are also straight type/L-shape type combinations available.

Ratings and Specifications

DC 3-wire IO-Link Models

| | Size | M12 | M18 | M30 | | | |
|------------------------|--------------------|--|--|---|--|--|--|
| Shielded | | | Shielded | | | | |
| Item | Model | E2EQ-X3B4-IL□ | E2EQ-X7B4-IL□ | E2EQ-X10B4-IL□ | | | |
| Sensing dist | ance | 3 mm ±10% | 7 mm ±10% | 10 mm ±10% | | | |
| Set distance | *1 | 0 to 2.4 mm | 0 to 5.6 mm | 0 to 8 mm | | | |
| Differential t | ravel | 10% max. of sensing distance | | | | | |
| Detectable o | bject | Ferrous metal (The sensing distance decreases v | vith non-ferrous metal. Refer to <i>Er</i> | ngineering Data on pages 71.) | | | |
| Standard sei | nsing object | Iron, 12 × 12 × 1 mm | Iron, 18 × 18 × 1 mm | Iron, 30 × 30 × 1 mm | | | |
| Response fro | equency *2 | 1 kHz | 0.5 kHz | 0.4 kHz | | | |
| Power suppl | y voltage | 10 to 30 VDC (including 10% ripple | e (p-p)) | | | | |
| Current cons | sumption | 20 mA max. | | | | | |
| Control | Load current | 100 mA max. | | | | | |
| output | Residual voltage | 2 V max. (Load current: 100 mA, C | Cable length: 2 m) | | | | |
| Indicators *1 | | In the Standard I/O mode (SIO mode In the IO-Link mode: Operation indic | | nd stability indicator (green, lit) n indicator (green, blinking at 1 s intervals) | | | |
| Operation m | ode | PNP NO/NC switching type (Factory setting: NO) Refer to the timing charts under <i>I/O Circuit Diagrams</i> on page 72 for details. | | | | | |
| Protection circuits | | Power supply reverse polarity protection, output reverse polarity protection, surge suppressor, and output short-circuit protection | | | | | |
| Ambient tem | perature range | Operating/Storage: -25 to 70°C (with no icing or condensation) | | | | | |
| Ambient hun | nidity range | Operating/Storage: 35% to 95% (with no condensation) | | | | | |
| Temperature | influence | ±10% max. of sensing distance at 23°C in the temperature range of -25 to 70°C | | | | | |
| Voltage influ | ence | ±1% max. of sensing distance at rated voltage in the rated voltage ±15% range | | | | | |
| Insulation re | sistance | 50 MΩ min. (at 500 VDC) between current-carrying parts and case | | | | | |
| Dielectric str | rength | 1,000 VAC, 50/60 Hz for 1 minute between current-carrying parts and case | | | | | |
| Vibration res | sistance | Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions | | | | | |
| Shock resist | ance | Destruction: 1,000 m/s² 10 times each in X, Y, and Z directions | | | | | |
| Degree of pr | otection | IEC 60529 IP67, in-house standards: oil-resistant | | | | | |
| Connection | method | Pre-wired Models (Standard cable length: 2 m), Pre-wired Connector Models (Standard cable length: 0.3 m) | | | | | |
| | Case | Fluororesin coating (Base material: brass) | | | | | |
| Materials | Sensing surface | Fluororesin | | | | | |
| Materiais | Clamping nuts | Fluororesin coating (Base material: brass) | | | | | |
| | Toothed washer | Zinc-plated iron | | | | | |
| Main IO-Link functions | | Operation mode switching between NO and NC, self diagnosis enabling, excessive proximity judgment distance selecting, timer function of the control output and timer time selecting, instability output (IO-Link mode) ON delay timer time selecting function, monitor output, operating hours read-out, and initial reset | | | | | |
| IO-Link specification | | Ver 1.1 | | | | | |
| Communication | Baud rate | -IL3: COM3 (230.4 kbps), -IL2: CO | M2 (38.4 kbps) | | | | |
| specifications | Data length | PD size: 2 bytes, OD size: 1 byte (| M-sequence type: TYPE_2_2) | | | | |
| | Minimum cycle time | -IL3 (COM3): 1 ms, -IL2 (COM2): 2 | | | | | |
| Accessories | | Instruction manual | | | | | |
| | | No also representative representative the IO Link patrus file (IODD file) | | | | | |

Note: Please contact your OMRON sales representative regarding the IO-Link setup file (IODD file).

*2. The response frequency is an average value. Measurement conditions are as follows: standard sensing object, a distance of twice the standard sensing object, and a set distance of half the sensing distance.

^{*1.} In the Standard I/O mode (SIO mode), use the product in a range that the green stability indication lamp is lit. (Although the lamp is turned off when the object detected has approached excessively, the detection performance is stable.)

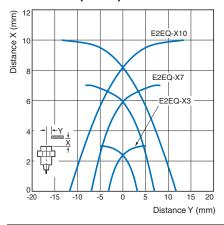
In the IO-Link mode, use the product in a range that the Byte1_bit4 for instability detection is zero. (Although the Byte1_bit5 for excessive proximity detection is one if the object detected has approached excessively, the detection performance is stable.)

Please contact your OMRON sales representative regarding assignment of data.

Engineering Data (Reference Value)

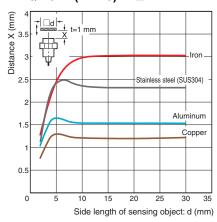
Sensing Area

E2EQ-X□B4 (-M1TJ) -IL□

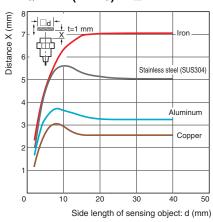


Influence of Sensing Object Size and Material

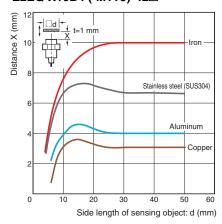
E2EQ-X3B4 (-M1TJ) -IL□



E2EQ-X7B4 (-M1TJ) -IL□

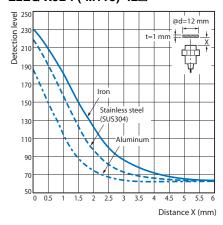


E2EQ-X10B4 (-M1TJ) -IL□

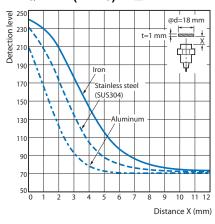


Monitor Output

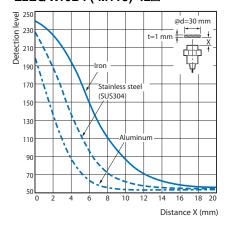
E2EQ-X3B4 (-M1TJ) -IL□



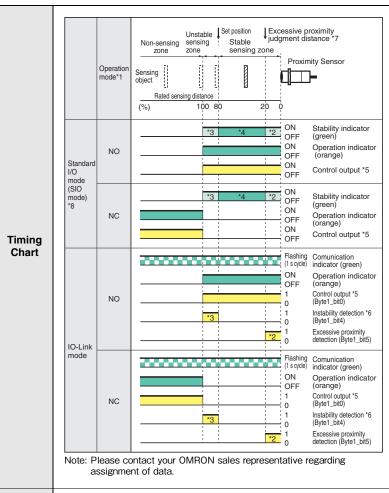
E2EQ-X7B4 (-M1TJ) -IL□



E2EQ-X10B4 (-M1TJ) -IL□



I/O Circuit Diagrams



- *1. The operation mode can be changed by the IO-Link
- *1. The operation mode can be changed by the IO-Link communications.
 *2. If the excessive proximity diagnosis function using the IO-Link communications is disabled, the lamp is lit in this zone, too, in the Standard I/O mode (SIO mode). In the IO-Link mode, diagnosis is disabled (fixed to zero).
 *3. If the instability detection diagnosis function using the IO-Link communications is disabled, the lamp is lit in this zone, too, in the Standard I/O mode (SIO mode). In the IO-Link mode, diagnosis is disabled (fixed to zero).
- diagnosis is disabled (fixed to zero).

 *4. If both the diagnosis functions of excessive proximity and instability detection using the IO-Link communications are disabled, the lamp is not lit in all the zones.
- The timer function of the control output can be set up by the IO-Link communications. (It is able to select ON delay, OFF delay, or one-shot function and select a timer time of 1 to 4000 ms (T).)

| ON-delay | OFF-delay | One Shot |
|---|--|--|
| Sensing Not Object present NO ON 1 NO OFF 0 OFF 0 | Sensing Not object present object present NO ON 1 OFF 0 ON 1 OFF 0 OFF 0 | Sensing Not object present NO ON 1 NO OFF 0 NT OFF 0 |

- *6. The judgment time for the instability detection diagnosis can be selected by the IO-Link communications.

 (For the ON delay timer function, the setting can be selected from 0 (invalid), 10, 50, 100, 300, 500, or 1000 ms.

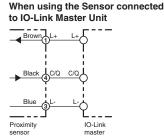
 *7. The judgment distance of the excessive proximity diagnosis function can be selected by the IO-Link communications.

 (The distance can be selected as a combination of the material.
- The distance can be selected by the 10-Link communications. (The distance can be selected as a combination of the material of the object detected, such as iron, aluminum, or SUS and the judgment distance of approximately 10, 20, or 30%. However, it is not allowed to select a combination of aluminum and 30%.)
- *8. If using the product as a general sensor, it operates in the Standard I/O mode (SIO mode).

Output circuit



Load Proximity



Pre-wired Connector Model Connections

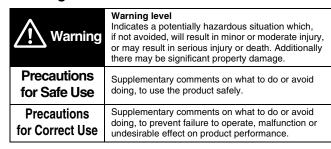
| Model | Connections |
|--------------------|---|
| E2EQ-X□B4-M1TJ-IL□ | E2EQ XSSF * O Brown (+V) O White (not used) O Blue (0V) O Black (Output) |

^{*} If the XS5W-D42 -- 81-F Connector which has a socket and plug on the cable ends is connected to the Sensor, this part will be a plug.

Safety Precautions

Be sure to read the precautions for all models in the website at: http://www.ia.omron.com/.

Warning Indications



Meaning of Product Safety Symbols



General prohibition

Indicates the instructions of unspecified prohibited action



Caution, explosion

Indicates the possibility of explosion under specific conditions.



This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Risk of explosion.

Do not connect sensor to AC power supply.



Precautions for Safe Use

The following precautions must be observed to ensure safe operation.

- Do not use the product in an environment where flammable or explosive gas is present.
- 2. Do not attempt to disassemble, repair, or modify the product.
- 3. Power Supply Voltage

Do not use a voltage that exceeds the rated operating voltage range. Applying a voltage that is higher than the operating voltage range may result in damage or burnout.

- 4. Incorrect Wiring
 - Be sure that the power supply polarity and other wiring is correct. Incorrect wiring may cause explosion or burnout.
- 5. Connection without a Load
 - If the power supply is connected directly without a load, the internal elements may explode or burn. Be sure to insert a load when connecting the power supply.
- 6. Dispose of this product as industrial waste.

Precautions for Correct Use

Do not use this product under ambient conditions that exceed the ratings

Operating Environment

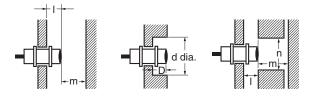
- Do not install the product in the following locations.
 Doing so may result in product failure or malfunction.
 - Outdoor locations directly subject to sunlight, rain, snow, water droplets, or oil.
 - (2) Locations subject to atmospheres with chemical vapors, in particular solvents and acids.
 - (3) Locations subject to corrosive gases.
- 2. The Sensor may malfunction if used near ultrasonic cleaning equipment, high-frequency equipment, transceivers, cellular phones, inverters, or other devices that generate a high-frequency electric field. Please refer to the Precautions for Correct Use on the OMRON website (www.ia.omron.com) for typical measures.
- Laying the Proximity Sensor wiring in the same conduit or duct as high-voltage wires or power lines may result in incorrect operation and damage due to induction. Wire the Sensor using a separate conduit or independent conduit.

Never use thinner or other solvents. Otherwise, the Sensor surface may be dissolved.

Design

Influence of Surrounding Metal

When mounting the Sensor within a metal panel, ensure that the clearances given in the following table are maintained. Failure to maintain these distances may cause deterioration in the performance of the Sensor.

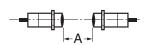


(Unit: mm)

| Model Item | I | d | D | m | n |
|-------------------------|---|----|---|----|----|
| E2EQ-X3B4 (-M1TJ) -IL□ | | 12 | | 8 | 18 |
| E2EQ-X7B4 (-M1TJ) -IL□ | 0 | 18 | 0 | 20 | 27 |
| E2EQ-X10B4 (-M1TJ) -IL□ | | 30 | | 40 | 45 |

Mutual Interference

When installing Sensors face-to-face or side-by-side, ensure that the minimum distances given in the following table are maintained.





(Unit: mm)

| Model | Item | Α | В |
|------------------------|------|-----|----|
| E2EQ-X3B4 (-M1TJ) -IL□ | | 30 | 20 |
| E2EQ-X7B4 (-M1TJ) -IL□ | | 50 | 35 |
| E2EQ-X10B4 (-M1TJ) -IL | | 100 | 70 |

Mounting

Tightening Force

Do not tighten the nut with excessive force. A washer must be used with the nut. Do not use tightening force that exceeds the values in the following table.



| Model | Item | Torque |
|------------------------|------|---------|
| E2EQ-X3B4 (-M1TJ) -IL□ | | 30 N⋅m |
| E2EQ-X7B4 (-M1TJ) -IL□ | | 70 N⋅m |
| E2EQ-X10B4 (-M1TJ) -IL | | 180 N·m |

Wiring

In the IO-Link mode, the cable between the IO-link Master and Sensor must have a length of 20m or less.

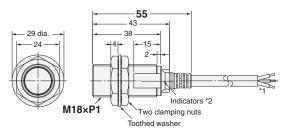
Pre-wired Models



E2EQ-X3B4-IL□ - 21 dia. -33-M12xP1 Two clamping nuts Toothed washer

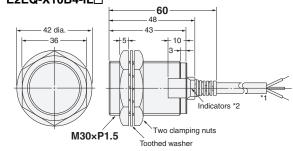
- *1. 4-dia. vinyl-insulated round cable with 3 conductors (Flame-resistant, Conductor cross section: 0.3 mm², Insulator diameter: 1.3 mm), Standard length: 2 m *2. Operation indicator (orange), stability indicator/
- communication indicator (green)

E2EQ-X7B4-IL□



- *1. 6-dia. vinyl-insulated round cable with 3 conductors (Flame-resistant, Conductor cross section: 0.5 mm², Insulator diameter: 1.9 mm), Standard length: 2 m
- *2. Operation indicator (orange), stability indicator/ communication indicator (green)

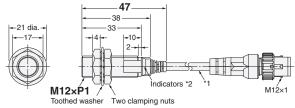
E2EQ-X10B4-IL□



- *1. 6-dia. vinyl-insulated round cable with 3 conductors (Flame-resistant, Conductor cross section: 0.5 mm², Insulator diameter: 1.9 mm), Standard length: 2 m °2. Operation indicator (orange), stability indicator/ communication indicator (green)

Pre-wired Connector Models

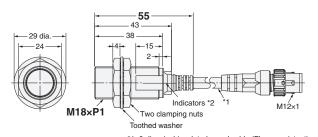
E2EQ-X3B4-M1TJ-IL□



- *1. 4-dia. vinyl-insulated round cable (Flame-resistant),
- **2. Operation indicator (green)

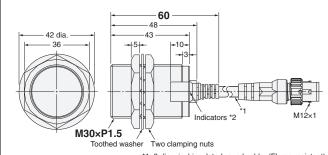
 *2. Operation indicator (green)

E2EQ-X7B4-M1TJ-IL□



- *1. 6-dia. vinyl-insulated round cable (Flame-resistant),
- Standard length: 0.3 m
 *2. Operation indicator (orange), stability indicator/communication indicator (green)

E2EQ-X10B4-M1TJ-IL□



- *1. 6-dia. vinyl-insulated round cable (Flame-resistant), Standard length: 0.3 m *2. Operation indicator (orange), stability indicator/
- communication indicator (green)

Mounting Hole Dimensions



| Model | E2EQ-X3B4 | E2EQ-X7B4 | E2EQ-X10B4 |
|--------|--|--|--|
| F (mm) | 12.5 ₀ ^{+0.5} dia. | 18.5 ₀ ^{+0.5} dia. | 30.5 ₀ ^{+0.5} dia. |

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